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16. Abstract This report describes a study of motorcycle handling qualities, involving both transient and steady-state directional stability and control properties, and the development of test procedures suitable for the evaluation of these properties. The approach used in the study consisted of the application of both experimental (with one machine) and simulation techniques (with six motorcycles) for the identification of the significant physical properties and performance measures with which to characterize the machine's accident avoidance capabilities. Emphasis was placed on evaluating the input-output relationships for the group of motorcycles in a series of constant speed-variable radius (hence, variable lateral acceleration) runs covering a range of cornering capability which encompasses normal operation. The primary test used for evaluating transient maneuvering and rider-vehicle interaction characteristics was the single lane change. Supporting activity involved testing of nine motorcycle tires in eighteen configurations to obtain side force performance data developed through slip angle and inclination angle; measurements of the physical characteristics, including all pertinent dimensions and masses and moments of inertia of major assemblies, for all machines; development of a special-purpose lightweight instrumentation system employing telemetering techniques (enabling the measurement of such variables as applied steering torque and rider lean angle); and the application of simplified analytical models of motorcycle response to provide some insight regarding motorcycle stability and control. Results of this initial handling					
17. Key Words Motorcycle Response Characteristics Motorcycle Tire Performance Motorcycle Performance Tests Motorcycle Simulation			18. Distribution Statement		
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16. Abstract - Cont'd.

study indicate that substantial differences in the values of several performance parameters (for example, steady state control gains) exist among various motorcycle designs and that tire performance characteristics play a very significant role in the determination of these parameters. It is concluded that the results of the study provide a firm foundation of information on several important aspects of motorcycle behavior and have identified special areas where additional study is required.

## INTRODUCTION

This volume of the report contains several appendices which provide additional details of information on subjects discussed in the technical report, Vol. I. Appendix A contains descriptions of the two detailed test procedures which were used in the study. Appendix B is a collection of all the printed and plotted output from the tire performance measurement tests performed at the Calspan Tire Research Facility. Appendix C consists of a full set of machine-plotted responses of the principal input and output quantities from the simulation study. Appendix D contains data from the full-scale tests with the Honda CB 360 motorcycle including typical raw data time histories for both procedures.



## Appendix A

This appendix includes the detailed procedures for the vehicle response and handling tests. Section A-1 describes the constant speed directional control test; Section A-2 outlines the lane change procedures. These procedures were used for the full-scale test work performed as part of this program and have proven to be practical methods but they should still be viewed as initial versions until they have been applied to a large number of vehicles and minor modifications have been incorporated.

Test Procedure for Measuring the  
Directional Control Properties of Motorcycles

1. Scope

This test procedure describes a method for measuring the principal control response characteristics of motorcycles. It is chiefly concerned with the steady state properties but may also be used to obtain transient response information.

2. Objectives

The objectives of this procedure are:

- (a) To measure the lateral/directional performance characteristics of motorcycles at constant speed conditions.
- (b) To provide a data base for computation of the motorcycle's steady state control gains.

3. Introduction

A basic concept for evaluating the stability and control properties of a vehicle is the determination of its steady-state response parameters - the relationships between a control input and the resultant motion after the transient has effectively decayed. This approach has been successfully used with the automobile and is being applied to the motorcycle in this procedure. In the case of the automobile, only the position control responses (i.e., the effects of a steering wheel displacement) have been of general interest; the situation is not as simple with the motorcycle. In its case, the position control mode is joined by a torque control mode (i.e., applied steering torque is the input of interest) and rider lean control mode (in which the rider's position relative to the machine produces control inputs). The problem is further complicated with the motorcycle because the driver is important to the stability of the system (unlike the automobile) as well as its control. A comparatively large number of response parameters are therefore required for

defining performance, and care must be taken to separate the effects of the different inputs. This procedure describes an experimental technique for measuring the variables of interest and methods for treating the resultant data to compute the principal response parameters.

4. Instrumentation

The following measurements are minimum requirements for this test procedure:

Vehicle velocity (including visual readout)  
Yaw rate  
Roll Angle  
Steering displacement  
Applied steering torque  
Rider lean angle (relative to vehicle frame)

Optional equipment (for data checks and testing convenience) includes:

Lateral accelerometer  
Visual readouts of input variables

It is important of course to minimize the weight of the instrumentation and related equipment, especially with lightweight machines. In any case, the added weight should be determined and an effort should be made to locate the gear so as to affect moments of inertia and centers-of-gravity locations minimally.

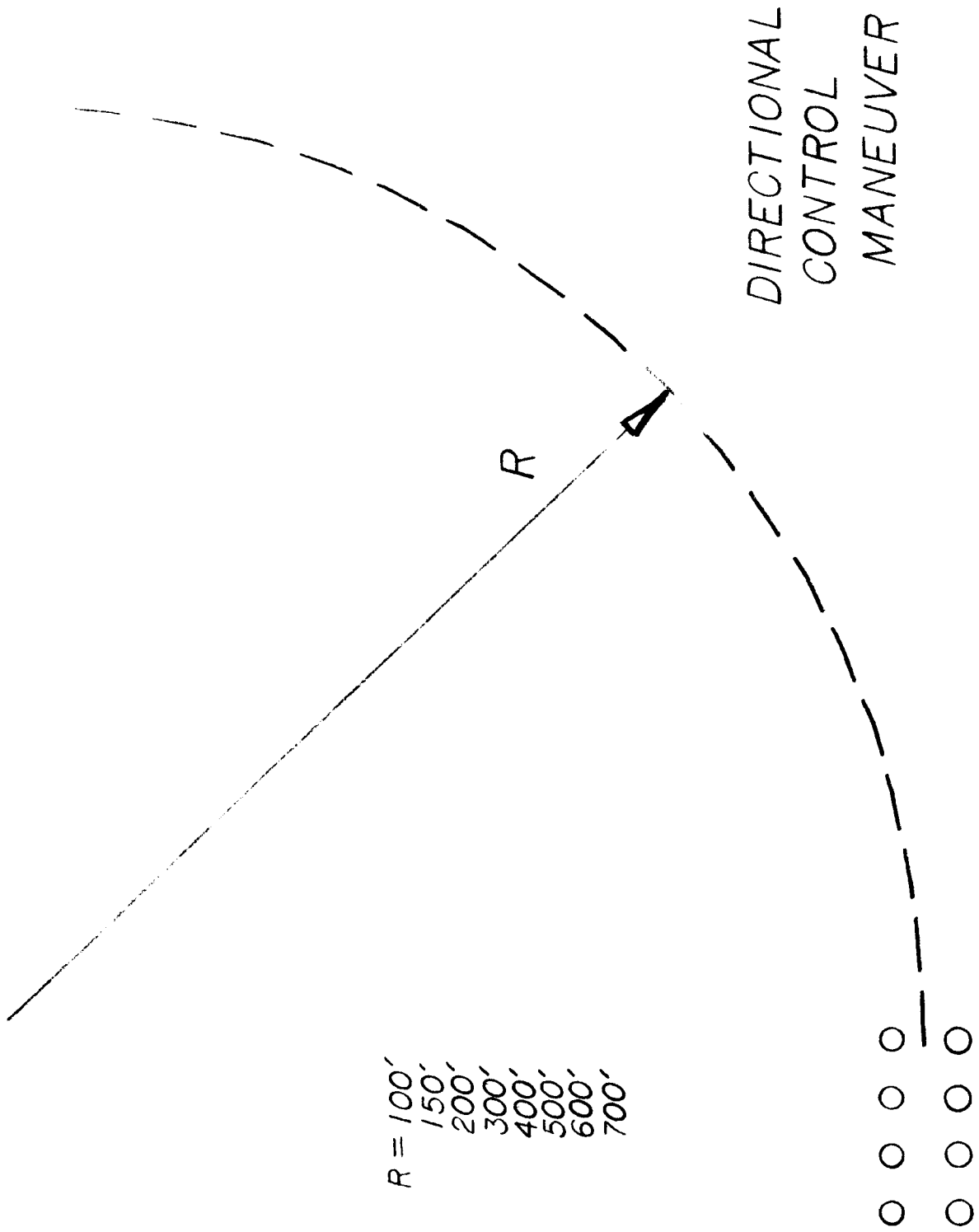
5. Test Area Requirements

The size and shape of a test area required for performing to this procedure will depend on the selected operating speed and range of lateral accelerations to be investigated. The site must allow for build-up and stabilization of test speed, development of steady state cornering (including the transient and, preferably, several seconds of steady-state operation), and a way for exiting from the test area or braking without endangerment. Although not essential, paths of various radii emanating from an initial straight section as shown in the sketch provide the test rider with excellent references for performing this test. A series of arcs from 200 to 700 ft. radius covers a lateral acceleration range from less than .2g to over .5g at 40 mph.

6. Procedure

1. At standstill on a flat level surface with the test vehicle in an upright position and with front wheel at zero displacement, apply calibration signals to all data channels. Do not turn off instrumentation.
2. Accelerate test vehicle to nominal test speed on a straight course. Allow for sufficient run-up distance to assure development of steady state conditions.
3. Apply first pre-determined value of steer angle and allow test vehicle to reach and hold steady state cornering conditions for at least two seconds. (In some vehicles with high position control gain, it may be found that pre-selection of an approximate path facilitates performance). The rider should make every effort to attempt to be in the X-Z plane of the motorcycle during steady state conditions.





4. Bring test vehicle to a stop and turn off instrumentation.
5. Repeat steps 2 through 4 (being sure to start instrumentation prior to each run) for a series of increments of steering angle to cover as wide a range of lateral acceleration as is deemed safe and prudent. At least five increments should be used.
6. Repeat steps 2 through 5 for steering inputs of opposite sense.

The procedure may also be used to determine rider lean control performance parameters. In fact, it is essential that measurements of this effect be made to correct for possible biases in the data from steps 2 through 6.

7. At a low value of lateral acceleration (not necessarily specified), bring the test vehicle to steady state conditions with the rider leaning into the turn to the maximum angle deemed to be safe and prudent, repeating in effect steps 2 through 4.
8. Repeat step 7 with the rider leaning out of the turn.
9. Repeat steps 7 and 8 for a series of lateral accelerations within limits considered to be safe.
10. After completing all runs, apply calibration signals to all data channels.

7. Data Analysis

1. Plot the following two-variable curves from steady state test data -

- lateral acceleration vs. steer angle
- lateral acceleration vs. applied steer torques
- lateral acceleration vs. rider lean angle
- lateral acceleration vs. vehicle roll angle

In reducing the test data, care must be taken to correct the measurements in computing lateral acceleration -

$$a_{y \text{ actual}} = a_{y \text{ measured}} - g \tan \phi = V r / \cos \phi$$

2. Using best estimates for the slopes of the curves from the plots identified above, compute the following performance parameters -

- position control lateral acceleration gain
- torque control lateral acceleration gain
- lean control lateral acceleration gain
- understeer factor

Test Procedure for Measuring the  
Transient Handling Properties of  
Motorcycles in a Lane Change

1. Scope

This test procedure describes a method for measuring the performance characteristics of motorcycles in a single lane change maneuver. It may also be used for evaluating rider skill effects on performance in a transient maneuver. Techniques are described for investigating both sub-limit and limit behavior over a range of operating speed.

2. Objectives

The objectives of this procedure are:

- (a) To measure the input-output characteristics of motorcycles in a transient maneuver at nominally constant speed.
- (b) To obtain information on rider requirements for performing a lane change.
- (c) To identify possible problem areas in the transient handling qualities of the test motorcycle.

3. Introduction

The development of test procedures suitable for obtaining objective measures of vehicle performance has received considerable attention in recent years. In the case of the automobile, emphasis has been placed on response tests which yield more-or-less direct measurements of certain motion variables (e.g., yaw rate, lateral acceleration) in relation to known steering control inputs. Various task performance tests have been tried, with mixed success due in part to driver variability effects. This problem is not less complicated for motorcycles. Indeed, the fact that the rider-motorcycle system depends on the rider for stability as well as control introduces additional dimensions into the problem. On the other hand, this dependence defines the approach -

there is really no alternative to the inclusion of the rider in motorcycle performance evaluations. In the test procedure outlined below, a fundamental path change maneuver is employed to obtain measures of input requirements (steering displacement and applied torque and rider lean motions) and output behavior (transient lateral-directional motions and steady-state lateral displacement) at nominally constant speed over a fixed path geometry course.

#### 4. Instrumentation

The following measurements are minimum requirements for this test procedure:

- Vehicle velocity (including visual readout)
- Yaw rate
- Roll Angle
- Steering displacement
- Applied steering torque
- Rider lean angle (relative to vehicle frame)

Optional equipment (for data checks and testing convenience) includes:

- Lateral accelerometer
- Visual readouts of input variables

It is important of course to minimize the weight of the instrumentation and related equipment, especially with lightweight machines. In any case, the added weight should be determined and an effort should be made to locate the gear so as to affect moments of inertia and centers-of-gravity locations minimally.

5. Test Course Geometry

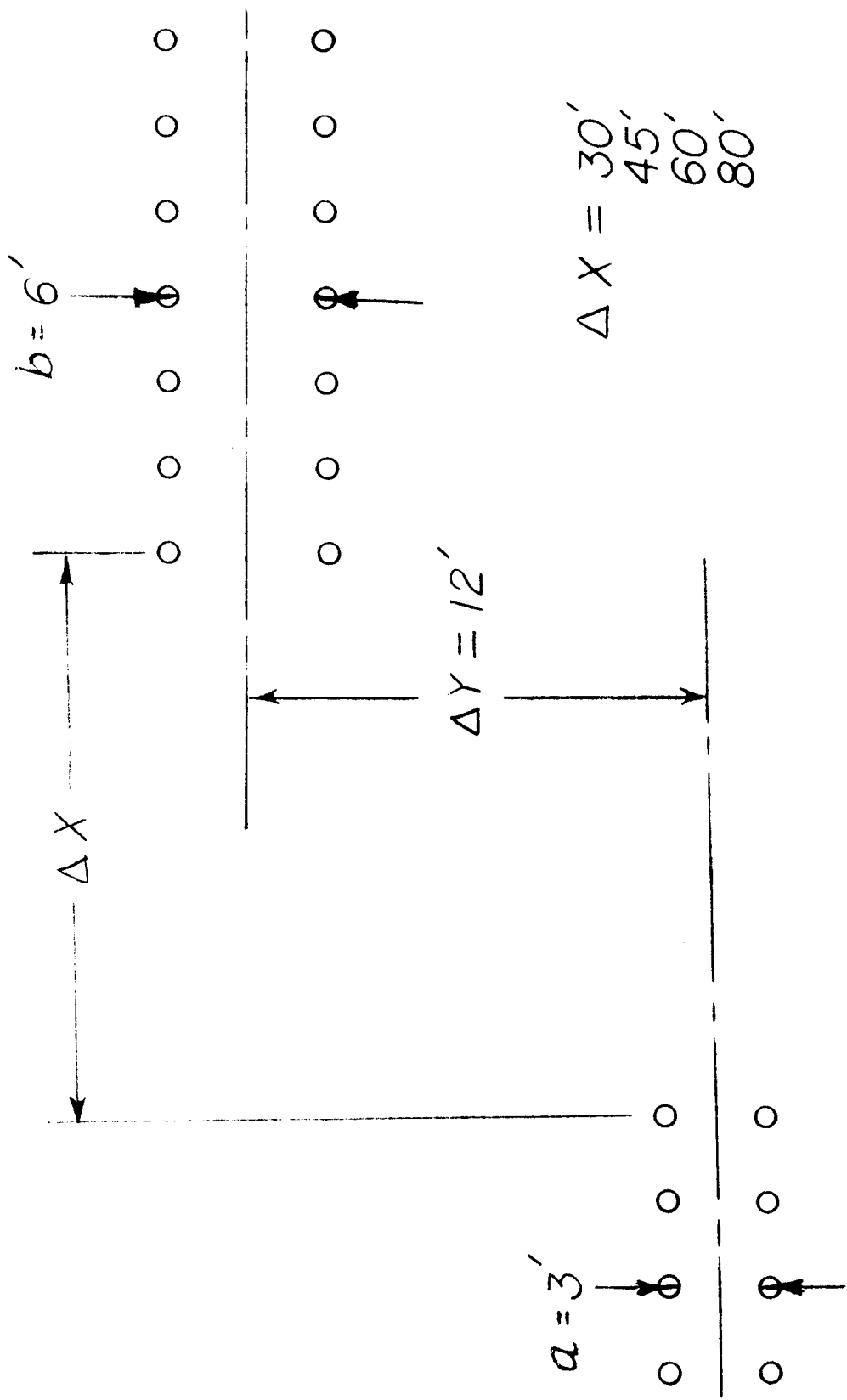
The test is to be performed over a course laid out as shown in the sketch. All dimensions may be varied according to the purposes of the test (speed range of interest, rider skill level, road condition) but experience with the procedure indicates that the values given in Table 1 represent reasonably challenging conditions for an experienced rider. In any case, it is recommended that the values for a, b, and  $\Delta y$  be fixed at the given levels to ensure good path definition and to simulate a real-world lateral displacement requirement.

TABLE 1  
TEST COURSE DIMENSIONS

Nominal* Speed (mph)	Dimensions (feet)				
	a	b	$\Delta x$	$\Delta y$	cone spacing
20	3	6	30	12	6
30	3	6	45	12	6
40	3	6	60	12	6
50	3	6	80	12	6

It will be observed that these values represent control input at a frequency of about 1 Hz (i.e., this is the frequency of the fundamental steering doublet required for a lane change).

\*Test speeds may be increased to a maximum value at which the maneuver may be successfully performed. This speed is called proof speed.



LANE CHANGE MANEUVER

6. Procedure

1. At standstill on a flat level surface and the test vehicle in an upright position with front wheel at zero steer angle, apply calibration signals to all data channels.
2. Accelerate vehicle to desired speed and perform the maneuver. Allow for sufficient run-up distance to assure development of desired test speed. Tightening the throttle cable drag screw will aid in maintaining a constant speed through the maneuver. Record success-failure performance and identify any violated lane markers after coming to a stop.
3. Continue to repeat step 2, incrementing speed on each run until failure occurs or until desired proof speed has been achieved. Perform three runs at this condition.
4. After completing the series of runs, reapply calibration signals.

7. Data Analysis

Data treatment will depend on the specific purposes for which the procedure has been applied--comparative vehicle evaluations, definition of rider input requirements for particular conditions, definition of maximum transient characteristics, etc. In all cases, the following should be noted:

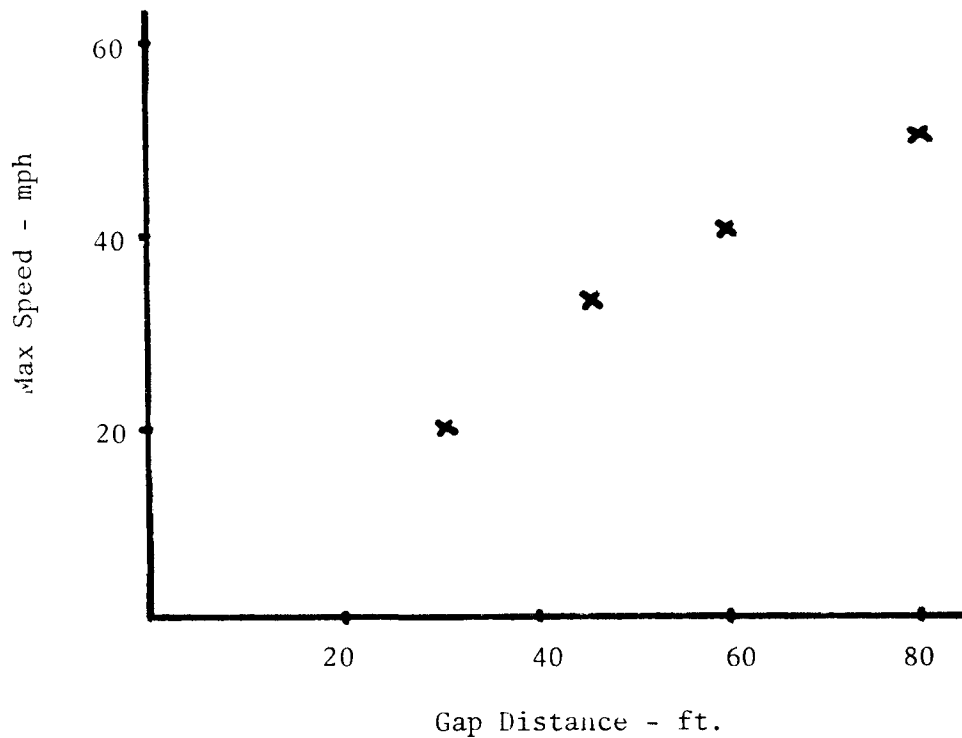
1. Course geometry
2. Maximum speed at which the maneuver could be successfully performed
3. Input requirements:
  - maximum applied torque
  - maximum yaw rate achieved



- maximum steering rate

4. Failure pattern (identify which cones were hit or where lane violations occurred).

For test series in which the longitudinal gap is varied to obtain a performance profile of the test vehicle in this type of maneuver, it is convenient to plot results in the form of the example shown below. This method of presentation facilitates vehicle comparisons by giving a graphical portrait of the variable of interest across a range of operating conditions.





## Appendix B

### Tire Test Data

This appendix contains detailed data on the performance characteristics of tires used with each of the motorcycles which were studied in this program. For each tire configuration, the information consists of:

1. Tire description, test identification number, and the condition at which it was tested. These data are collected in Table B-1.
2. Machine-generated best fit carpet plots of side force capability as a function of slip angle and inclination angle at test conditions (normal load and inflation pressure).
3. Data listings of performance characteristics over the ranges of the independent test variables.

A brief discussion to facilitate interpretation of the information may be useful at this point. The data shown in the carpet plots give side force (SF) over a range of slip angles ( $\alpha$ ) from +1 degree to -8 degrees and a range of inclination (camber) angles ( $\gamma$ ) from zero to +28 degrees. The actual test points were used to define best least-squares fit curves for the two variables--second order on  $\alpha$  and second order on  $\gamma$ . All data were taken at a speed of 30 mph under free-rolling (non-driven) conditions on a dry high friction coefficient surface.

The listed data augment the information given in the side force plots. Each primary listing (odd-numbered tables) gives the measured values for the three principal forces and three moments as tested. The secondary listing (even-numbered listing) gives supplementary data (including normalized side force) for each test condition. The symbols used in these listings are:

Test Designation	Tread Pattern	Test Identification No.	Normal Test Load (lbs.)	Test Inflation Pressure (psi)	Application
Dunlop 2.75 x 18	Ribbed	1-3-6 2-3-6	125 150	26	Honda 125 Front
Bridgestone 3.50 x 18	Universal	7-3-6 4-3-6	315 380	28	Honda 360 Rear
Bridgestone 3.00 x 18	Ribbed	5-3-6 6-3-6	210 250	26	Honda 360 Front
Yokohama 3.50 x 19	Ribbed	8-3-6 9-3-6	240 290	23	Yamaha 650 Front
Yokohama 4.00 x 18	Universal	10-3-6 11-3-6	360 430	28	Yamaha 650 Rear
Dunlop 4.00 x 19	Universal	12-3-6 13-3-6	215 260	24	Norton 850 Front & Rear
Dunlop 4.00 x 18	Trials	14-3-6 15-3-6	265 320	31	Kawasaki 250 Rear
Carlisle 3.00 x 17	Universal	16-3-6 17-3-6	230 275	28	Honda 125 Rear
Dunlop 3.00 x 21	Trials	18-3-6 19-3-6	155 185	24	Kawasaki 250 Front

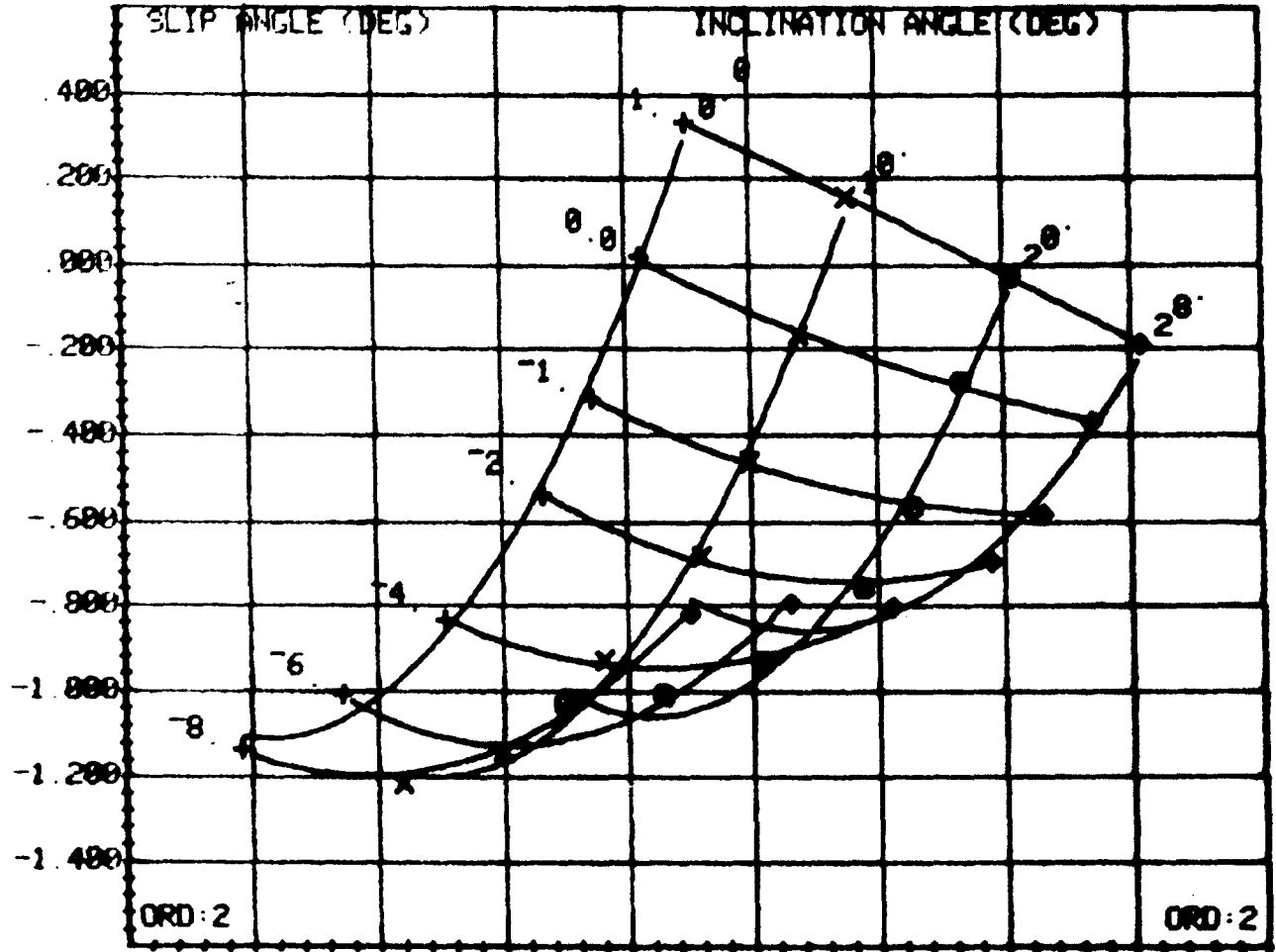
Table B-1  
Tire Identifications

SA	Slip Angle
IA	Inclination Angle
FZ	Normal Load
FY	Side Force
FX	Rolling Resistance
MX	Overturning Moment
MY	Rolling Resistance Moment
MZ	Aligning Torque
RL	Rolling Radius Under Load
V	Test Velocity
NFY	Normalized Side Force

Detailed test data for the Harley-Davidson 1200 machine are not included in this appendix. The recommended tires for this motorcycle (Goodyear MT90-16T) had been previously tested at Calspan under a different format and these data were adapted for use in this program. Their primary performance characteristics are given in Section 3 of the Technical Report.

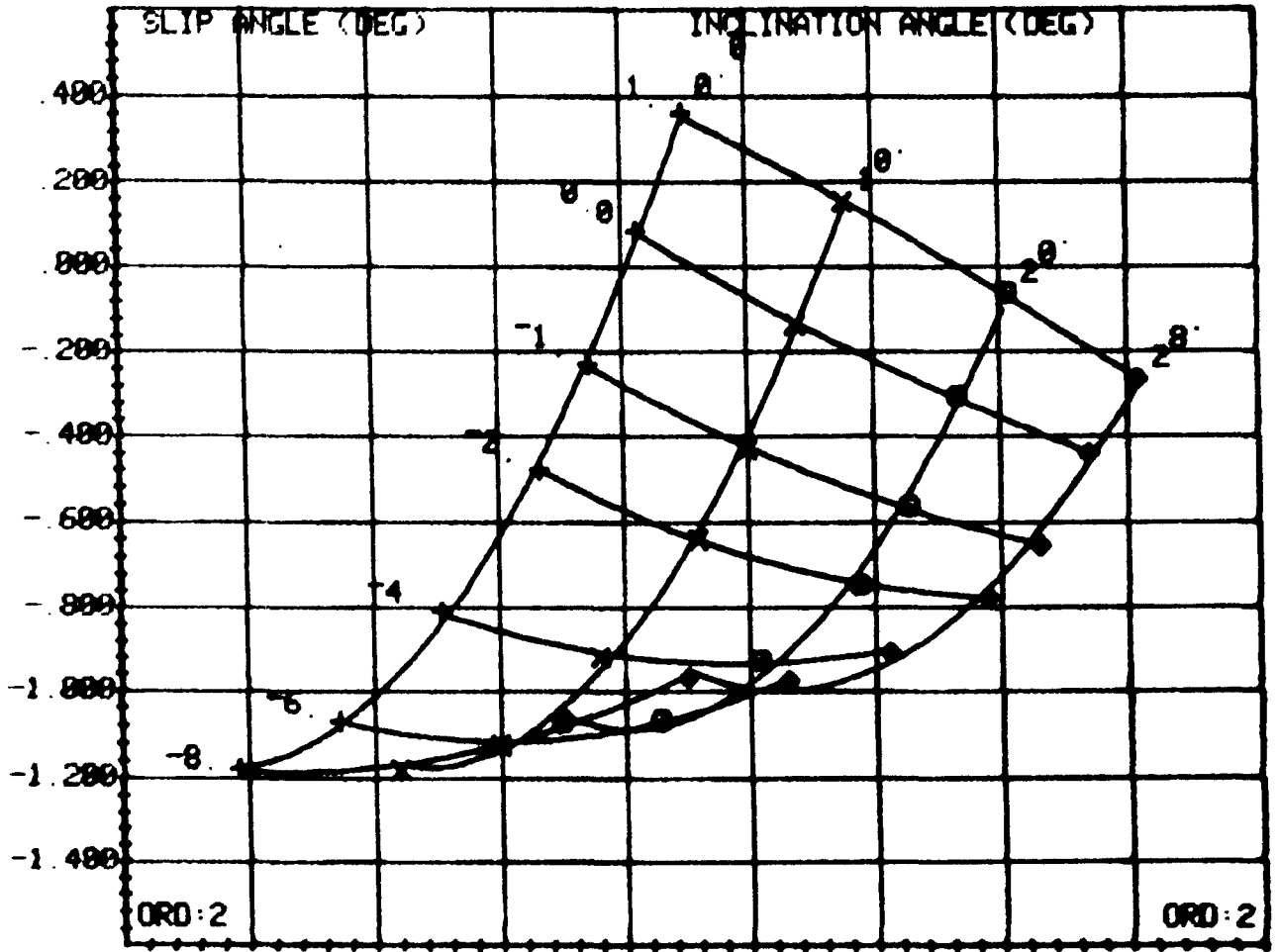
1: N F Y (FY/FZ)

RUN: 1-3-6



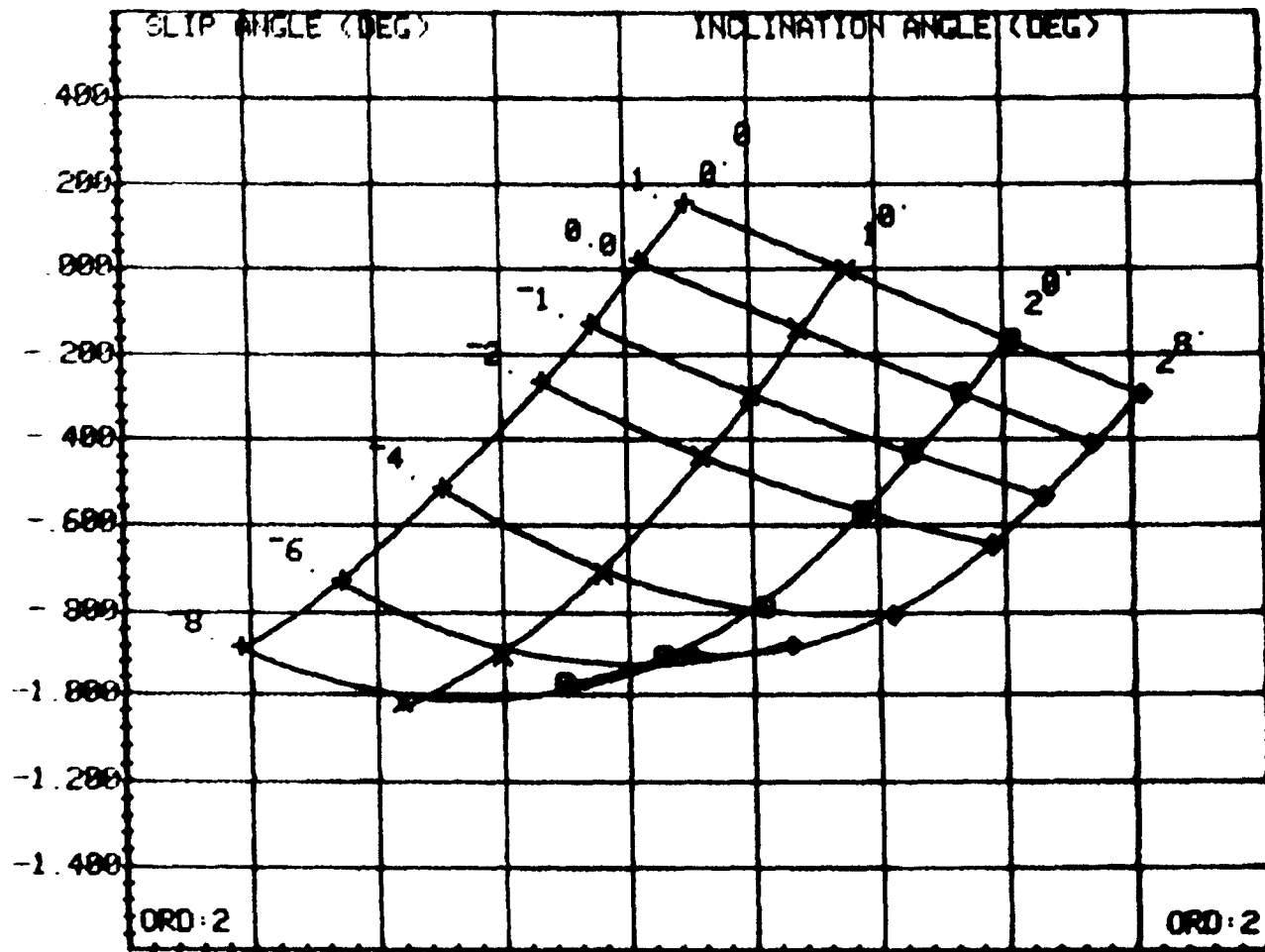
1. N F Y (FY/FZ)

RUN: 2-3-6



1. N F Y (FY/FZ)

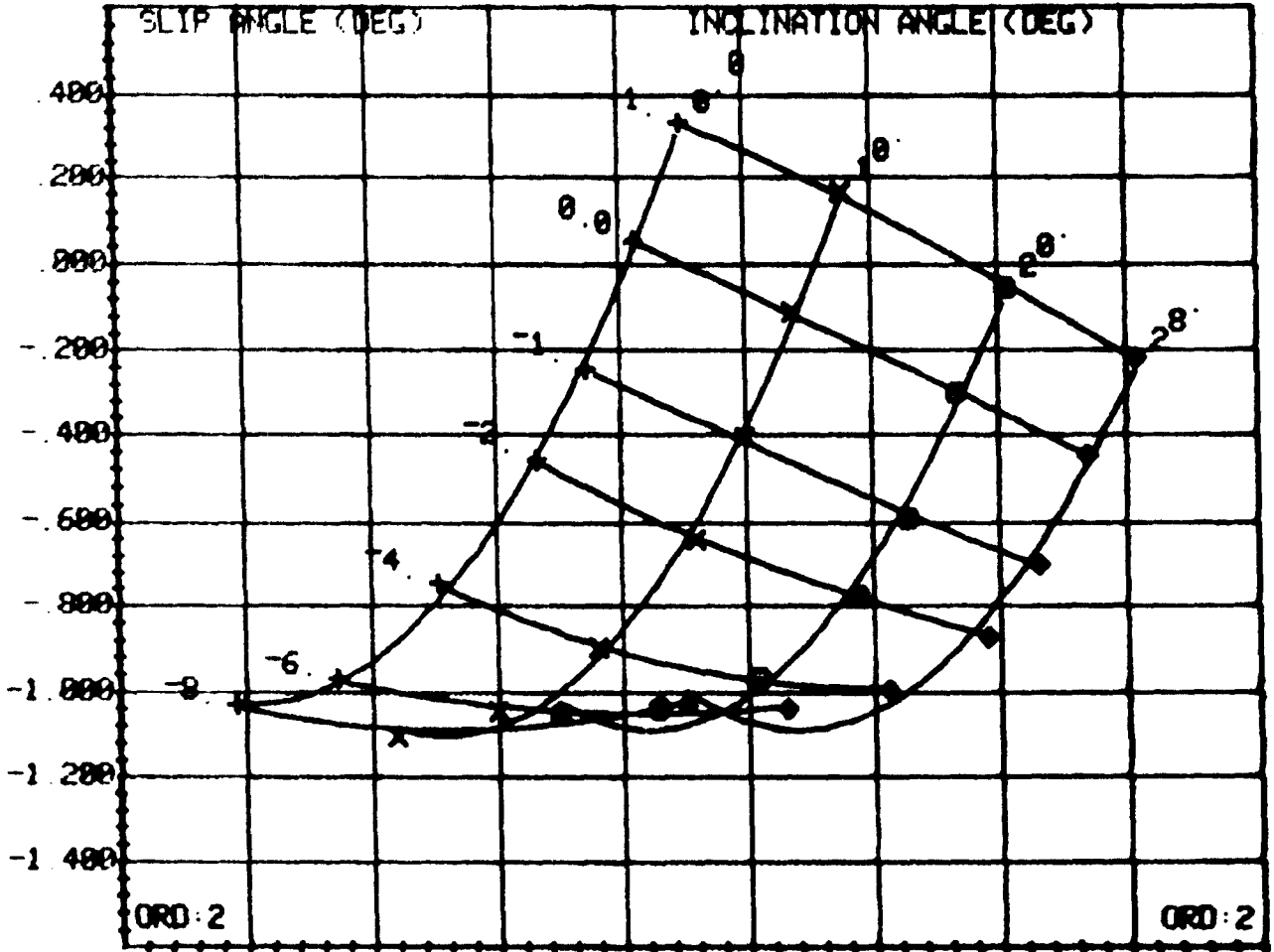
RUN: 4-3-6





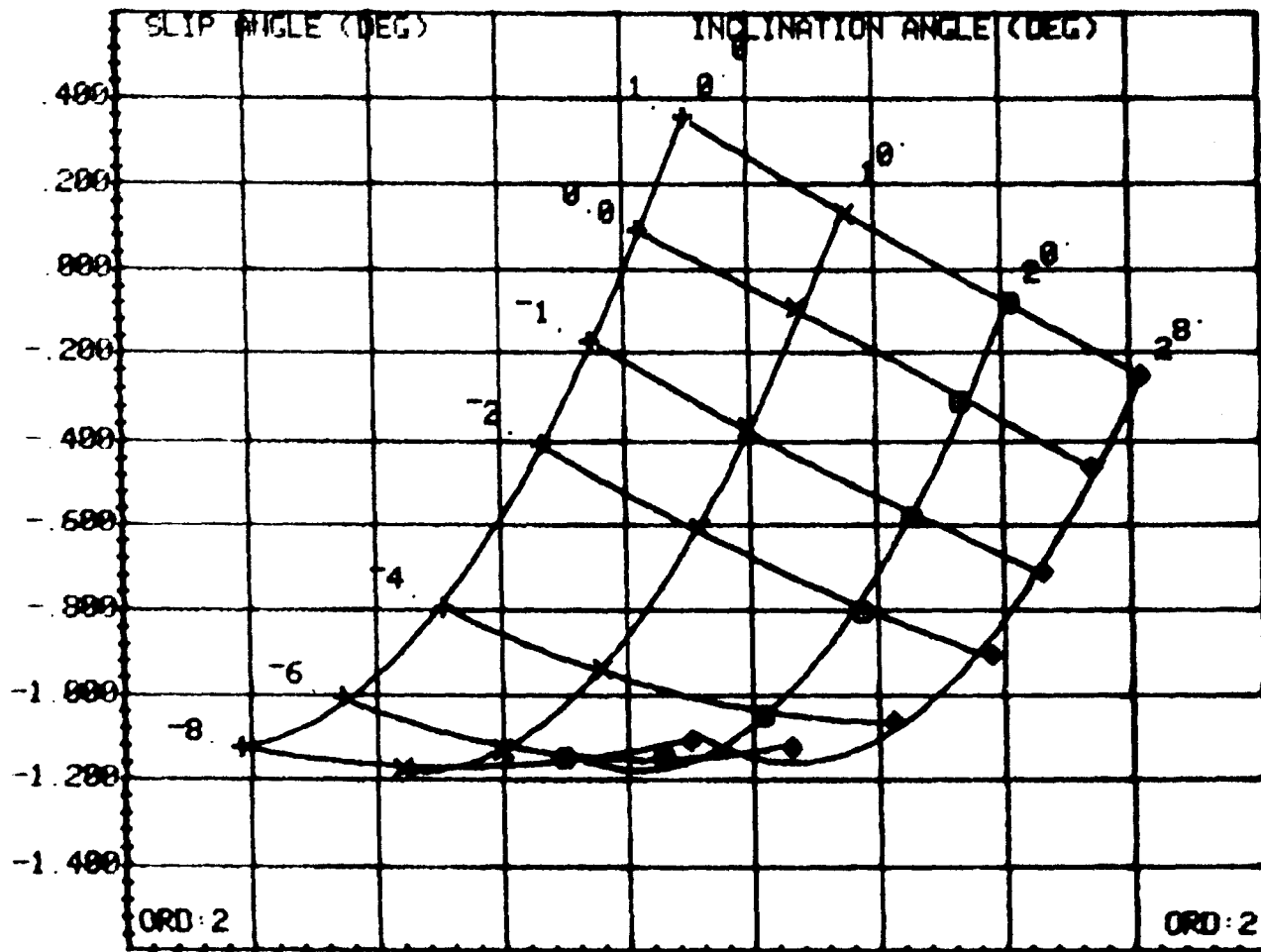
1: N F Y (FY/FZ)

RUN: 5-3-6



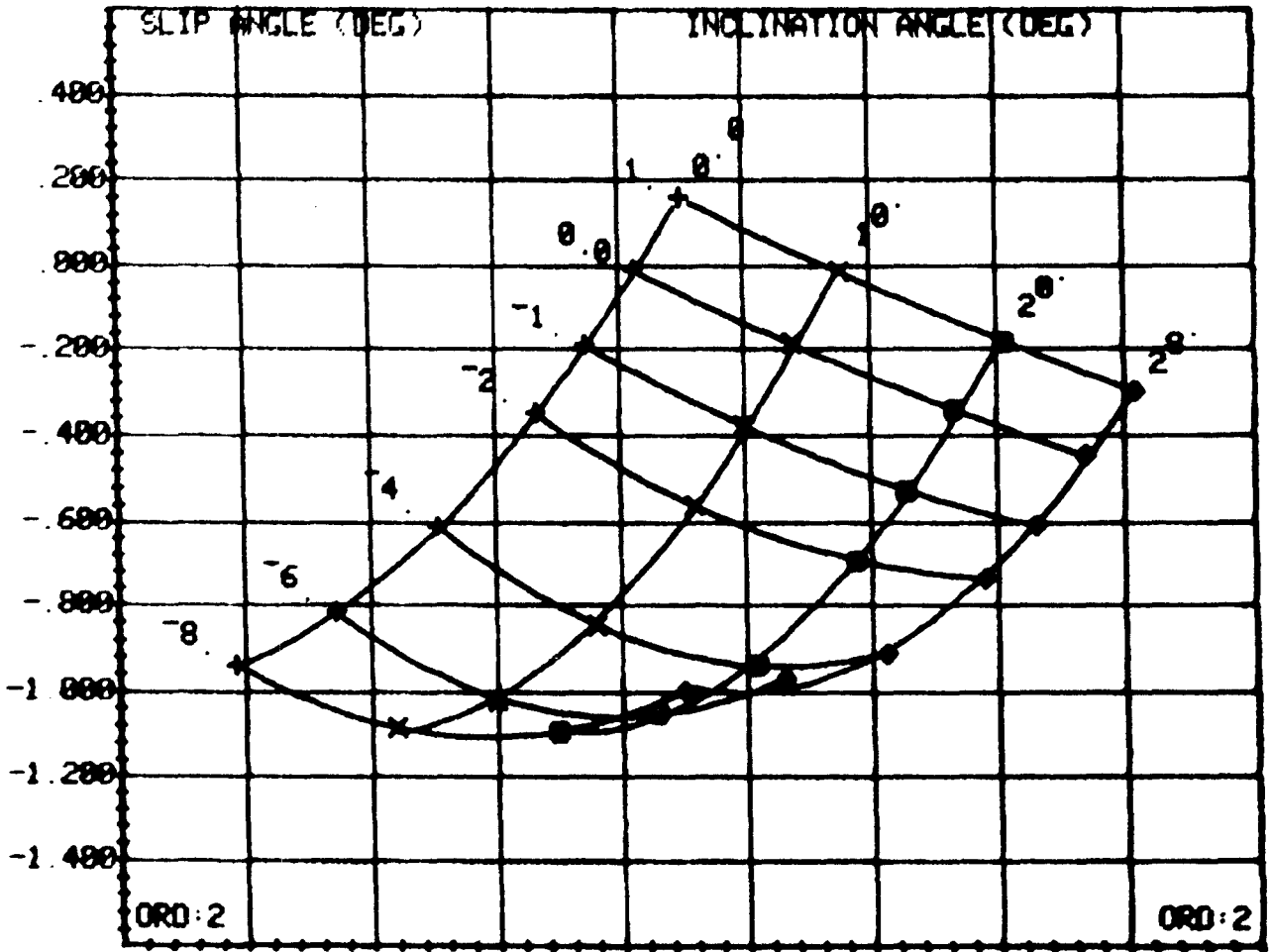
1: N F Y (FY/FZ)

RUN: 6-3-6



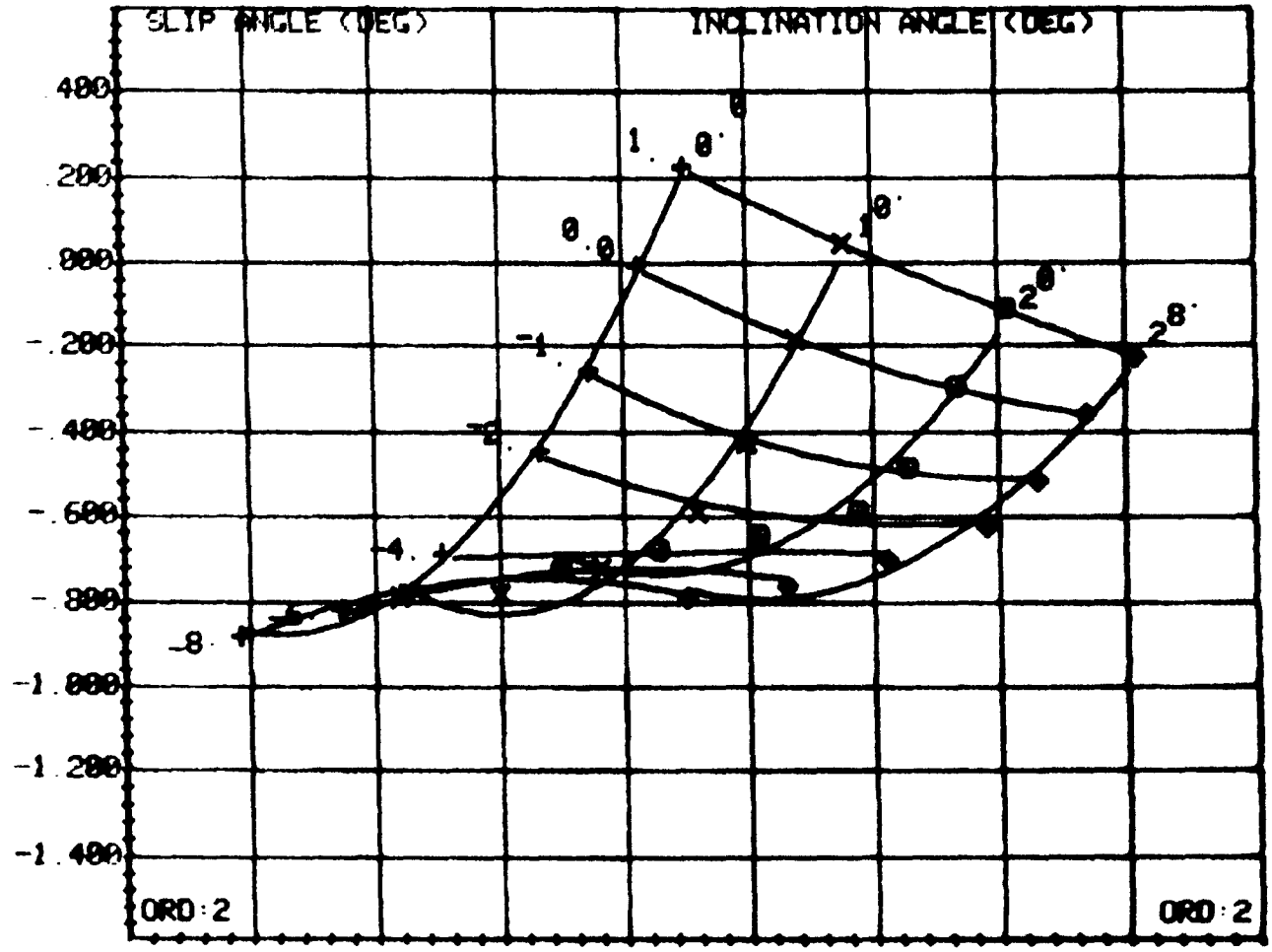
1: N F Y (FY/FZ)

RUN: 7-3-6



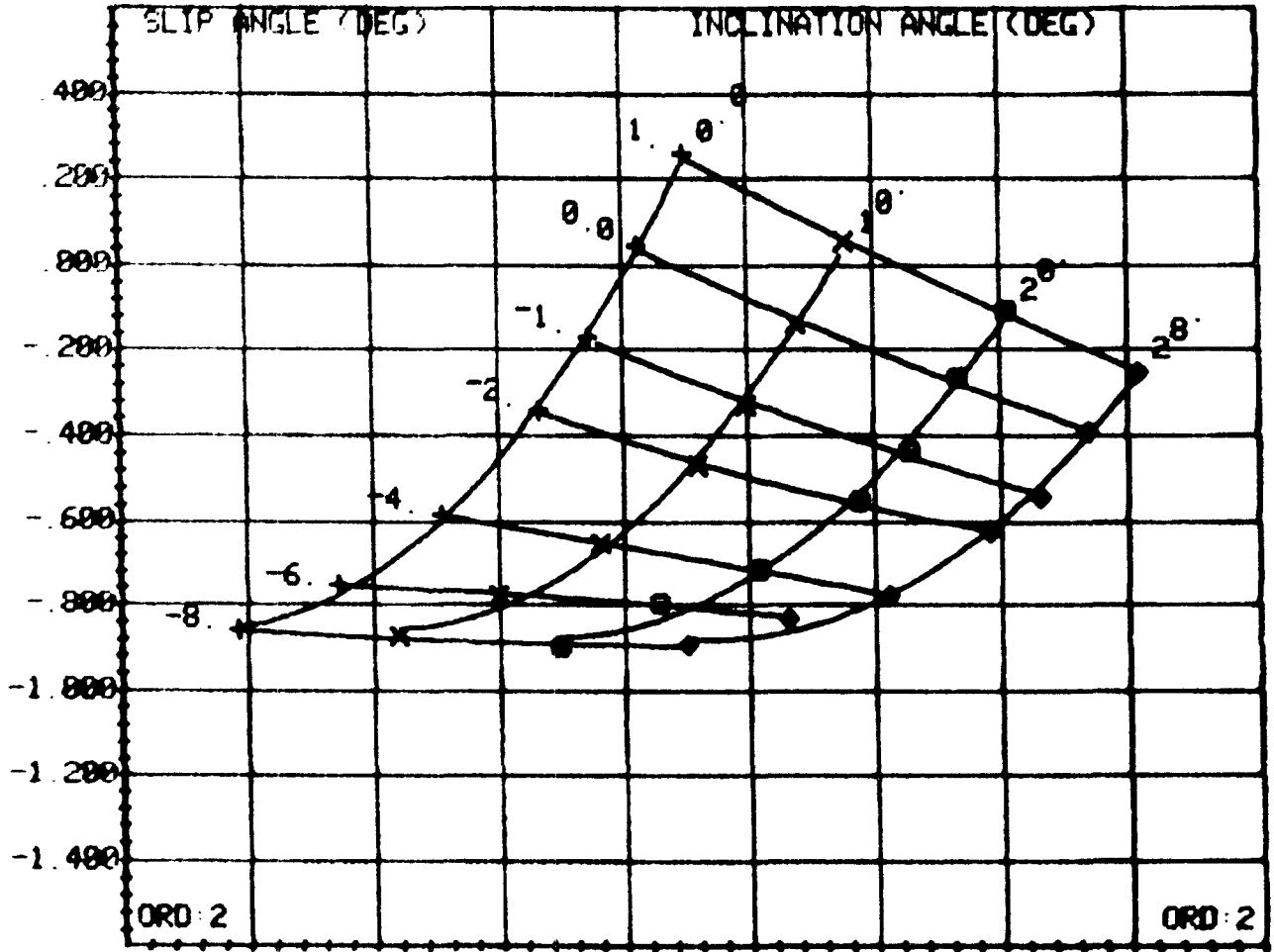
1: N F Y (FY/FZ)

RUN: 8-3-6



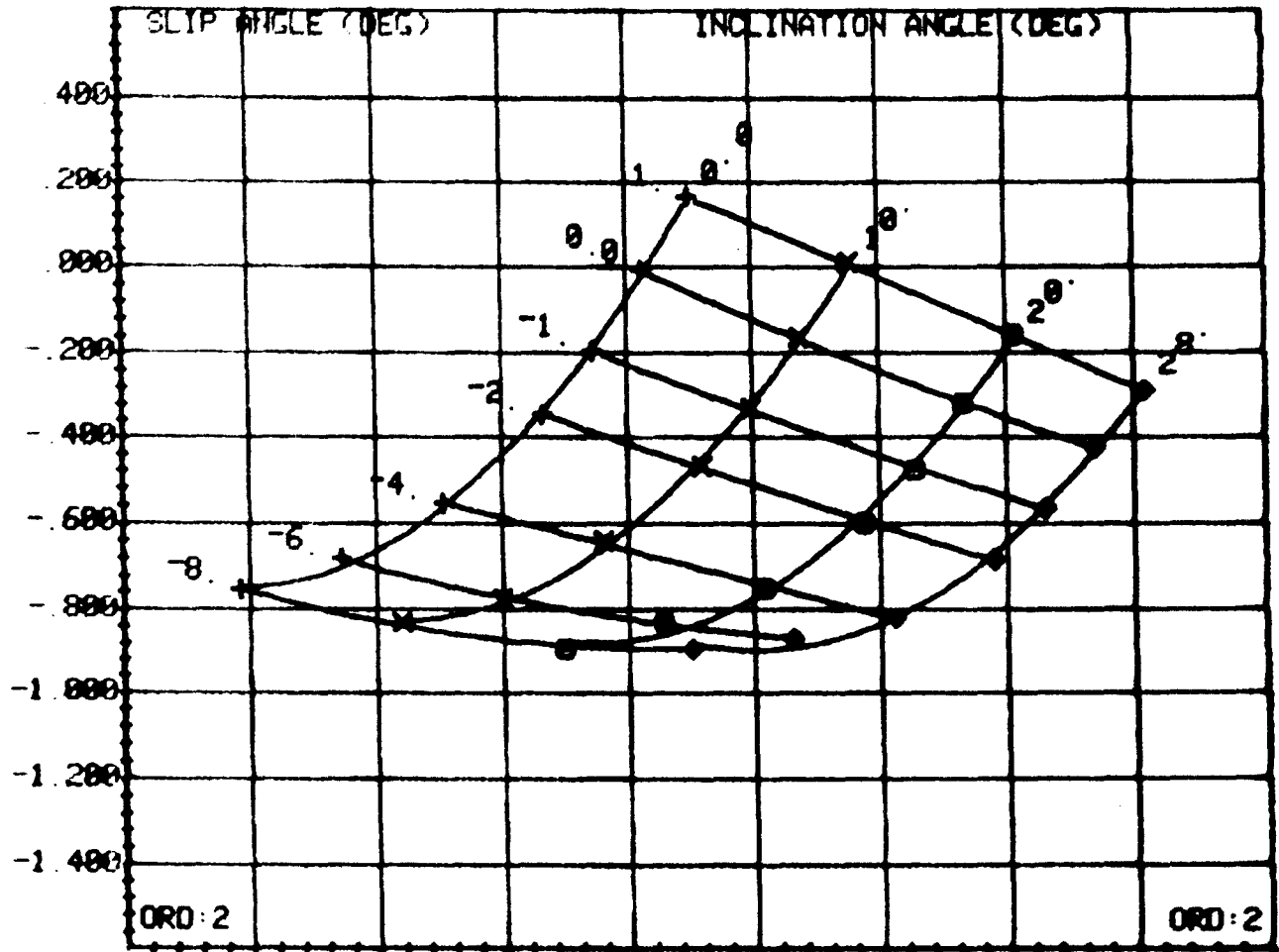
1 N F Y (FY/FZ)

RUN: 9-3-6



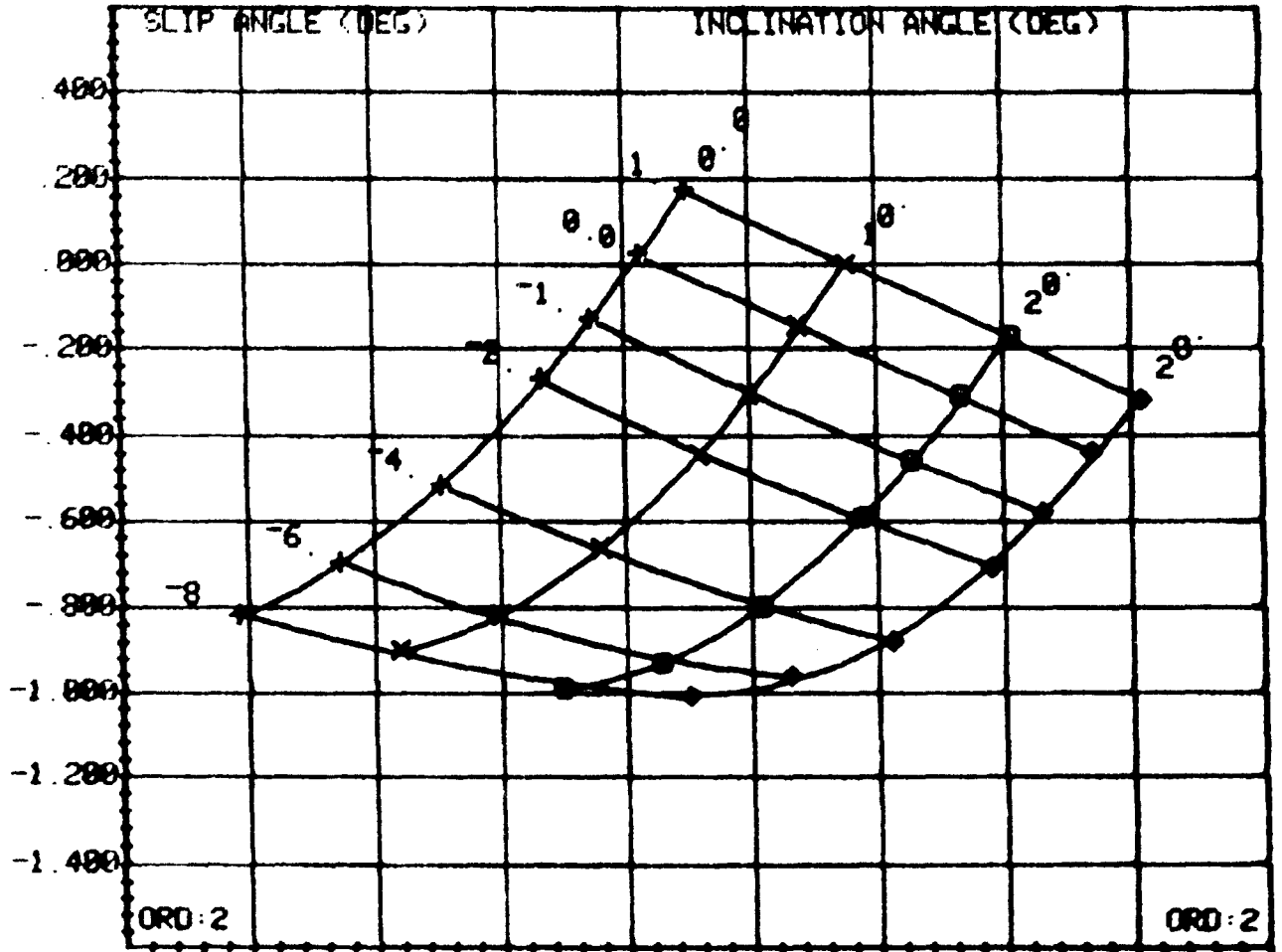
1: N F Y (FY/FZ)

RUN: 10-3-6



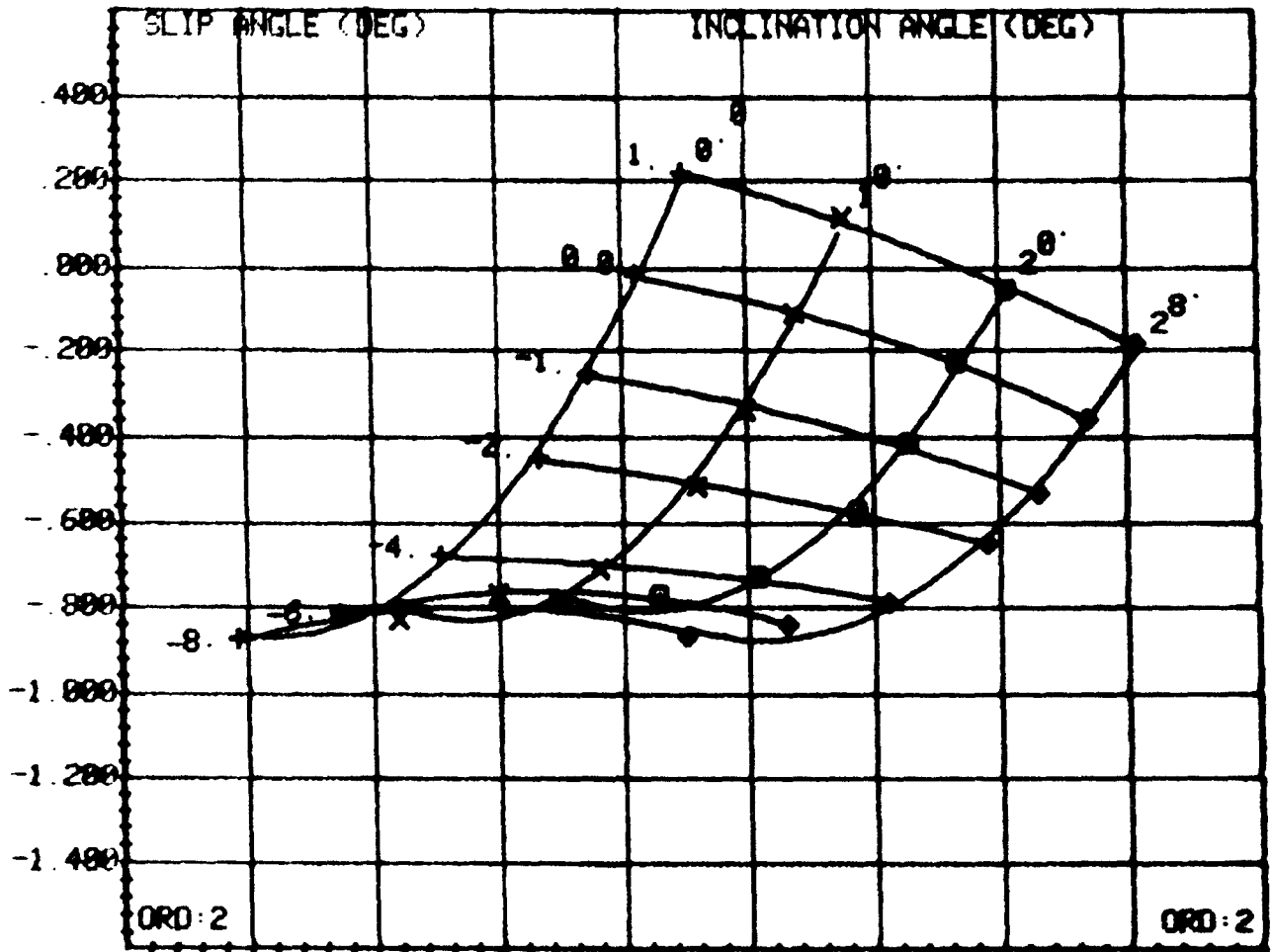
1: N F Y (FY/FZ)

RUN: 11-3-6



1: N F Y (FY/FZ)

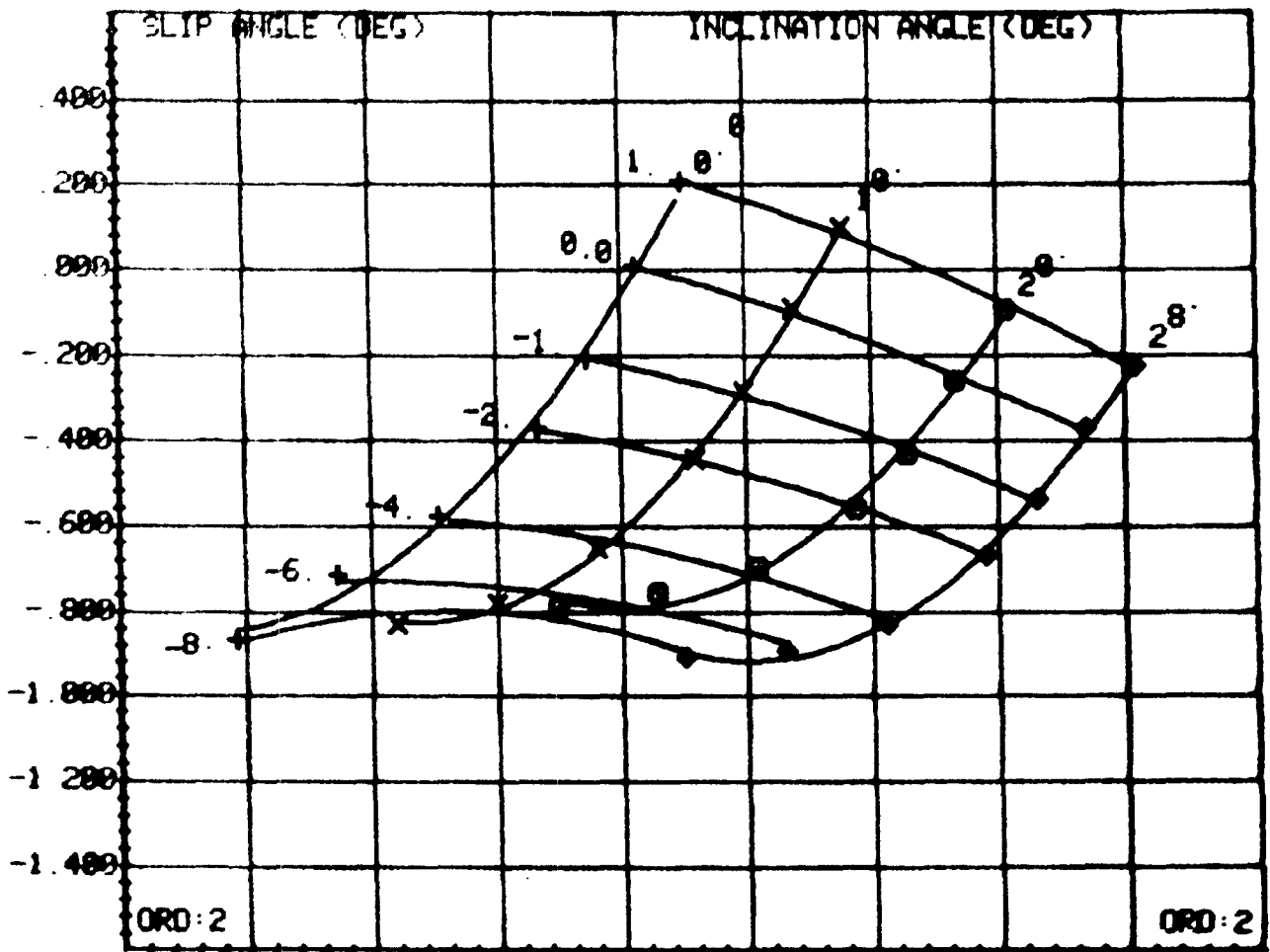
RUN: 12-3-6





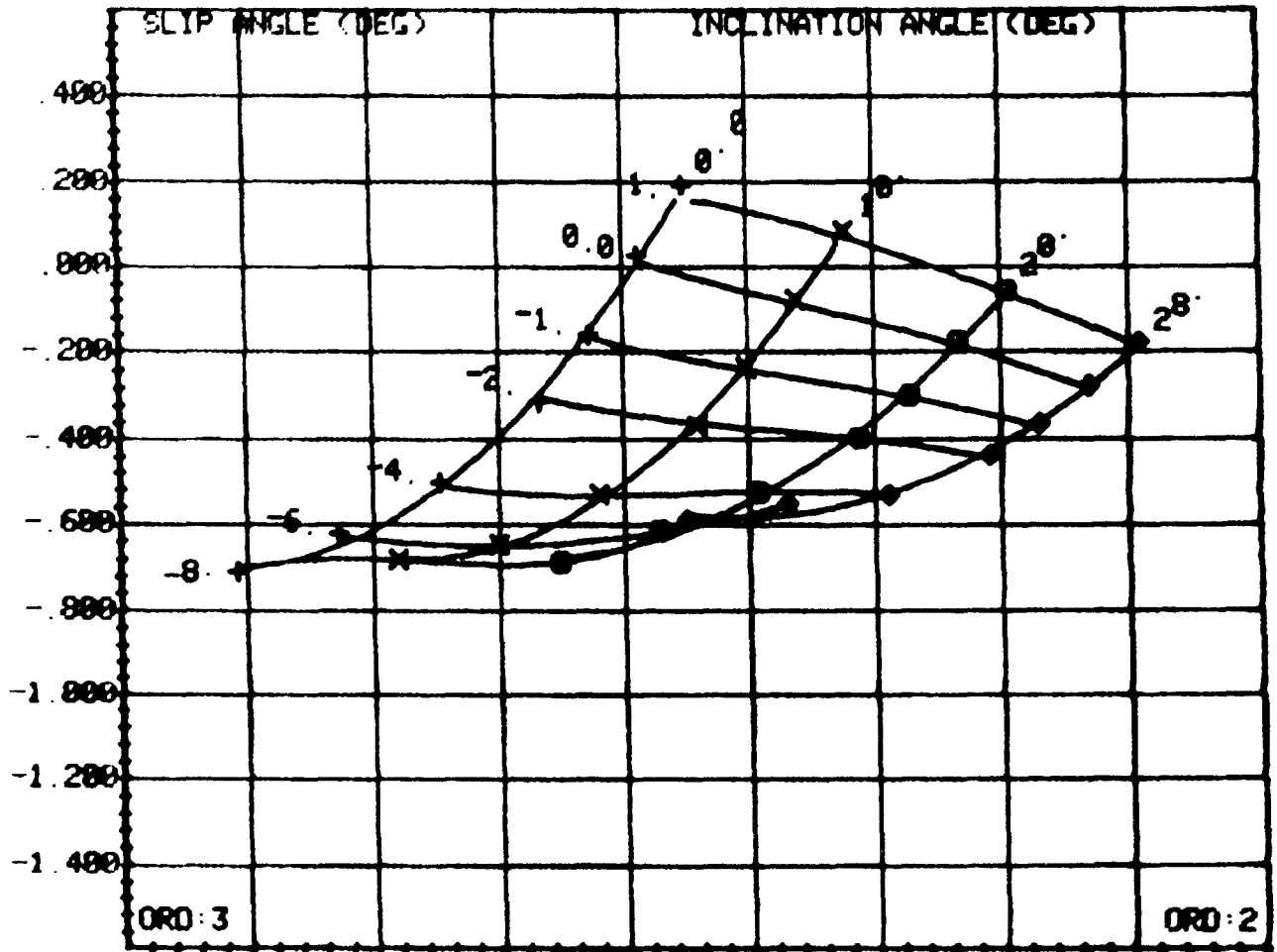
1: N F Y (FY/FZ)

RUN: 13- 3- 6



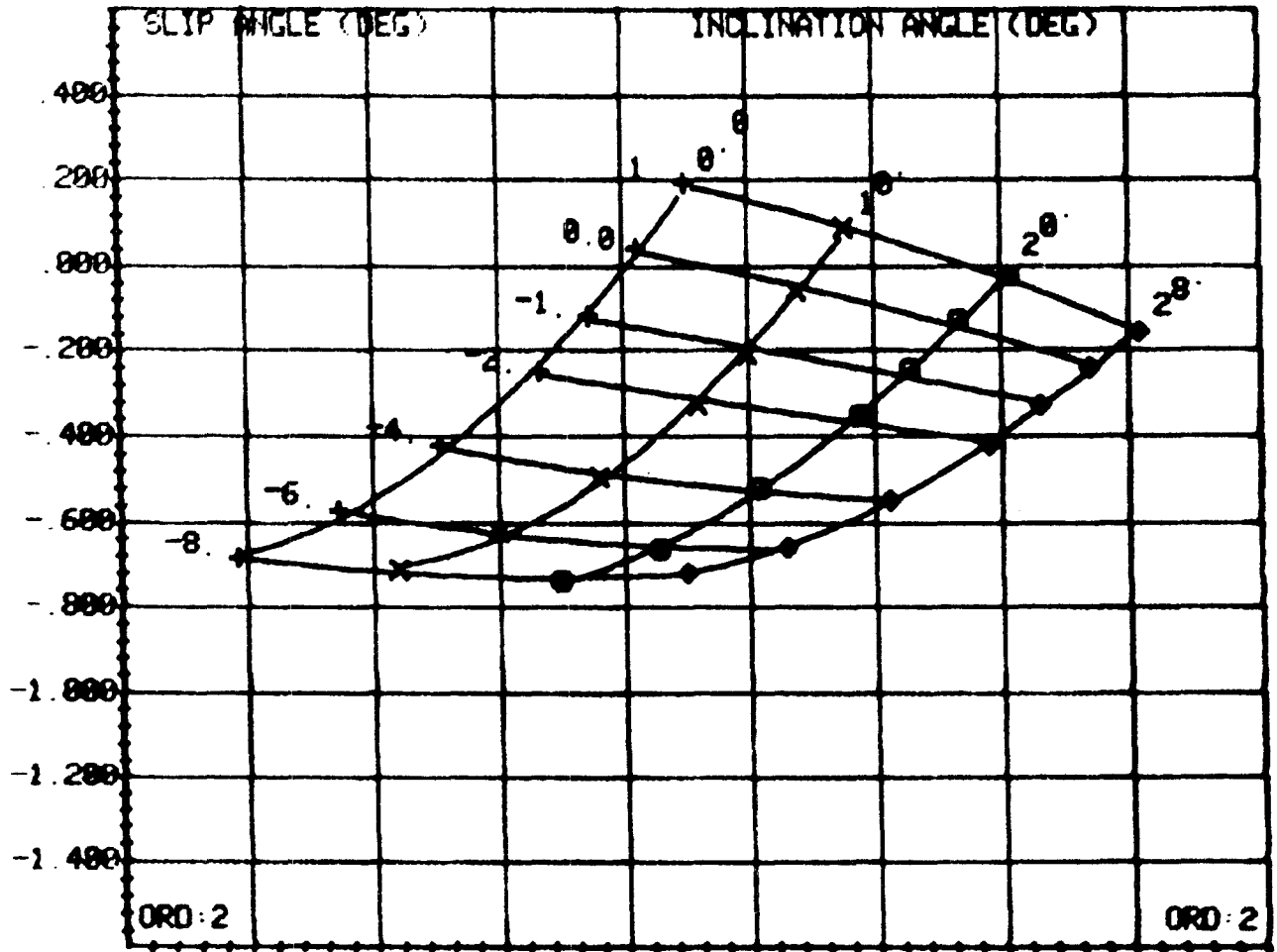
1- N F Y (FY/FZ)

RUN: 14-3-6



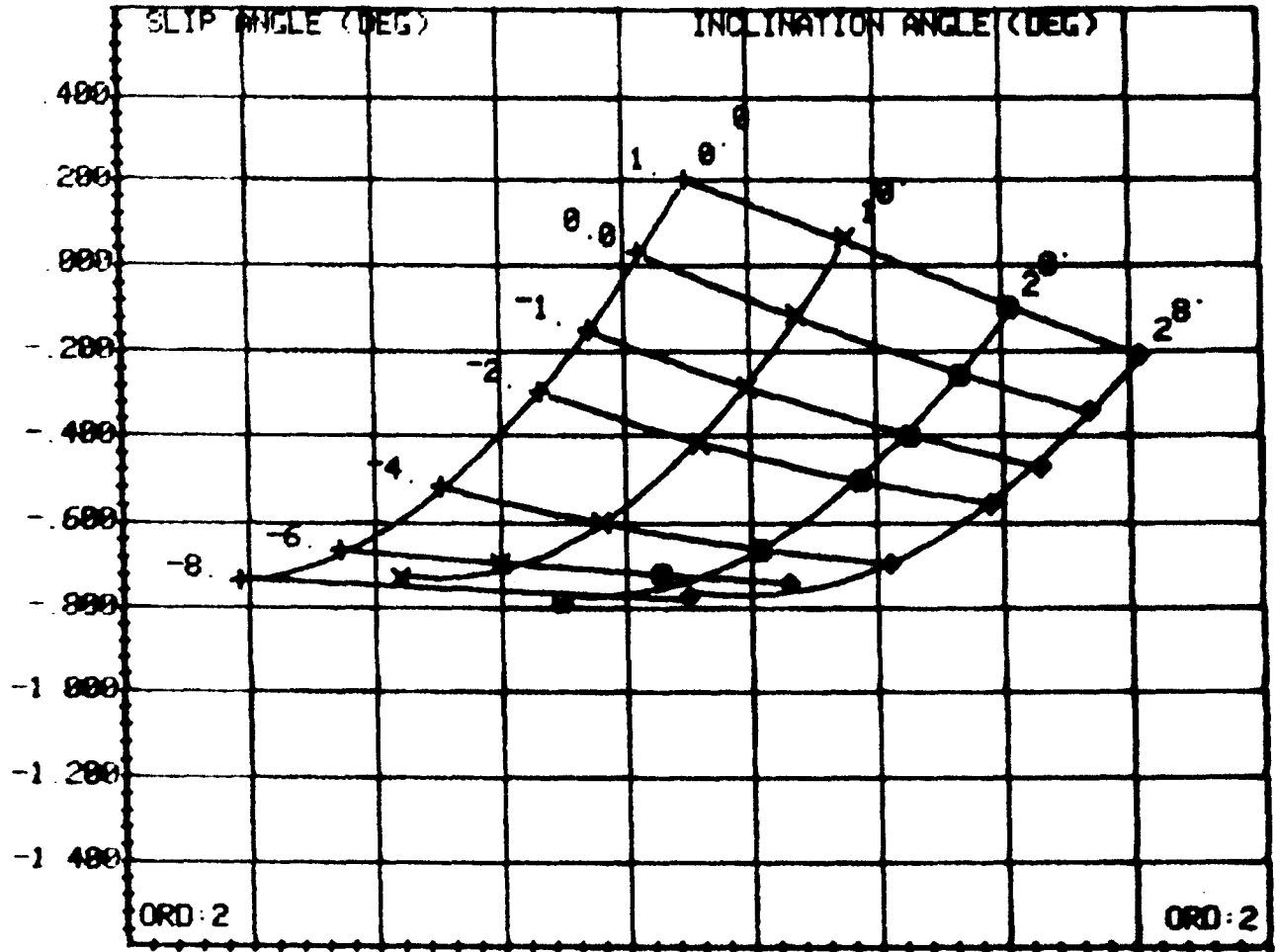
1: N F Y (FY/FZ)

RUN: 15- 3- 6



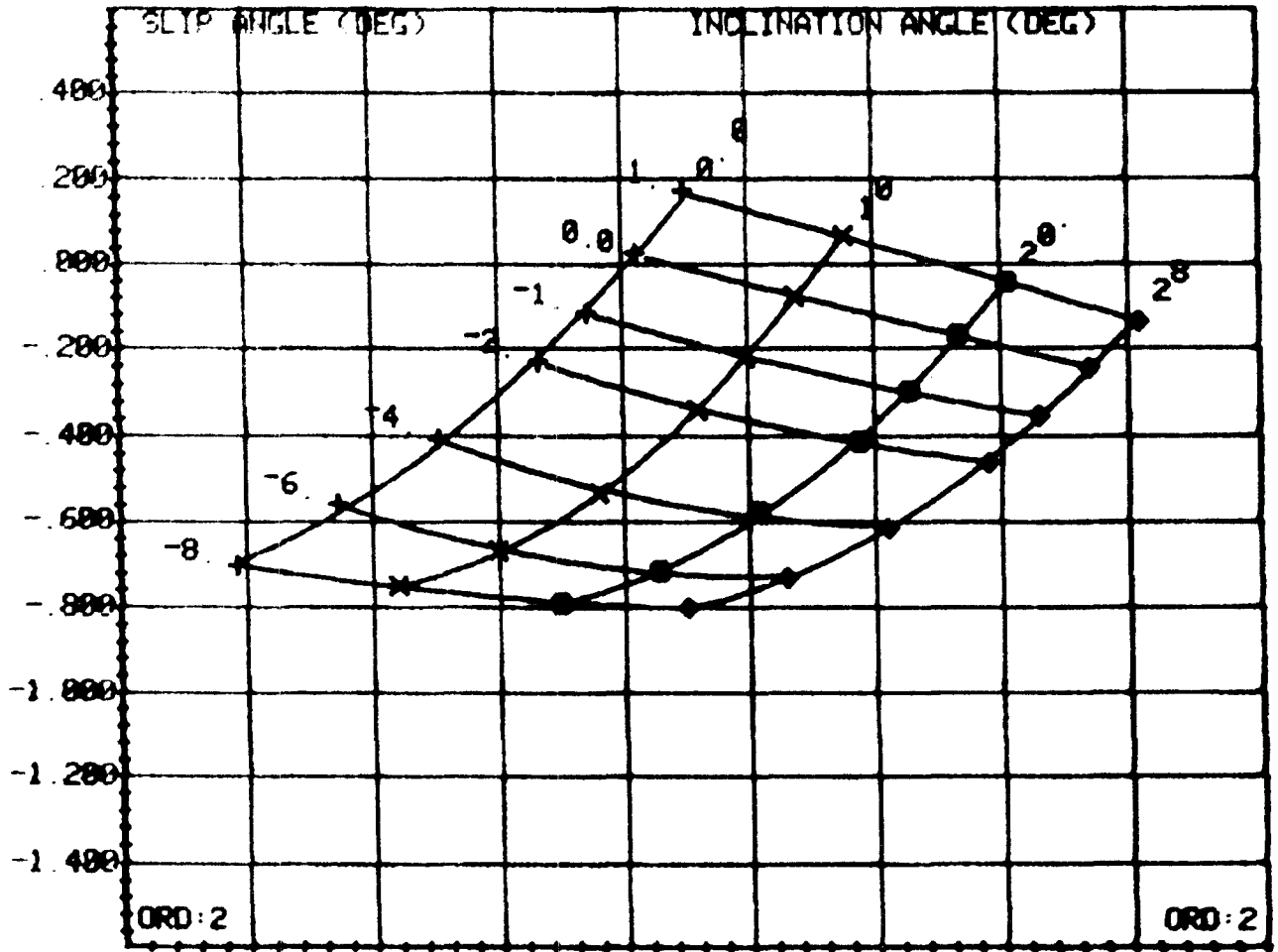
1: N F Y (FY/FZ)

RUN: 16-3-6



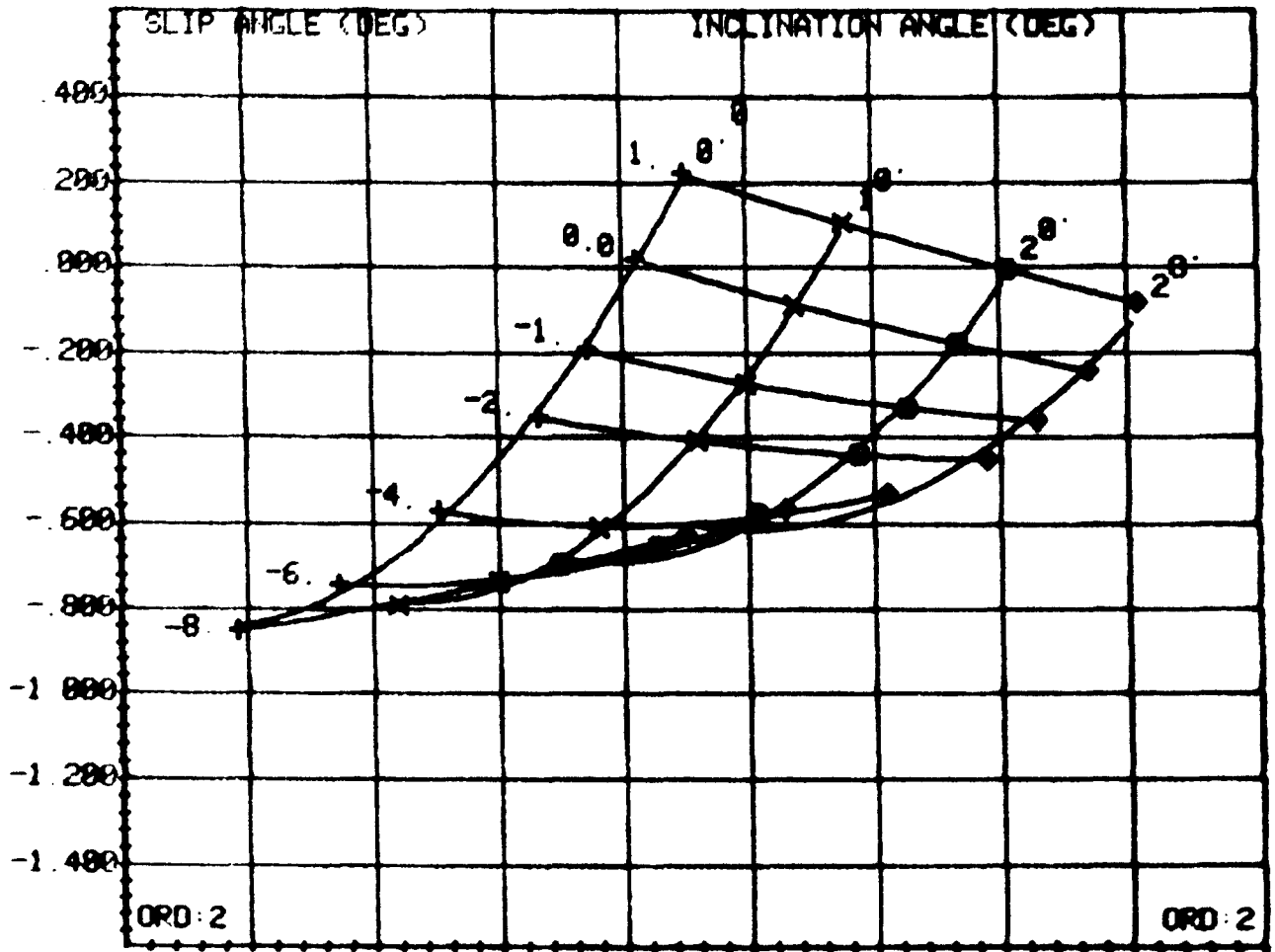
1. N F Y (FY/FZ)

RUN: 17- 3- 6



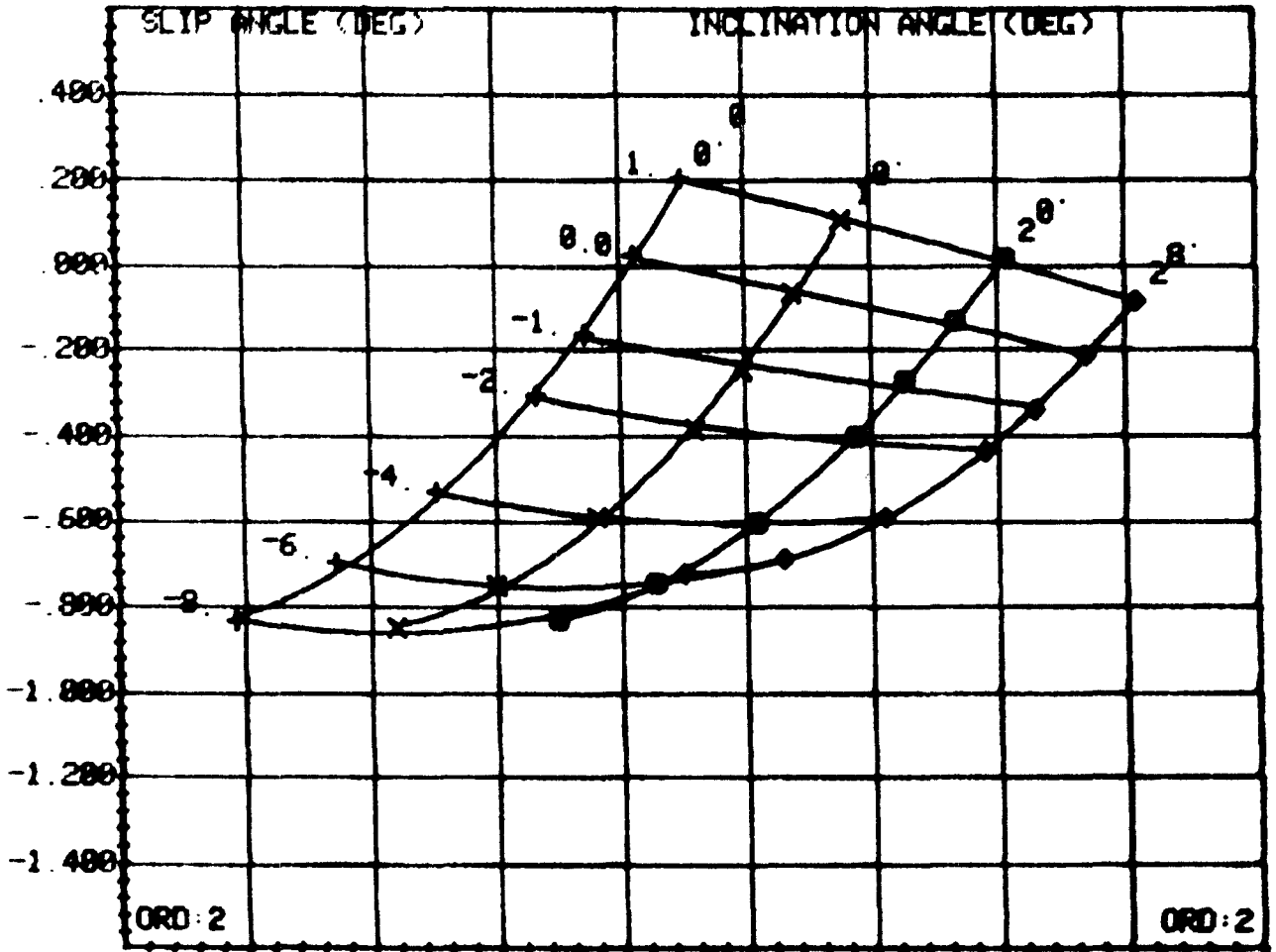
1: N F Y (FY/FZ)

RUN: 18-3-6



1: N F Y (FY/FZ)

RUN: 19-3-6



1-3-6 S.A. DEG	1-3-6 F.Z. LB	1-3-6 F.Y. LB	1-3-6 F.X. LB	1-3-6 M.X. FT-LB	1-3-6 M.Y. FT-LB	1-3-6 M.Z. FT-LB
I.A. =	0					
1.03	-124	-41	-1	-2	-1	6.1
0.04	-124	-2	-2	-2	-0.6	3.8
-0.94	-125	40	-2	-3	-0.6	2.6
-1.95	-125	68	-2	-4	-0.9	3.6
-3.93	-124	104	-1	-6	-1.7	3.5
-5.96	-125	127	-2	-6	-1.7	4.4
-7.97	-124	141	-3	-8	-3.5	4.2
I.A. =	10.02					
1.03	-138	-21	-3	-15	-0.0	7.9
0.04	-125	21	-1	-14	-0.0	5.4
-0.94	-111	52	-3	-15	-0.4	4.4
-1.93	-105	72	-1	-14	-2.2	3.1
-3.93	-99	93	-1	-15	-2.3	4.1
-5.96	-96	110	-1	-13	-2.3	5.1
-7.97	-93	113	-1	-14	-2.5	5.1
I.A. =	20.07					
1.03	-149	4	-3	-23	-2.0	8.3
0.04	-122	34	-3	-26	-1.0	5.8
-0.94	-103	59	-1	-24	-3.4	3.5
-1.95	-93	71	-3	-22	-1.3	3.5
-3.94	-82	77	-2	-25	-2.1	4.9
-5.95	-81	82	-0	-22	-4.1	3.3
-7.97	-81	84	-1	-23	-2.0	4.7
I.A. =	28.08					
1.03	-156	29	-4	-32	-3.6	10.1
0.04	-128	48	-3	-34	-2.7	7.1
-0.94	-108	63	-3	-33	-2.7	4.6
-1.95	-101	71	-1	-31	-3.4	4.2
-3.93	-94	76	-1	-32	-3.4	4.2
-5.96	-91	72	-1	-31	-3.7	4.5
-7.97	-89	73	-1	-33	-2.9	4.5



1-3-6 S.A. DEG	1-3-6 P.L. IN	1-3-6 I.A. DEG	1-3-6 U. MPH	1-3-6 N.F.Y. FY/FZ		
I.A. =	0.					
1	11.75	0	30.	0.33		
0.04	11.75	0	30.	0.02		
-0.94	11.75	0	30.	-0.32		
-1.95	11.73	0	30.	-0.54		
-3.93	11.72	0	30.	-0.84		
-5.95	11.71	0	30.	-1.01		
-7.97	11.7	0	30.	-1.14		
I.A. =	10.02					
1.03	11.74	10.02	30.	0.16		
0.04	11.78	10.02	30.	-0.17		
-0.94	11.81	10.02	30.	-0.47		
-1.93	11.82	10.02	30.	-0.69		
-3.93	11.83	10.02	30.	-0.94		
-5.95	11.83	10.02	30.	-1.15		
-7.97	11.83	10.02	30.	-1.22		
I.A. =	20.07					
1.03	11.8	20.07	30.	-0.03		
0.04	11.86	20.07	30.	-0.28		
-0.94	11.91	20.07	30.	-0.57		
-1.95	11.93	20.07	30.	-0.76		
-3.94	11.94	20.08	30.	-0.94		
-5.96	11.95	20.07	30.	-1.01		
-7.97	11.95	20.07	30.	-1.04		
I.A. =	28.08					
1.03	11.88	28.08	30.	-0.19		
0.04	11.94	28.1	30.	-0.37		
-0.94	12.	28.08	30.	-0.59		
-1.95	12.02	28.08	30.	-0.7		
-3.93	12.04	28.1	30.	-0.81		
-5.96	12.03	28.08	30.	-0.8		
-7.97	12.04	28.1	30.	-0.83		

2-3-6 S.A. DEG	2-3-6 F.Z. LB	2-3-6 F.Y. LB	2-3-6 F.X. LB	2-3-6 M.X. FT-LB	2-3-6 M.Y. FT-LB	2-3-6 M.Z. FT-LB
I.A. =	0					
1	-147	-53	-2	-2.8	-0.8	6.1
0.84	-148	-12	-2	-3.1	-0.6	3.8
-0.94	-151	35	-2	-4.2	-0.4	1.5
-1.95	-147	71	-2	-4.7	-0.4	0.4
-3.93	-151	123	-3	-5.5	-0.3	1.2
-5.96	-150	161	-4	-8	-0.5	3
-7.97	-148	176	-3	-9.6	-0.4	4.1
I.A. =	10.82					
1.03	-170	-26	-4	-12	-0.1	7.9
0.84	-151	20	-1	-14.2	-2.3	5.4
-0.94	-136	59	-1	-12	-2.3	3.2
-1.95	-128	83	-1	-15	-2.2	3.1
-3.94	-120	111	-3	-16	-0.8	3.1
-5.96	-114	128	-3	-13.3	-0.6	4.1
-7.97	-112	133	-3	-14.9	-1.2	5.1
I.A. =	20.07					
1.03	-178	11	-4	-22.6	-1.5	9.7
0.84	-152	47	-3	-22.4	-2.3	6.1
-0.94	-129	73	-1	-21.1	-2.9	3.6
-1.95	-113	85	-1	-22.5	-3.3	3.4
-3.94	-104	97	-2	-20.6	-2	3.8
-5.96	-101	108	-1	-21.3	-3.2	4.4
-7.97	-100	108	0	-18.9	-4.8	5.1
I.A. =	28.1					
1.01	-181	48	-6	-31.5	-2.5	11.7
0.84	-150	67	-4	-29.3	-2.2	7.2
-0.94	-131	86	-4	-28.9	-1.5	5.1
-1.95	-119	93	-1	-27.6	-3.3	4.4
-3.94	-112	102	-3	-28.1	-3.6	4.5
-5.96	-107	105	-2	-29.3	-3.4	5.2
-7.97	-108	106	-2	-27	-3.4	5.2

2-3-6 S.A. DEG	2-3-6 P.L IN	2-3-6 I.A DEG	2-3-6 I. MPH	2-3-6 N.F.Y. FY/FZ
I.A. =	0.			
1.	11.7	0	30	0.36
0.04	11.71	0	30	0.08
-0.94	11.71	0	30	-0.23
-1.95	11.7	0	30	-0.48
-3.93	11.67	0	30	-0.82
-5.96	11.65	0	30	-1.08
-7.97	11.63	0	30	-1.19
I.A. =	10.02			
1.03	11.68	10.02	30	0.15
0.04	11.73	10.02	30	-0.14
-0.94	11.76	10.02	30	-0.44
-1.95	11.77	10.02	30	-0.65
-3.94	11.78	10.02	30	-0.92
-5.96	11.79	10.02	30	-1.13
-7.97	11.79	10.02	30	-1.19
I.A. =	20.07			
1.03	11.75	20.07	30	-0.06
0.04	11.82	20.07	30	-0.31
-0.94	11.87	20.07	30	-0.57
-1.95	11.89	20.08	30	-0.75
-3.94	11.9	20.08	30	-0.93
-5.96	11.93	20.07	30	-1.07
-7.97	11.91	20.08	30	-1.08
I.A. =	28.1			
1.01	11.86	28.1	30	-0.27
0.04	11.92	28.1	30	-0.45
-0.94	11.99	28.08	30	-0.66
-1.95	12.02	28.1	30	-0.78
-3.94	12.03	28.1	30	-0.91
-5.96	12.04	28.1	30	-0.98
-7.97	12.04	28.1	30	-0.98

4-3-6 S.A. DEG	4-3-6 F.Z. LB	4-3-6 F.Y. LB	4-3-6 F.X. LB	4-3-6 M.X. FT-LB	4-3-6 M.Y. FT-LB	4-3-6 M.Z. FT-LB
I.A. =	0					
1	-378	-59	-5	-3.1	1.1	12.7
0.04	-377	-6	-7.5	-7.3	3.3	5.1
-0.94	-379	49	-6.	-10.7	3.2	0.2
-1.95	-380	101	-6.	-12.6	4.3	-4.7
-3.94	-380	197	-6.	-19.	4.3	-10.4
-5.96	-378	276	-6.	-26.5	5.5	-9.6
-7.97	-377	334	-10.	-33.6	6.6	0.
I.A. =	10.02					
1.03	-403	2	-7.	-22.8	1.9	16.
0.04	-383	53	-6.	-24.9	1.2	9.5
-0.94	-364	188	-6.	-26.9	1.5	3.
-1.95	-349	155	-6.	-38.	2.	-1.3
-3.94	-324	232	-6.	-34.	1.1	-3.8
-5.96	-305	278	-6.	-37.9	1.6	-1.8
-7.97	-296	305	-4.	-36.5	0.3	2.1
I.A. =	20.07					
1.03	-433	72	-11.	-41.6	1.8	20.
0.04	-394	115	-7.	-43.5	0.3	12.8
-0.94	-359	156	-4.	-42.5	0.5	5.9
-1.95	-330	189	-4.	-44.8	0.1	1.6
-3.94	-293	231	-3.	-44.3	0.1	0.4
-5.96	-279	254	-2.	-43.1	0.9	1.9
-7.97	-267	262	-4.	-42.5	0.5	4.4
I.A. =	28.1					
1.01	-465	137	-13.	-57.4	-0.3	23.6
0.04	-415	171	-9.	-57.3	-0.2	14.3
-0.94	-371	200	-6.	-56.1	-0.1	7.4
-1.95	-338	220	-6.	-56.	0.8	4.2
-3.94	-302	244	-2.	-54.7	0.3	2.7
-5.96	-290	256	-3.	-53.1	0.9	4.
-7.97	-287	261	-3.	-50.6	0.8	5.6

4-3-6 S.A. DEG	4-3-6 R.L. IN	4-3-6 I.A. DEG	4-3-6 II. MPH	4-3-6 N.F.Y. FY/FZ		
I.A. =	0					
1	12.18	0	30	0.15		
0.04	12.19	0	30	0.02		
-0.94	12.18	0	30	-0.13		
-1.95	12.16	0	30	-0.27		
-3.94	12.11	0	30	-0.52		
-5.96	12.04	0	30	-0.73		
-7.97	11.98	0	30	-0.89		
I.A. =	10.02					
1.03	12.17	10.02	30	-0		
0.04	12.2	10.02	30	-0.14		
-0.94	12.23	10.02	30	-0.3		
-1.95	12.24	10.02	30	-0.44		
-3.94	12.25	10.02	30	-0.72		
-5.96	12.25	10.02	30	-0.91		
-7.97	12.25	10.03	30	-1.03		
I.A. =	20.07					
1.03	12.23	20.07	30	-0.17		
0.04	12.31	20.07	30	-0.29		
-0.94	12.37	20.07	30	-0.44		
-1.95	12.4	20.07	30	-0.57		
-3.93	12.45	20.08	30	-0.79		
-5.96	12.47	20.08	30	-0.91		
-7.97	12.48	20.08	30	-0.98		
I.A. =	28.1					
1.01	12.31	28.1	30	-0.29		
0.04	12.41	28.1	30	-0.41		
-0.94	12.49	28.08	30	-0.54		
-1.95	12.54	28.1	30	-0.65		
-3.94	12.61	28.1	30	-0.81		
-5.96	12.63	28.1	30	-0.89		
-7.97	12.63	28.08	30	-0.91		

5-3-6 S.A. DEG	5-3-6 F.Z. LB	5-3-6 F.Y. LB	5-3-6 F.X. LB	5-3-6 M.X. FT-LB	5-3-6 M.Y. FT-LB	5-3-6 M.Z. FT-LB
I.A. =	0					
1	-209	-69	4	-1	1	5
0.94	-212	-11	4	-1	0	4
-0.94	-211	53	4	-4	0	2
-1.95	-212	99	4	-2	0	2
-3.94	-211	159	4	-5	0	4
-5.96	-213	208	4	-7	1	4
-7.97	-210	218	4	-7	2	8
I.A. =	10.82					
1.03	-240	-40	4	-13	0	11
0.83	-214	24	4	-14	0	6
-0.94	-194	80	4	-15	0	3
-1.95	-182	118	4	-16	0	3
-3.94	-172	156	4	-15	1	4
-5.96	-166	174	4	-15	2	4
-7.97	-162	180	4	-15	0	9
I.A. =	20.87					
1.03	-254	14	-1	-38	0	14
0.94	-211	64	-1	-38	0	8
-0.94	-179	107	-1	-27	0	5
-1.95	-162	126	-1	-27	0	4
-3.94	-147	144	-1	-27	0	4
-5.96	-142	149	-1	-27	0	5
-7.97	-142	150	-1	-27	0	6
I.A. =	28.1					
1.01	-271	60	-1	-43	1	17
0.84	-219	99	-1	-40	1	11
-0.94	-175	123	-1	-39	1	6
-1.95	-157	138	-1	-39	0	5
-3.94	-143	143	-1	-36	0	5
-5.96	-141	148	-1	-36	0	6
-7.97	-141	146	-1	-36	0	6

5-3-6 S.A. DEG	5-3-6 P.L. IN	5-3-6 I.A. DEG	5-3-6 I. MPH	5-3-6 N.F.Y. FY/FZ
I.A. =	0.			
1.	12.04	0.	30.	0.33
0.04	12.04	0.	30.	0.05
-0.94	12.04	0.	30.	-0.25
-1.95	12.02	0.	30.	-0.46
-3.94	11.99	0.	30.	-0.75
-5.96	11.96	0.	30.	-0.98
-7.97	11.95	0.	30.	-1.04
I.A. =	10.02			
1.03	12.02	10.02	30.	0.17
0.03	12.06	10.02	30.	-0.11
-0.94	12.08	10.02	30.	-0.41
-1.95	12.1	10.02	30.	-0.65
-3.94	12.1	10.02	30.	-0.9
-5.96	12.1	10.02	30.	-1.05
-7.97	12.1	10.02	30.	-1.11
I.A. =	20.07			
1.03	12.08	20.07	30.	-0.05
0.04	12.15	20.07	30.	-0.31
-0.94	12.21	20.07	30.	-0.6
-1.95	12.24	20.07	30.	-0.78
-3.94	12.25	20.08	30.	-0.98
-5.96	12.26	20.08	30.	-1.05
-7.97	12.25	20.08	30.	-1.06
I.A. =	28.1			
1.01	12.16	28.1	30.	-0.22
0.04	12.25	28.1	30.	-0.45
-0.94	12.33	28.1	30.	-0.7
-1.95	12.36	28.1	30.	-0.88
-3.94	12.39	28.08	30.	-1.
-5.96	12.38	28.1	30.	-1.05
-7.97	12.39	28.08	30.	-1.04

6-3-6 S.A. DEG	6-3-6 F.Z. LB	6-3-6 F.Y. LB	6-3-6 F.X. LB	6-3-6 M.X. FT-LB	6-3-6 M.Y. FT-LB	6-3-6 M.Z. FT-LB
I A. =	0					
1.03	-247	-87	-5	1.5	1.5	9.6
0.04	-252	-22	-4	1.1	1.4	5.9
-0.94	-251	45	-5	-2.7	2.2	1.1
-1.95	-249	103	-4	-4.5	1.2	-1.1
-3.94	-247	198	-5	-7.3	2.2	-1.5
-5.95	-250	253	-5	-10.7	2.1	2.4
-7.97	-249	281	-6	-12.3	2.4	5.4
I A. =	10.02					
1.03	-276	-36	-6	-14.4	0.6	13.2
0.04	-258	24	-6	-15.0	1.5	7.0
-0.94	-237	88	-4	-14.5	0.5	3.3
-1.95	-219	135	-4	-15.5	0.6	1.1
-3.94	-198	187	-5	-17.0	0.9	1.0
-5.95	-186	212	-4	-18.7	-0.1	4.0
-7.97	-188	222	-4	-17.4	0.1	5.0
I A. =	20.07					
1.03	-296	24	-8	-31.5	-0.6	17.5
0.04	-252	79	-5	-31.1	-0.7	10.7
-0.94	-214	126	-4	-28.4	-0.6	5.1
-1.95	-189	153	-4	-27.3	-0.3	3.1
-3.94	-167	177	-3	-28.5	-1.7	4.6
-5.95	-160	184	-3	-28.5	-2.4	6.5
-7.97	-161	187	-2	-27.6	-3.2	7.3
I A. =	28.1					
1.01	-309	78	-11	-44.7	-1.6	21.1
0.04	-253	117	-8	-42.4	-0.7	12.2
-0.94	-206	147	-4	-39	-2.2	6.7
-1.95	-183	167	-4	-37.7	-1.1	4.9
-3.93	-164	175	-3	-37.0	-3.3	6.1
-5.95	-160	180	-2	-35.4	-4.2	6.0
-7.97	-160	179	-2	-35.5	-3.7	7.



6-3-6 S.A. DEG	6-3-6 P.L. IN	6-3-6 I.A. DEG	6-3-6 U MPH	6-3-6 N.F.Y. FY/FZ		
I.A. =	0					
1.04	11.96	0	30	0.35		
0.04	11.96	0	30	0.09		
-0.94	11.96	0	30	-0.18		
-1.95	11.94	0	30	-0.41		
-3.94	11.89	0	30	-0.8		
-5.96	11.84	0	30	-1.01		
-7.97	11.81	0	30	-1.13		
I.A. =	10.02					
1.03	11.94	10.02	30	0.13		
0.04	11.97	10.02	30	-0.09		
-0.94	12.01	10.02	30	-0.37		
-1.95	12.02	10.02	30	-0.61		
-3.94	12.03	10.02	30	-0.95		
-5.96	12.03	10.02	30	-1.14		
-7.97	12.02	10.02	30	-1.18		
I.A. =	20.07					
1.03	12.	20.07	30	-0.08		
0.04	12.07	20.07	30	-0.31		
-0.94	12.13	20.07	30	-0.59		
-1.95	12.17	20.07	30	-0.81		
-3.94	12.2	20.07	30	-1.05		
-5.96	12.2	20.07	30	-1.15		
-7.97	12.2	20.07	30	-1.16		
I.A. =	28.1					
1.01	12.07	28.1	30	-0.25		
0.04	12.17	28.1	30	-0.46		
-0.94	12.27	28.08	30	-0.72		
-1.95	12.3	28.1	30	-0.91		
-3.93	12.33	28.08	30	-1.07		
-5.96	12.33	28.08	30	-1.13		
-7.97	12.33	28.1	30	-1.12		

7-3-6 S.A. DEG	7-3-6 F.Z. LB	7-3-6 F.Y. LB	7-3-6 F.X. LB	7-3-6 M.X. FT-LB	7-3-6 M.Y. FT-LB	7-3-6 M.Z. FT-LB
I.A. =	0					
1	-315	-50	-5	1.6	1.2	10.7
0.04	-315	4	-5.5	-1.1	1.6	10.3
-0.94	-314	61	-4.5	-2.7	1.6	10.1
-1.95	-313	111	-6	-3.3	2.2	10.5
-3.94	-316	194	-8	-10.9	4.1	10.1
-5.95	-316	260	-6	-14.3	2.4	10.1
-7.97	-318	300	-8	-15.8	4.1	10.3
I.A. =	10.02					
1.03	-335	5	-7	-18.1	1.9	14.4
0.04	-315	60	-5.5	-20	0.6	10.4
-0.94	-294	112	-4.5	-22.6	0.2	10.4
-1.95	-279	157	-4	-23.9	0.1	10.4
-3.94	-257	220	-3	-23.9	-0.6	10.7
-5.95	-246	253	-4	-28	0.1	10.3
-7.97	-242	263	-2	-23.8	-2.3	10.2
I.A. =	20.07					
1.03	-349	64	-9	-41.5	0.2	17.3
0.04	-315	109	-6	-39.7	-0.1	10.6
-0.94	-281	148	-3	-40.7	-2.2	4.4
-1.95	-252	176	-2	-39.9	-2.1	2.1
-3.94	-226	213	-1	-38.2	-2.8	2.9
-5.95	-215	227	-3	-36.9	-1.4	4.3
-7.97	-212	233	-2	-33.7	-2.7	5.
I.A. =	28.1					
1.01	-373	112	-13	-58.1	0.1	20.4
0.04	-328	148	-7	-55.3	-1.3	12.8
-0.94	-284	174	-6	-54.9	-0.4	6.2
-1.95	-259	192	-3	-53.9	-1.2	3.4
-3.94	-232	213	-3	-51.4	-2	4.1
-5.95	-222	217	-2	-50.8	-3.4	4.6
-7.97	-221	222	-4	-50.9	-2.2	6.2

7-3-6 S.A. DEG	7-3-6 P.L. IN	7-3-6 I.A. DEG	7-3-6 U MPH	7-3-6 N.F.Y. FY/FZ
I.A. =	0			
1	12.25	0	30	0.16
0.04	12.25	0	30	-0.01
-0.94	12.25	0	30	-0.19
-1.95	12.24	0	30	-0.36
-3.94	12.18	0	30	-0.61
-5.96	12.13	0	30	-0.82
-7.97	12.08	0	30	-0.94
I.A. =	10.02			
1.03	12.24	10.02	30	-0.01
0.04	12.27	10.02	30	-0.19
-0.94	12.3	10.02	30	-0.38
-1.95	12.31	10.02	30	-0.56
-3.94	12.31	10.02	30	-0.83
-5.96	12.32	10.02	30	-1.03
-7.97	12.31	10.02	30	-1.09
I.A. =	20.07			
1.03	12.32	20.07	30	-0.18
0.04	12.39	20.07	30	-0.35
-0.94	12.44	20.07	30	-0.53
-1.95	12.47	20.07	30	-0.7
-3.93	12.52	20.07	30	-0.95
-5.96	12.53	20.08	30	-1.06
-7.97	12.53	20.08	30	-1.1
I.A. =	28.1			
1.01	12.4	28.1	30	-0.3
0.04	12.48	28.1	30	-0.45
-0.94	12.57	28.1	30	-0.61
-1.95	12.63	28.1	30	-0.74
-3.94	12.67	28.1	30	-0.92
-5.96	12.68	28.1	30	-0.98
-7.97	12.7	28.1	30	-1.

8-3-6 S.A. DEG	8-3-6 F.Z. LB	8-3-6 F.Y. LB	8-3-6 F.X. LB	8-3-6 M.X. FT-LB	8-3-6 M.Y. FT-LB	8-3-6 M.Z. FT-LB
I A. =	0					
1.	-237	-53	4	3	1	7
0.04	-241	2	4	0	1	3
-0.94	-238	63	4	0	1	0
-1.95	-243	110	4	2	0	0
-3.94	-241	167	4	0	0	2
-5.96	-241	198	4	0	1	4
-7.97	-240	213	3	0	0	6
I A. =	10.02					
1.03	-258	-12	4	-15	0	11
0.04	-238	44	4	-17	0	6
-0.94	-221	94	4	-18	1	3
-1.95	-211	126	4	-18	0	3
-3.93	-200	146	4	-19	0	3
-5.96	-196	155	4	-18	0	2
-7.97	-200	159	3	-17	0	4
I A. =	20.07					
1.03	-279	32	7	-33	0	12
0.03	-246	74	7	-32	0	8
-0.94	-219	107	7	-31	0	4
-1.95	-202	120	7	-32	0	4
-3.94	-194	126	7	-33	2	4
-5.96	-194	133	7	-31	0	4
-7.97	-188	137	6	-32	0	5
I A. =	28.1					
1.01	-313	71	-11	-49	1	16
0.04	-267	96	-6	-47	0	10
-0.94	-232	120	-4	-47	-1	5
-1.95	-218	137	-4	-44	0	4
-3.94	-207	146	-4	-44	-1	5
-5.96	-199	153	-4	-44	-1	5
-7.97	-193	153	-4	-45	-1	5

8-3-6 S.A. DEG	8-3-6 P.L. IN	8-3-6 I.A. DEG	8-3-6 U. MPH	8-3-6 N.F.Y. FY/FZ
I.A. =	0			
1	12.84	0	30	0.22
0.04	12.85	0	30	-0.01
-0.94	12.84	0	30	-0.26
-1.95	12.83	0	30	-0.45
-3.94	12.81	0	30	-0.69
-5.96	12.79	0	30	-0.82
-7.97	12.78	0	30	-0.89
I.A. =	10.02			
1.03	12.82	10.02	30	0.04
0.04	12.86	10.02	30	-0.19
-0.94	12.88	10.02	30	-0.43
-1.95	12.91	10.02	30	-0.6
-3.93	12.92	10.02	30	-0.73
-5.96	12.91	10.02	30	-0.79
-7.97	12.9	10.02	30	-0.8
I.A. =	20.07			
1.03	12.87	20.07	30	-0.11
0.03	12.93	20.08	30	-0.3
-0.94	13	20.07	30	-0.49
-1.95	13.01	20.07	30	-0.59
-3.94	13.02	20.07	30	-0.65
-5.96	13.03	20.07	30	-0.68
-7.97	13.03	20.07	30	-0.73
I.A. =	28.1			
1.01	12.93	28.1	30	-0.23
0.04	13.02	28.1	30	-0.36
-0.94	13.07	28.1	30	-0.52
-1.95	13.13	28.08	30	-0.63
-3.94	13.15	28.08	30	-0.71
-5.96	13.17	28.1	30	-0.77
-7.97	13.17	28.1	30	-0.8

9-3-6 S.A. DEG	9-3-6 F.Z. LB	9-3-6 F.Y. LB	9-3-6 F.X. LB	9-3-6 M.X. FT-LB	9-3-6 M.Y. FT-LB	9-3-6 M.Z. FT-LB
I.A. =	0					
1	-288	-73	4.5	2.7	2.4	8.3
0.04	-285	-12	4.5	1.5	1.4	4.9
-0.94	-291	51	4.5	0.1	1.2	0.3
-1.95	-284	98	4.5	4.3	2.8	1.7
-3.93	-289	170	4.5	6.4	3.4	0.9
-5.96	-290	221	4.5	9.1	4	0.9
-7.97	-290	252	4.5	11.1	2.4	0.8
I.A. =	10.82					
1.03	-313	-17	4.5	-13	2.2	11.9
0.04	-291	40	4.5	-14.9	1.6	7.2
-0.94	-273	92	4.5	-18.3	0.7	3.6
-1.93	-263	125	4.5	-17.6	0.9	2.5
-3.93	-248	164	4.5	-19.7	1.1	2.4
-5.96	-241	189	4.5	-20.3	0.3	4.2
-7.97	-233	206	4.5	-20.7	0.6	3.3
I.A. =	20.88					
1.01	-343	37	4.5	-38.9	1.3	13.7
0.04	-304	82	4.5	-38.7	1.8	10.1
-0.94	-271	119	4.5	-38.5	0.1	3.7
-1.95	-251	139	4.5	-31.5	0.5	4.3
-3.93	-230	166	4.5	-29	1.2	3.9
-5.96	-224	180	4.5	-28.5	0.8	4.1
-7.97	-214	193	4.5	-28.2	0.3	3.3
I.A. =	28.1					
1.01	-368	94	4.5	-44.3	1.4	19.2
0.04	-326	129	4.5	-41.6	0.8	12.6
-0.94	-286	156	4.5	-41.5	0.1	7.2
-1.93	-262	165	4.5	-42.4	0.1	6.
-3.93	-242	189	4.5	-40.4	0.1	4.6
-5.96	-229	192	4.5	-39.4	0.1	3.6
-7.97	-220	198	4.5	-40.3	0.9	2.2

9-3-6 S.A. DEG	9-3-6 R.L. IN	9-3-6 I.A. DEG	9-3-6 U. MPH	9-3-6 N.F.Y. FY/FZ
I.A. =	0.			
1.	12.77	0.	38.	0.23
0.04	12.78	0.	38.	0.04
-0.94	12.77	0.	38.	-0.18
-1.95	12.76	0.	38.	-0.33
-3.93	12.73	0.	38.	-0.59
-5.96	12.7	0.	38.	-0.76
-7.97	12.68	0.	38.	-0.87
I.A. =	10.02			
1.03	12.73	10.02	38.	0.05
0.04	12.77	10.02	38.	-0.14
-0.94	12.8	10.02	38.	-0.34
-1.93	12.82	10.02	38.	-0.47
-3.93	12.83	10.02	38.	-0.66
-5.96	12.84	10.02	38.	-0.78
-7.97	12.84	10.02	38.	-0.88
I.A. =	20.08			
1.01	12.76	20.08	38.	-0.11
0.04	12.84	20.07	38.	-0.27
-0.94	12.9	20.07	38.	-0.44
-1.95	12.92	20.07	38.	-0.55
-3.93	12.95	20.07	38.	-0.72
-5.96	12.98	20.08	38.	-0.8
-7.97	13.	20.07	38.	-0.9
I.A. =	28.1			
1.01	12.83	28.1	38.	-0.26
0.04	12.93	28.1	38.	-0.4
-0.94	13.01	28.1	38.	-0.54
-1.93	13.04	28.08	38.	-0.63
-3.93	13.11	28.1	38.	-0.78
-5.96	13.11	28.1	38.	-0.84
-7.97	13.12	28.08	38.	-0.9

10-3-6 S.A. DEG	10-3-6 F.Z. LB	10-3-6 F.Y. LB	10-3-6 F.X. LB	10-3-6 M.X. FT-LB	10-3-6 M.Y. FT-LB	10-3-6 M.Z. FT-LB
I A. =	0					
1	-361	-58	-6	1.7	3.7	3.9
0.04	-359	4	-6	-3.2	3.6	3.5
-0.94	-363	72	-6	-3.0	3.5	3.7
-1.95	-359	126	-6	-3.9	3.7	1.6
-3.94	-361	202	-6	-9.6	4.7	0.1
-5.95	-361	248	-6	-12.6	3.2	1.1
-7.97	-359	272	-7	-12.6	3.6	3.1
I A. =	10.02					
1.03	-384	-2	-7	-20.2	2.6	14.1
0.03	-361	60	-6	-21.6	2.1	0.6
-0.94	-342	115	-4	-24.7	1.1	4.6
-1.95	-328	155	-3	-22.7	1.1	1.8
-3.94	-310	200	-3	-24.5	2.2	2.8
-5.95	-298	233	-3	-23.7	1.6	4.7
-7.97	-294	247	-4	-23.7	0.2	6.3
I A. =	20.07					
1.03	-405	65	-11	-43.7	2.6	16.9
0.04	-366	118	-9	-42.6	2.2	11.2
-0.94	-331	160	-6	-40.9	1.7	6.4
-1.95	-307	186	-6	-43.2	0.7	3.1
-3.94	-282	213	-6	-40.4	0.9	3.6
-5.95	-270	226	-6	-38.2	0.5	6.6
-7.97	-261	235	-4	-38.6	1.2	6.4
I A. =	28.1					
1.01	-431	125	-14	-63.1	2.1	22.4
0.03	-382	164	-9	-59.5	0.6	14.7
-0.94	-335	191	-6	-58.0	1.2	9.0
-1.95	-307	211	-6	-55.0	0.9	9.0
-3.94	-282	233	-6	-53.0	0.7	9.0
-5.95	-274	240	-6	-51.6	0.3	9.0
-7.97	-266	239	-6	-48.6	0.3	6.9



10-3-6 S.A. DEG	10-3-6 P.L. IN	10-3-6 I.A. DEG	10-3-6 U. MPH	10-3-6 N.F.Y. FY/FZ
I.A. =	0			
1	12.6	0	30	0.16
0.04	12.6	0	30	-0.01
-0.94	12.61	0	30	-0.2
-1.95	12.6	0	30	-0.93
-3.94	12.57	0	30	-0.56
-5.96	12.54	0	30	-0.69
-7.97	12.53	0	30	-0.76
I.A. =	10.02			
1.03	12.62	10.02	30	0.01
0.03	12.65	10.03	30	-0.17
-0.94	12.68	10.02	30	-0.33
-1.95	12.68	10.03	30	-0.47
-3.94	12.7	10.02	30	-0.65
-5.96	12.7	10.02	30	-0.78
-7.97	12.7	10.02	30	-0.84
I.A. =	20.07			
1.03	12.7	20.07	30	-0.16
0.04	12.76	20.07	30	-0.32
-0.94	12.81	20.07	30	-0.48
-1.95	12.86	20.07	30	-0.6
-3.94	12.87	20.08	30	-0.73
-5.96	12.89	20.08	30	-0.84
-7.97	12.9	20.07	30	-0.9
I.A. =	28.1			
1.01	12.82	28.1	30	-0.29
0.03	12.88	28.1	30	-0.43
-0.94	12.95	28.1	30	-0.57
-1.95	13.	28.1	30	-0.69
-3.94	13.04	28.1	30	-0.83
-5.96	13.05	28.1	30	-0.88
-7.97	13.05	28.08	30	-0.9

11-3-6 S.A. DEG	11-3-6 F.Z. LB	11-3-6 F.Y. LB	11-3-6 F.X. LB	11-3-6 M.X. FT-LB	11-3-6 M.Y. FT-LB	11-3-6 M.Z. FT-LB
I.A. =	0					
1	-429	-75	-10	2	4	10
0.04	-431	-10	-10	0.9	0	4.9
-0.94	-430	57	-10	1	0	6
-1.95	-430	117	-10	1	1	6
-3.94	-432	225	-10	4	1	6
-5.96	-432	303	-9	3	2	6
-7.97	-430	354	-9	9	2	6
I.A. =	10.02					
1.03	-456	1	-10	-23.1	4.3	16.2
0.04	-437	66	-10	-24.1	3.7	9.6
-0.94	-412	126	-10	-26.6	2.9	3.1
-1.95	-393	176	-10	-27.9	2.6	4.4
-3.94	-373	250	-7	-28.8	4.4	4.4
-5.96	-356	293	-10	-31.4	4.4	5.5
-7.97	-349	315	-7	-31.4	3.4	5.5
I.A. =	20.07					
1.03	-487	84	-14	-38.5	4	22.7
0.04	-442	138	-10	-38.7	1.9	14.3
-0.94	-402	186	-10	-49.2	2.0	6.7
-1.95	-371	221	-10	-48.0	1.9	3.4
-3.94	-333	268	-10	-48.1	1.1	3.2
-5.96	-309	289	-10	-48.0	2.2	3.2
-7.97	-304	303	-10	-47.4	1.2	3.0
I.A. =	28.1					
1.01	-512	164	-18	-73.5	3.2	28.4
0.03	-452	200	-12	-73.7	2.7	17.4
-0.94	-402	235	-7	-69.5	0.5	9
-1.95	-364	259	-10	-68.1	0.5	9
-3.94	-329	290	-7	-68.1	1.1	9
-5.96	-308	298	-4	-68.6	1.9	9
-7.97	-300	304	-6	-68.1	1.7	9

11-3-6 S.A. DEG	11-3-6 P.L. IN	11-3-6 I.A. DEG	11-3-6 U. MPH	11-3-6 N.F.Y. FY/FZ		
I.A. =	0					
1	12.52	0	30	0.17		
0.04	12.52	0	30	0.02		
-0.94	12.52	0	30	-0.13		
-1.95	12.5	0	30	-0.27		
-3.94	12.46	0	30	-0.52		
-5.95	12.42	0	30	-0.7		
-7.97	12.38	0	30	-0.82		
I.A. =	10.02					
1.03	12.53	10.02	30	-0		
0.04	12.56	10.02	30	-0.15		
-0.94	12.59	10.02	30	-0.31		
-1.95	12.6	10.02	30	-0.45		
-3.94	12.61	10.02	30	-0.67		
-5.95	12.61	10.02	30	-0.82		
-7.97	12.61	10.02	30	-0.9		
I.A. =	20.07					
1.03	12.61	20.07	30	-0.17		
0.04	12.67	20.07	30	-0.31		
-0.94	12.73	20.07	30	-0.46		
-1.95	12.77	20.07	30	-0.6		
-3.94	12.8	20.07	30	-0.8		
-5.95	12.83	20.08	30	-0.94		
-7.97	12.84	20.08	30	-1		
I.A. =	28.1					
1.01	12.74	28.1	30	-0.32		
0.03	12.81	28.1	30	-0.44		
-0.94	12.88	28.1	30	-0.58		
-1.95	12.93	28.1	30	-0.71		
-3.94	13	28.1	30	-0.88		
-5.95	13	28.1	30	-0.97		
-7.97	13.02	28.1	30	-1.01		

12-3-6 S.A. DEG	12-3-6 F.Z. LB	12-3-6 F.Y. LB	12-3-6 F.X. LB	12-3-6 M.X. FT-LB	12-3-6 M.Y. FT-LB	12-3-6 M.Z. FT-LB
I.A. =	0					
1	-214	-46	4	1.5	0.3	6.2
0.04	-219	4	4	2.1	1.4	4.4
-0.94	-218	56	4	2.2	0.8	1.4
-1.95	-218	99	4	1.4	1.4	0.5
-3.94	-216	148	4	2.0	3.3	2.4
-5.96	-217	179	4	2.0	3.3	4.4
-7.96	-220	193	4	2.0	1.3	6.4
I.A. =	10.02					
1.03	-238	-27	4	-1.0	0.3	0.4
0.04	-222	25	4	-1.2	1.3	3.8
-0.94	-205	70	4	-1.2	0.3	3.8
-1.93	-195	101	4	-1.3	0.7	3.2
-3.93	-182	130	4	-1.3	3.3	2.4
-5.96	-180	140	4	-1.3	1.1	3.5
-7.96	-177	148	4	-1.4	0.7	6.4
I.A. =	20.07					
1.03	-260	13	7	-2.6	1.1	10.1
0.04	-232	53	4	-2.3	0.8	6.9
-0.94	-203	85	4	-2.4	1.1	3.8
-1.95	-183	105	4	-2.5	3.3	2.4
-3.93	-170	125	4	-2.5	1.1	4.5
-5.96	-164	127	4	-2.5	0.8	3.8
-7.96	-164	129	4	-2.6	0.6	3.8
I.A. =	28.1					
1.01	-284	54	9	-4.2	0.8	14.2
0.04	-238	86	6	-4.0	0.9	8.1
-0.94	-203	108	4	-3.8	1.3	5.5
-1.95	-182	119	4	-3.8	0.7	4.6
-3.93	-164	130	2	-3.7	3.3	3.4
-5.96	-160	136	4	-3.7	0.6	3.2
-7.96	-159	139	3	-3.8	0.6	6.1

12-3-6 S.A. DEG	12-3-6 P.L. IN	12-3-6 I.A. DEG	12-3-6 U. MPH	12-3-6 N.F.Y. FY/FZ
I.A. =	0.			
1.	12.91	0.	30.	0.22
0.04	12.92	0.	30.	-0.02
-0.94	12.92	0.	30.	-0.26
-1.95	12.91	0.	30.	-0.45
-3.94	12.9	0.	30.	-0.68
-5.95	12.88	0.	30.	-0.82
-7.95	12.88	0.	30.	-0.88
I.A. =	10.02			
1.03	12.87	10.02	30.	0.11
0.04	12.91	10.02	30.	-0.11
-0.94	12.94	10.02	30.	-0.34
-1.93	12.95	10.02	30.	-0.52
-3.93	12.97	10.02	30.	-0.71
-5.95	12.97	10.02	30.	-0.78
-7.95	12.97	10.02	30.	-0.83
I.A. =	20.07			
1.03	12.89	20.07	30.	-0.05
0.04	12.94	20.07	30.	-0.23
-0.94	13.	20.07	30.	-0.42
-1.95	13.02	20.07	30.	-0.57
-3.93	13.05	20.07	30.	-0.73
-5.95	13.07	20.07	30.	-0.78
-7.95	13.07	20.07	30.	-0.79
I.A. =	28.1			
1.01	12.94	28.1	30.	-0.19
0.04	13.03	28.1	30.	-0.36
-0.94	13.1	28.1	30.	-0.53
-1.95	13.13	28.1	30.	-0.66
-3.93	13.15	28.08	30.	-0.79
-5.95	13.17	28.1	30.	-0.85
-7.95	13.17	28.1	30.	-0.87

13-3-6 S.A. DEG	13-3-6 F.Z. LB	13-3-6 F.Y. LB	13-3-6 F.X. LB	13-3-6 M.X. FT-LB	13-3-6 M.Y. FT-LB	13-3-6 M.Z. FT-LB
I.A. =	0					
1	-258	-53	6	3.7	2	6.2
0.04	-261	-1	6	3.3	2	4.4
-0.94	-259	55	6	2.	2	8.6
-1.93	-261	99	6	-1.1	2	0.6
-3.93	-261	152	6	-2.7	3	6.6
-5.96	-260	187	6	-4.	2	2
-7.96	-261	227	6	-3.6	9	4.
I.A. =	10.02					
1.03	-285	-28	6	-11.7	2	9.8
0.04	-266	23	6	-12.6	0	6.1
-0.94	-253	72	6	-14.2	1	2.8
-1.93	-240	108	6	-14.	1	1.6
-3.93	-223	146	6	-14.2	0	3.4
-5.96	-214	168	6	-15.4	0	4.2
-7.96	-210	173	6	-16.2	0	4.4
I.A. =	20.87					
1.03	-306	38	6	-27.9	2	12.7
0.04	-271	70	6	-29.1	3	7.4
-0.94	-240	104	6	-27.6	0	4.8
-1.93	-225	127	6	-28.3	1	2.8
-3.94	-206	144	6	-28.3	0	4.7
-5.95	-201	153	6	-28.1	0	3.3
-7.96	-190	157	6	-28.8	0	3.8
I.A. =	28.1					
1.11	-334	75	-11	-43.3	1	17.1
0.14	-287	108	0	-43.2	0	10.2
-0.94	-252	137	5	-40.3	0	6.1
-1.93	-220	147	4	-42.4	0	4.7
-3.93	-200	166	4	-43.7	1	3.3
-5.95	-190	170	3	-43.4	1	6.6
-7.96	-186	170	3	40.	1	6.

13-3-6 S.A. DEG	13-3-6 P.L. IN	13-3-6 I.A. DEG	13-3-6 V. MPH	13-3-6 N.F.Y. FY/FZ
I.A. =	0			
1	12.86	0	30	0.21
0.04	12.86	0	30	0
-0.94	12.86	0	30	-0.21
-1.95	12.85	0	30	-0.38
-3.93	12.83	0	30	-0.58
-5.95	12.81	0	30	-0.72
-7.95	12.79	0	30	-0.87
I.A. =	10.02			
1.03	12.79	10.02	30	0.1
0.04	12.83	10.02	30	-0.09
-0.94	12.86	10.02	30	-0.28
-1.93	12.87	10.02	30	-0.45
-3.93	12.89	10.02	30	-0.66
-5.96	12.9	10.02	30	-0.78
-7.95	12.9	10.02	30	-0.83
I.A. =	20.07			
1.03	12.83	20.07	30	-0.1
0.04	12.89	20.07	30	-0.26
-0.94	12.94	20.07	30	-0.44
-1.95	12.97	20.07	30	-0.56
-3.94	13.	20.07	30	-0.7
-5.95	13.	20.08	30	-0.76
-7.95	13.	20.08	30	-0.79
I.A. =	28.1			
1.01	12.86	28.1	30	-0.22
0.04	12.96	28.1	30	-0.37
-0.94	13.04	28.1	30	-0.54
-1.95	13.07	28.1	30	-0.67
-3.93	13.12	28.1	30	-0.83
-5.95	13.13	28.1	30	-0.9
-7.95	13.13	28.1	30	-0.91

14-3-6 S.A. DEG	14-3-6 F.Z. LB	14-3-6 F.Y. LB	14-3-6 F.X. LB	14-3-6 M.X. FT-LB	14-3-6 M.Y. FT-LB	14-3-6 M.Z. FT-LB
I.A. =	0					
0.98	-270	-52	-3	1.9	0.2	7.0
0.04	-267	-6	-4	-0.9	0.5	4.5
-0.95	-268	45	-3	-1.6	0.8	2.2
-1.95	-266	84	-4	-3.3	1.4	1.2
-3.94	-268	136	-5	-5.4	2.4	0.7
-5.96	-269	169	-5	-4	1.9	2.6
-7.96	-268	191	-4	-4.9	2	3.6
I.A. =	10.82					
1.03	-290	-24	-5	-28.3	0.6	8.9
0.04	-274	22	-4	-19	0.9	6.7
-0.94	-265	63	-4	-28.5	0.2	3.2
-1.95	-248	92	-4	-21.1	1.5	2.2
-3.94	-235	126	-4	-28.0	1.1	2.2
-5.96	-230	150	-4	-21.3	0.5	2.9
-7.96	-229	158	-3	-21.3	-1.3	4.0
I.A. =	20.07					
1.01	-326	19	-7	-36.2	0.4	12.3
0.04	-301	53	-6	-36.7	0.0	9.3
-0.94	-278	83	-5	-36	-1.4	6.1
-1.95	-257	103	-5	-35.1	-1.0	3.7
-3.94	-238	126	-5	-34.4	-1.7	4.7
-5.96	-226	141	-5	-34.2	-0.8	3.0
-7.96	-220	152	-2	-33.5	-2.4	4.4
I.A. =	28.1					
1.03	-366	66	-9	-54.2	-0.1	14.9
0.04	-329	91	-8	-51.2	1.4	10.9
-0.94	-297	109	-7	-49.5	1	7.2
-1.93	-277	123	-7	-49.0	-1.2	5.2
-3.93	-260	139	-6	-47.9	-1.9	3.7
-5.96	-252	148	-6	-48.0	-0.9	4.7
-7.97	-246	146	-4	-47.5	-1.3	4.0



14-3-6 S.A. DEG	14-3-6 P.L. IN	14-3-6 I.A. DEG	14-3-6 U. MPH	14-3-6 N.F.Y. FY/FZ
I.A. =	0			
0.98	13.04	0	38	0.19
0.04	13.05	0	38	0.02
-0.95	13.04	0	38	-0.17
-1.95	13.04	0	38	-0.32
-3.94	13.03	0	38	-0.51
-5.96	13.02	0	38	-0.63
-7.96	13.01	0	38	-0.71
I.A. =	10.02			
1.03	13.03	10.02	38	0.08
0.04	13.06	10.02	38	-0.08
-0.94	13.09	10.02	38	-0.24
-1.95	13.11	10.02	38	-0.37
-3.94	13.12	10.02	38	-0.54
-5.96	13.13	10.02	38	-0.63
-7.96	13.13	10.02	38	-0.69
I.A. =	20.07			
1.01	13.13	20.07	38	-0.06
0.04	13.17	20.07	38	-0.18
-0.94	13.21	20.07	38	-0.3
-1.95	13.23	20.07	38	-0.4
-3.94	13.25	20.08	38	-0.53
-5.96	13.26	20.07	38	-0.62
-7.96	13.28	20.07	38	-0.69
I.A. =	28.1			
1.03	13.24	28.1	38	-0.18
0.04	13.3	28.1	38	-0.28
-0.94	13.35	28.1	38	-0.37
-1.93	13.38	28.1	38	-0.44
-3.93	13.42	28.08	38	-0.54
-5.96	13.41	28.1	38	-0.56
-7.97	13.43	28.08	38	-0.6

15-3-6 S.A. DEG	15-3-6 F.Z. LB	15-3-6 F.Y. LB	15-3-6 F.X. LB	15-3-6 M.X. FT-LB	15-3-6 M.Y. FT-LB	15-3-6 M.Z. FT-LB
I.A. =	0					
1	-326	-62	5	1.1	2	7.6
0.84	-323	-13	4.5	2.1	1.9	5.4
-0.95	-323	40	4.4	4.4	1.7	2.1
-1.95	-323	82	6.5	5.5	2.0	3.3
-3.94	-322	137	7.6	6.5	2.9	6.6
-5.96	-323	186	7.7	9.9	4.4	8.8
-7.96	-324	224	6	9.9	3.4	2
I.A. =	10.82					
1.01	-352	-31	6	-21.4	1.5	11.7
0.84	-335	21	6	-21.5	2.6	6.7
-0.95	-318	67	6	-21.3	1.6	3.3
-1.95	-305	102	6	-23.0	1.7	1.1
-3.94	-293	146	6	-21.3	2.4	1.1
-5.95	-282	177	6	-22.0	1.1	2.8
-7.96	-271	195	6	-24	2.1	2.8
I.A. =	20.87					
1.03	-402	10	8	-43	0.8	15.7
0.84	-376	49	7	-40.2	1.2	10.2
-0.74	-348	86	6	-39.4	1.3	6.9
-1.95	-318	113	4	-39.4	0.4	4.3
-3.93	-288	151	4	-40.2	0.9	2.1
-5.95	-266	178	4	-38	0.7	2.6
-7.96	-258	192	4	-39.6	0.3	2.8
I.A. =	28.1					
1.01	-459	73	-13	-60	2.5	19.5
0.84	-412	100	-11	-59.2	3.2	14
-0.94	-376	125	8	-58	1.1	9.5
-1.95	-348	147	6	-56.9	0.7	6.9
-3.93	-310	172	6	-54.9	1.4	6.9
-5.96	-288	191	6	-51.8	0.4	6.9
-7.96	-275	200	4	-52.0	0.7	8

15-3-6 S.A. DEG	15-3-6 P.L. IN	15-3-6 I.A. DEG	15-3-6 U. MPH	15-3-6 N.F.Y. FY/FZ
I.A. =	0			
1	13	0	30	0.19
0.04	13	0	30	0.04
-0.95	12.98	0	30	-0.12
-1.95	12.98	0	30	-0.25
-3.94	12.96	0	30	-0.43
-5.96	12.95	0	30	-0.58
-7.96	12.93	0	30	-0.69
I.A. =	10.02			
1.01	12.95	10.02	30	0.09
0.04	12.98	10.02	30	-0.06
-0.95	13.01	10.02	30	-0.21
-1.95	13.03	10.02	30	-0.33
-3.94	13.05	10.02	30	-0.5
-5.95	13.05	10.02	30	-0.63
-7.96	13.06	10.02	30	-0.72
I.A. =	20.07			
1.03	13.01	20.07	30	-0.03
0.04	13.06	20.07	30	-0.13
-0.94	13.11	20.07	30	-0.25
-1.95	13.15	20.08	30	-0.36
-3.93	13.2	20.07	30	-0.52
-5.95	13.22	20.08	30	-0.67
-7.96	13.24	20.08	30	-0.74
I.A. =	28.1			
1.01	13.09	28.1	30	-0.16
0.04	13.17	28.1	30	-0.24
-0.94	13.23	28.1	30	-0.33
-1.95	13.28	28.1	30	-0.42
-3.93	13.34	28.1	30	-0.55
-5.96	13.38	28.08	30	-0.66
-7.96	13.4	28.1	30	-0.72

16-3-6 S.A. DEG	16-3-6 F.Z. LB	16-3-6 F.Y. LB	16-3-6 F.X. LB	16-3-6 M.X. FT-LB	16-3-6 M.Y. FT-LB	16-3-6 M.Z. FT-LB
I.A. =	0					
1	0	-43		-1.5	1	6.4
0.83	-217	-6		-4	2	4.2
-0.97	-219	34		3	1	1.9
-1.95	-220	66		3	3	2.9
-3.96	-219	115		3	3	0.7
-5.98	-218	146		4	4	2.7
-7.97	-219	162		6	6	4.6
I.A. =	10.02					
1	0	-14		-7	2	7.9
0.83	-223	26		0	1	5.5
-0.97	-222	64		0	1	3.2
-1.95	-224	94		1	2	1.2
-3.96	-222	135		1	2	2.1
-5.98	-224	155		3	6	4.1
-7.97	-225	165		4	5	
I.A. =	20.07					
1	0	23		-8	0	9.1
0.83	-228	68		-7	1	7.7
-0.97	-229	93		-6	1	5.5
-1.95	-230	117		-6	1	3.7
-3.96	-231	157		-8	2	3.4
-5.98	-235	168		-3	1	5.1
-7.97	-232	184		4	0	5.4
I.A. =	28.1					
1	0	58		-7	-0	10.5
0.83	-236	84		-7	0	8.6
-0.97	-241	113		-6	0	6.6
-1.95	-238	135		-7	0	6.6
-3.96	-241	167		-9	0	5.5
-5.98	-239	178		-12	0	4.5
-7.97	-239	186		-11	0	4.2
				-13	0	2.9

16-3-6 S.A. DEG	16-3-6 P.L. IN	16-3-6 I.A. DEG	16-3-6 U. MPH	16-3-6 N.F.Y. FY/FZ
I.A. =	0			
1.03	11.29	0	38	0.2
0.03	11.29	0	38	0.03
-0.97	11.29	0	38	-0.15
-1.96	11.27	0	38	-0.3
-3.96	11.25	0	38	-0.32
-5.98	11.23	0	38	-0.67
-7.97	11.22	0	38	-0.74
I.A. =	10.02			
1.03	11.29	10.02	38	0.06
0.03	11.3	10.02	38	-0.12
-0.97	11.31	10.02	38	-0.29
-1.95	11.3	10.02	38	-0.42
-3.95	11.3	10.02	38	-0.6
-5.95	11.29	10.02	38	-0.7
-7.97	11.28	10.02	38	-0.74
I.A. =	20.07			
1.01	11.37	20.07	38	-0.1
0.03	11.38	20.07	38	-0.26
-0.97	11.39	20.07	38	-0.4
-1.95	11.39	20.07	38	-0.51
-3.95	11.39	20.07	38	-0.67
-5.93	11.38	20.08	38	-0.72
-7.97	11.39	20.07	38	-0.79
I.A. =	28.1			
1.01	11.48	28.1	38	-0.21
0.03	11.49	28.08	38	-0.25
-0.97	11.5	28.08	38	-0.48
-1.95	11.51	28.08	38	-0.56
-3.96	11.52	28.08	38	-0.7
-5.93	11.52	28.08	38	-0.75
-7.97	11.52	28.1	38	-0.78

17-3-6 S.A. DEG	17-3-6 F.Z. LB	17-3-6 F.Y. LB	17-3-6 F.X. LB	17-3-6 M.Y. FT-LB	17-3-6 M.Y. FT-LB	17-3-6 M.Z. FT-LB
I.A. =	0					
1	-265	-45	-6	1	2	7
0.03	-263	-6	-7	0	3	4
-0.97	-263	32	-8	-1	4	0
-1.95	-262	61	-8	-5	3	-1
-3.96	-265	108	-9	-7	4	0
-5.93	-261	148	-8	-8	4	0
-7.97	-265	188	-9	-12	4	0
I.A. =	10.82					
1.03	-269	-18	-7	-11	1	0
0.03	-268	21	-6	-13	1	0
-0.97	-269	68	-7	-14	3	6
-1.95	-268	92	-7	-16	3	2
-3.94	-267	144	-7	-19	3	1
-5.93	-267	188	-8	-21	3	1
-7.97	-269	283	-8	-23	3	1
I.A. =	20.87					
1.01	-277	13	-9	-19	1	9
0.03	-276	47	-8	-22	2	7
-0.95	-274	83	-7	-24	2	5
-1.95	-277	115	-6	-24	1	5
-3.94	-277	162	-6	-27	2	6
-5.95	-278	200	-8	-28	2	6
-7.97	-277	221	-8	-30	2	6
I.A. =	28.1					
1.01	-288	40	-9	-27	1	12
0.03	-285	78	-8	-28	1	9
-0.97	-286	102	-7	-30	1	7
-1.95	-286	133	-6	-30	1	4
-3.96	-286	178	-7	-33	3	4
-5.93	-288	212	-7	-35	3	4
-7.97	-287	232	-8	-38	3	4

17-3-6 S.A. DEG	17-3-6 P.L. IN	17-3-6 I.A. DEG	17-3-6 U. MPH	17-3-6 N.F.Y. FY/FZ
I.A. =	0.			
1.	11.21	0.	30.	0.17
0.03	11.22	0.	30.	0.02
-0.97	11.22	0.	30.	-0.12
-1.95	11.21	0.	30.	-0.23
-3.96	11.19	0.	30.	-0.41
-5.98	11.16	0.	30.	-0.56
-7.97	11.12	0.	30.	-0.71
I.A. =	10.02			
1.03	11.21	10.02	30.	0.07
0.03	11.22	10.02	30.	-0.08
-0.97	11.22	10.02	30.	-0.22
-1.95	11.22	10.02	30.	-0.33
-3.94	11.21	10.02	30.	-0.54
-5.98	11.19	10.02	30.	-0.67
-7.97	11.18	10.02	30.	-0.76
I.A. =	20.07			
1.01	11.28	20.07	30.	-0.05
0.03	11.3	20.07	30.	-0.17
-0.95	11.31	20.07	30.	-0.3
-1.95	11.31	20.07	30.	-0.42
-3.94	11.31	20.07	30.	-0.58
-5.96	11.3	20.07	30.	-0.72
-7.97	11.29	20.07	30.	-0.8
I.A. =	28.1			
1.01	11.38	28.1	30.	-0.14
0.03	11.4	28.1	30.	-0.25
-0.97	11.41	28.08	30.	-0.36
-1.95	11.43	28.1	30.	-0.47
-3.96	11.44	28.1	30.	-0.62
-5.98	11.44	28.1	30.	-0.74
-7.97	11.44	28.1	30.	-0.81

18-3-6 S.A. DEC	18-3-6 F.Z. LB	18-3-6 F.Y. LB	18-3-6 F.X. LB	18-3-6 M.X. FT-LB	18-3-6 M.Y. FT-LB	18-3-6 M.Z. FT-LB
I.A. =	0					
1.03	-142	-31	-3	-1.1	0.6	5.2
0.03	-142	-2	3	-1.1	0.6	5.2
-0.97	-142	27	3	-2.2	0.9	5.9
-1.95	-144	52	3	-2.2	0.9	5.9
-3.96	-146	84	3	-2.2	0.9	5.9
-5.98	-143	107	3	-2.1	0.8	5.7
-7.97	-142	122	2	-4.9	0.5	5.6
I.A. =	10.02					
1.03	-148	-15	-1	-1.1	-1.1	5.7
0.03	-151	13	3	-1.1	-1.1	5.7
-0.95	-152	42	2	-1.4	-1.2	5.8
-1.95	-152	63	2	-1.5	-1.1	5.7
-3.96	-150	93	4	-1.3	-0.9	5.8
-5.98	-147	109	3	-1.3	-0.9	5.8
-7.97	-147	117	2	-1.3	-0.4	5.6
I.A. =	20.07					
1.03	-150	1	3	-2.1	-1.0	5.6
0.03	-153	27	3	-2.1	-1.0	5.6
-0.97	-157	52	2	-2.4	-1.7	5.6
-1.95	-154	69	2	-2.3	-1.5	5.6
-3.96	-152	89	3	-2.3	-1.5	5.6
-5.98	-154	101	3	-2.2	-1.4	5.6
-7.97	-151	106	3	-2.3	-1.1	5.6
I.A. =	28.1					
1.01	-159	13	3	-2.0	-2.1	5.6
0.03	-163	40	2	-2.0	-2.1	5.6
-0.95	-160	58	3	-1.9	-2.0	5.6
-1.95	-159	73	4	-1.9	-2.0	5.6
-3.96	-159	86	2	-1.9	-2.0	5.6
-5.98	-161	92	2	-1.9	-2.0	5.6
-7.97	-158	100	2	-1.9	-2.0	5.6



18-3-6 S.A. DEG	18-3-6 P.L. IN	18-3-6 I.A. DEG	18-3-6 U. MPH	18-3-6 N.F.Y. FY/FZ
I.A. =	0			
1	13.67	0	30	0.22
0.03	13.68	0	30	0.01
-0.97	13.67	0	30	-0.19
-1.95	13.66	0	30	-0.36
-3.96	13.65	0	30	-0.58
-5.98	13.63	0	30	-0.73
-7.97	13.62	0	30	-0.86
I.A. =	10.02			
1.03	13.68	10.02	30	0.1
0.03	13.68	10.02	30	-0.09
-0.95	13.68	10.02	30	-0.27
-1.95	13.69	10.02	30	-0.41
-3.96	13.69	10.02	30	-0.62
-5.98	13.68	10.02	30	-0.74
-7.97	13.68	10.02	30	-0.8
I.A. =	20.07			
1.03	13.78	20.07	30	-0.01
0.03	13.79	20.07	30	-0.18
-0.97	13.79	20.07	30	-0.33
-1.95	13.8	20.07	30	-0.45
-3.95	13.8	20.07	30	-0.58
-5.98	13.8	20.07	30	-0.66
-7.97	13.8	20.07	30	-0.7
I.A. =	28.1			
1.01	13.91	28.1	30	-0.08
0.03	13.92	28.1	30	-0.24
-0.95	13.94	28.1	30	-0.36
-1.95	13.95	28.1	30	-0.46
-3.96	13.95	28.1	30	-0.54
-5.98	13.95	28.08	30	-0.57
-7.97	13.95	28.1	30	-0.63

19-3-6 S.A. DEC	19-3-6 F.Z. LB	19-3-6 F.Y. LB	19-3-6 F.X. LB	19-3-6 M.X. FT-LB	19-3-6 M.Y. FT-LB	19-3-6 M.Z. FT-LB
I.A. =	0					
1	-171	-35	4	1	1	5
0.83	-171	29.4	4	0.01	0.11	2.45
-0.97	-171	53	4	2.00	0.99	1.17
-1.95	-172	92	4	2.73	0.99	1.79
-3.95	-172	122	4	3.00	1	2.66
-5.98	-173	146	4	3.00	1	4.06
-7.97	-174		4	3.00	1	4.06
I.A. =	10.82					
1.83	-180	-28	4	-13	1	6
0.83	-182	12	4	-14	1	3.5
-0.97	-178	45	4	-13	1	3.5
-1.95	-178	78	4	-14	1	3.5
-3.96	-177	106	4	-16	1	3.5
-5.98	-177	134	4	-16	1	3.5
-7.97	-175	158	4	-17	1	3.5
I.A. =	20.87					
1.83	-185	-3	4	-23	0	7
0.83	-186	23	4	-22	1	6
-0.97	-186	51	4	-26	1	5.5
-1.95	-189	76	4	-26	1	5.5
-3.94	-188	114	4	-27	1	5.5
-5.98	-186	139	4	-27	1	5.5
-7.97	-185	158	4	-28	1	5.5
I.A. =	28.1					
1.81	-195	17	4	-31	-1	8
0.83	-193	42	4	-33	-2	6.8
-0.97	-193	66	4	-33	-2	6.8
-1.95	-198	87	4	-33	-2	6.8
-3.96	-197	117	4	-33	-2	6.8
-5.98	-195	135	4	-33	-2	6.8
-7.97	-196	143	4	-33	-2	6.8

19-3-6 S.A. DEG	19-3-6 P.L. IN	19-3-6 I.A. DEG	19-3-6 I. MPH	19-3-6 N.F.Y. FY/FZ
I.A. =	0.			
1.	13.62	0.	38.	0.2
0.83	13.63	0.	38.	0.02
-0.97	13.63	0.	38.	-0.17
-1.95	13.62	0.	38.	-0.31
-3.96	13.6	0.	38.	-0.34
-5.98	13.57	0.	38.	-0.7
-7.97	13.55	0.	38.	-0.84
I.A. =	10.02			
1.83	13.62	10.02	38.	0.11
0.83	13.63	10.02	38.	-0.07
-0.97	13.63	10.02	38.	-0.23
-1.95	13.64	10.02	38.	-0.39
-3.96	13.63	10.02	38.	-0.6
-5.98	13.62	10.02	38.	-0.76
-7.97	13.61	10.02	38.	-0.86
I.A. =	20.07			
1.83	13.71	20.07	38.	0.02
0.83	13.74	20.07	38.	-0.13
-0.97	13.74	20.07	38.	-0.27
-1.95	13.74	20.07	38.	-0.4
-3.96	13.74	20.07	38.	-0.61
-5.98	13.74	20.07	38.	-0.73
-7.97	13.74	20.07	38.	-0.84
I.A. =	28.1			
1.01	13.84	28.1	38.	-0.09
0.83	13.86	28.1	38.	-0.22
-0.97	13.87	28.00	38.	-0.34
-1.95	13.88	28.1	38.	-0.44
-3.96	13.89	28.00	38.	-0.6
-5.98	13.89	28.00	38.	-0.69
-7.97	13.89	28.00	38.	-0.73



Appendix C  
Simulation Runs

This appendix contains output plots for all runs performed with the directional control test procedure in the simulation study. These data, together with information on a large number of other variables which are printed out by the computer, are the support for the summarized results given in the technical report volume. Table C-1 identifies each of the plots by motorcycle and test condition and references them to the simulation program run schedule.

All associated print-outs are on file at Calspan. Since this information is voluminous, it is not practical to include it in this report. Table C-2 lists the pertinent variables which are included in the print-out.

Table C-1: Data Plots

Figure Number	Simulation Run No.	Vehicle	Conditions (Nominal)		Remarks
			Speed (mph)	Lat. Acc. <sub>g</sub>	
C-1	23	Honda 360	40	.2	Normal configuration  Medium rider Intermediate rider Low stiffness rider
C-2	05		40	.3	
C-3	11		40	.4	
C-4	05		40	.5	
C-5	23		20	.2	
C-6	19		20	.4	
C-7	19		60	.4	
C-8	22		5	.04	
C-9	27		20	.04	
C-10	27		40	.04	
C-11	34		40	.4	
C-12	31		40	.4	
C-13	33		40	.4	
C-14	17	Honda 125	40	.3	Normal configuration
C-15	13		40	.4	
C-16	17		40	.5	
C-17	20		60	.4	
C-18	18	Kawasaki 250	40	.3	Normal configuration
C-19	14		40	.4	
C-20	18		40	.5	
C-21	29	Yamaha 650	40	.3	Normal configuration  Low $C_{y}$ rear tire
C-22	28		40	.4	
C-23	29		40	.5	
C-24	25		40	.3	
C-25	24		40	.4	
C-26	25		40	.5	
C-27	26		60	.4	
C-28	15	Norton 850	40	.3	Normal configuration
C-29	08		40	.4	
C-30	15		40	.5	

Table C-1: Data Plots  
(Cont'd.)

Figure Number	Simulation Run No.	Vehicle	Conditions (Nominal)		Remarks
			Speed (mph)	Lat. Acc. g	
C-31	16	H-D 1200	40	.3	Normal configuration
C-32	12		40	.4	
C-33	16		40	.5	
C-34	C7		40	.3	Different tires; different rider representation
C-35	C5		40	.4	
C-36	C8		40	.5	
C-37	32		40	.4	

Table C-2  
Code Numbers, Names, Symbology, And Units For Program Variables

<u>Code</u>	<u>Variable Name</u>	<u>Printing &amp; Plotting Title</u>	<u>Units</u>
1	Elapsed Time	TIME	SEC
2	Path Distance	DISTANCE	FT
3	Steer Angle	STR ANG	DEG
4	Rider Lean Angle	RDR ROLL	DEG
5	Rider Steering Torque	STR TORQ	LB IN
6	Rider Lean Torque	RDR TORQ	LB IN
7	X Location of Vehicle Origin in Space Fixed Coordinate System	X	FT
8	Y Location of Vehicle Origin in Space Fixed Coordinate System	Y	FT
9	Forward Velocity	VELOCITY	MPH
10	Vehicle Roll Angle	ROLL	DEG
11	Vehicle Sideslip Angle ( )	VEH SLIP	DEG
12	Command Roll Angle	COM ROLL	DEG
13	Vehicle Lateral Acceleration	LAT ACC	G'S
14	Vehicle Path Radius	PATH RAD	FT
15	Z Location of Vehicle Origin in Space Fixed Coordinate System	Z	IN
16	Vehicle Pitch Angle	PITCH	DEG
17	Vehicle Yaw Angle	YAW	DEG
18	Vehicle Roll Velocity	ROLL VEL	DEG/SEC
19	Vehicle Pitch Velocity	PTCH VEL	DEG/SEC
20	Vehicle Yaw Velocity	YAW VEL	DEG/SEC
21	Total Yaw Moment	YAW MOM	LB FT
22	Front Normal Force/Total Normal Force	FNF/TNF	
23	Total Side Force/Total Normal Force	TSF/TNF	
24	Total Side Force Components/Total Normal Force	TSFP/TNF	
25	Total Tractive Force Components/Total Normal Force	TTFP/TNF	
26	Front Tire Slip Angle	FT SLIP	DEG
27	Front Tire Inclination Angle	FT INCL	DEG
28	Front Normal Force	FT NF	LB
29	Front Side Force	FT SF	LB
30	Front Side Force Component	FT SFP	LB
31	Front Tractive Force Component	FT TFP	LB
32	Rear Tire Slip Angle	RR SLIP	DEG
33	Rear Tire Inclination Angle	RR INCL	DEG
34	Rear Normal Force	RRNF	LB
35	Rear Side Force Component	RRSF	LB
36	Rear Side Force Component	RRSFP	LB
37	Rear Tractive Force Component	RRTFP	LB



STEADY STATE CORNERING - HONDA CB-360C MOTORCYCLE - 40 MPH

2 JUN '75

BRIDGESTONE 3.00-18 FRONT TIRE, BRIDGESTONE 3.50-18 REAR TIRE

# STEER AND ROLL ANGLES

- ROLL
- STR ANG
- △ COM ROLL

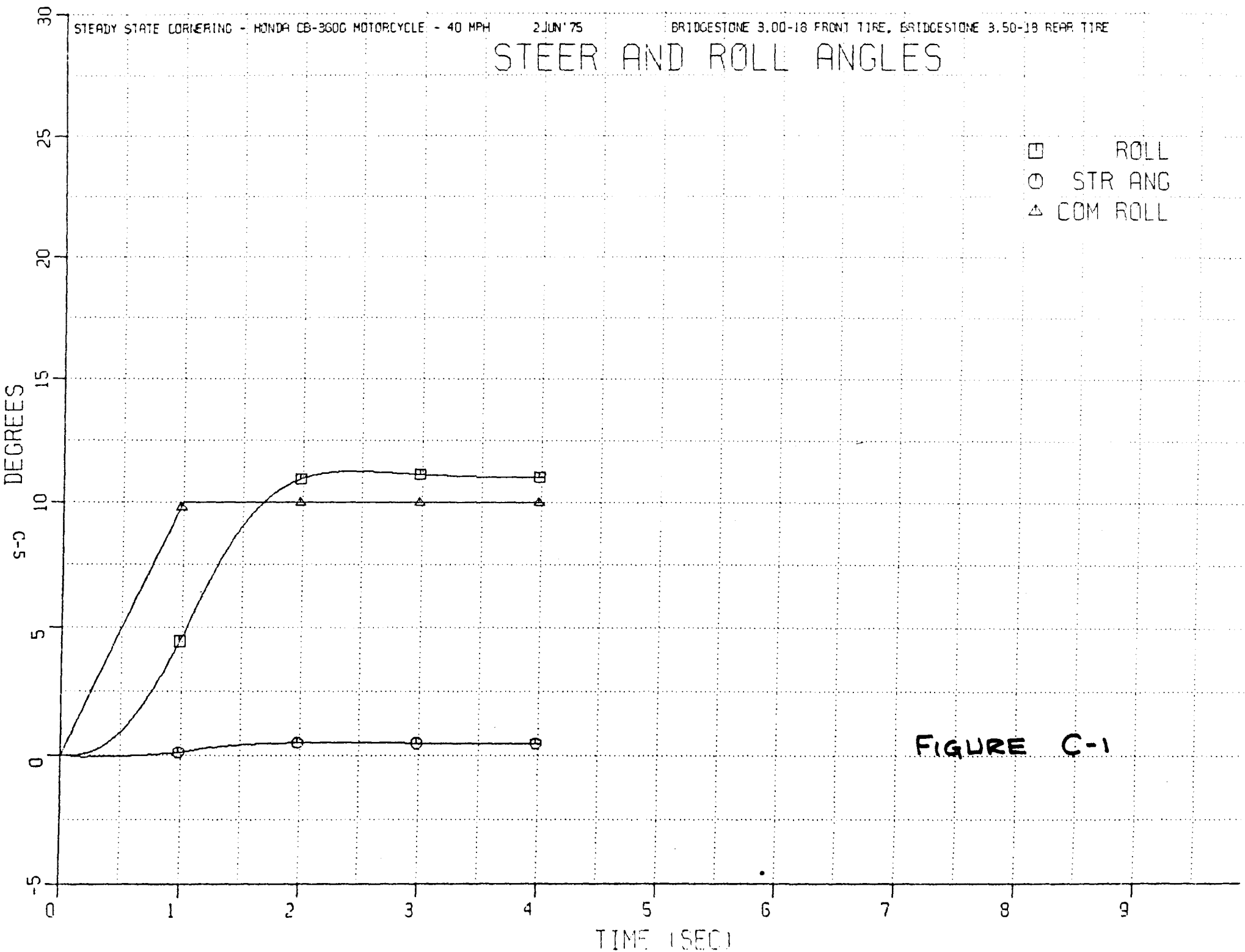


FIGURE C-1

STEADY STATE CORNERING - HONDA CB-360C MOTORCYCLE - 40 MPH

2 JUN '75

BRIDGESTONE 3.00-18 FRONT TIRE, BRIDGESTONE 3.50-18 REAR TIRE

# STEERING TORQUE

□ STR TORQ

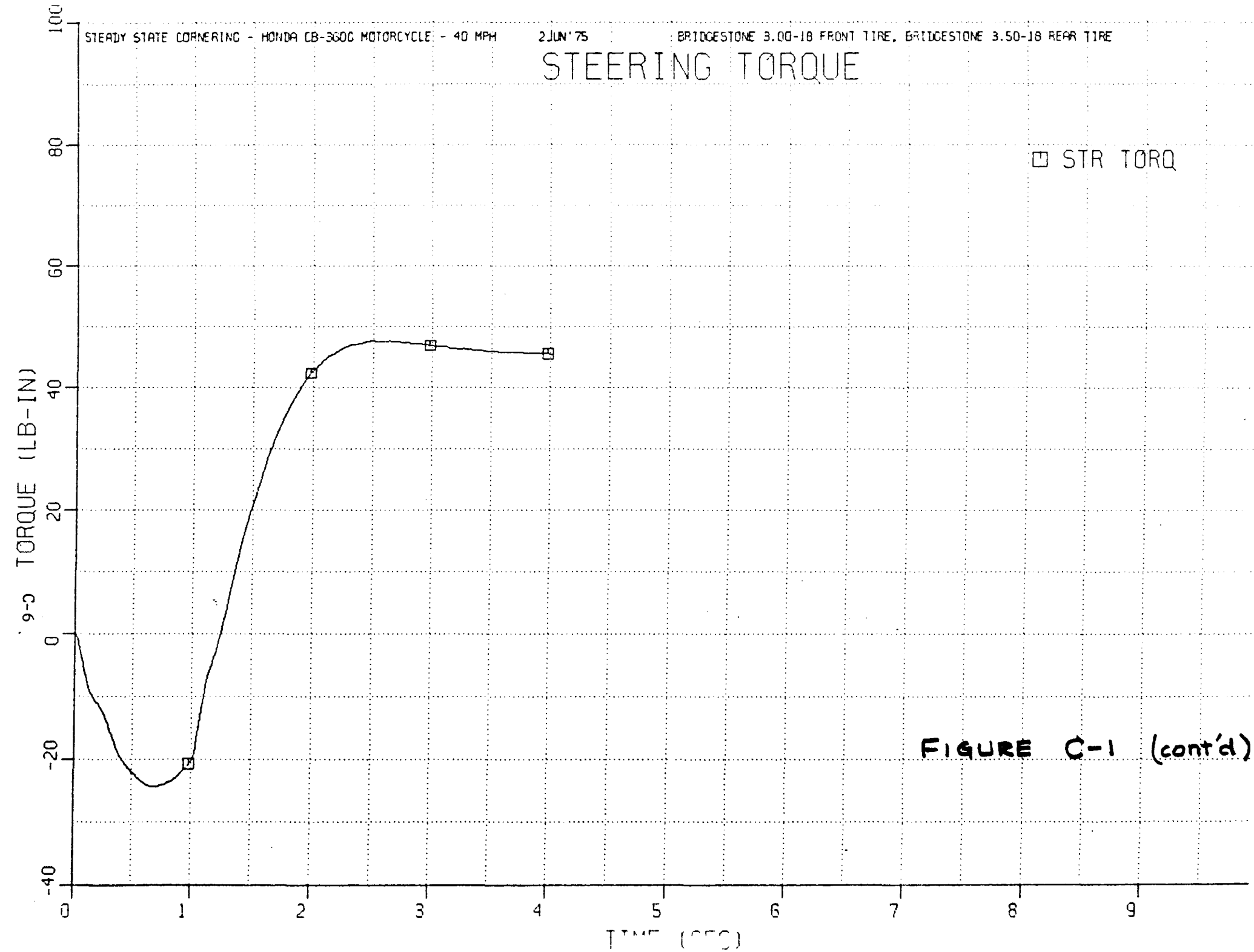


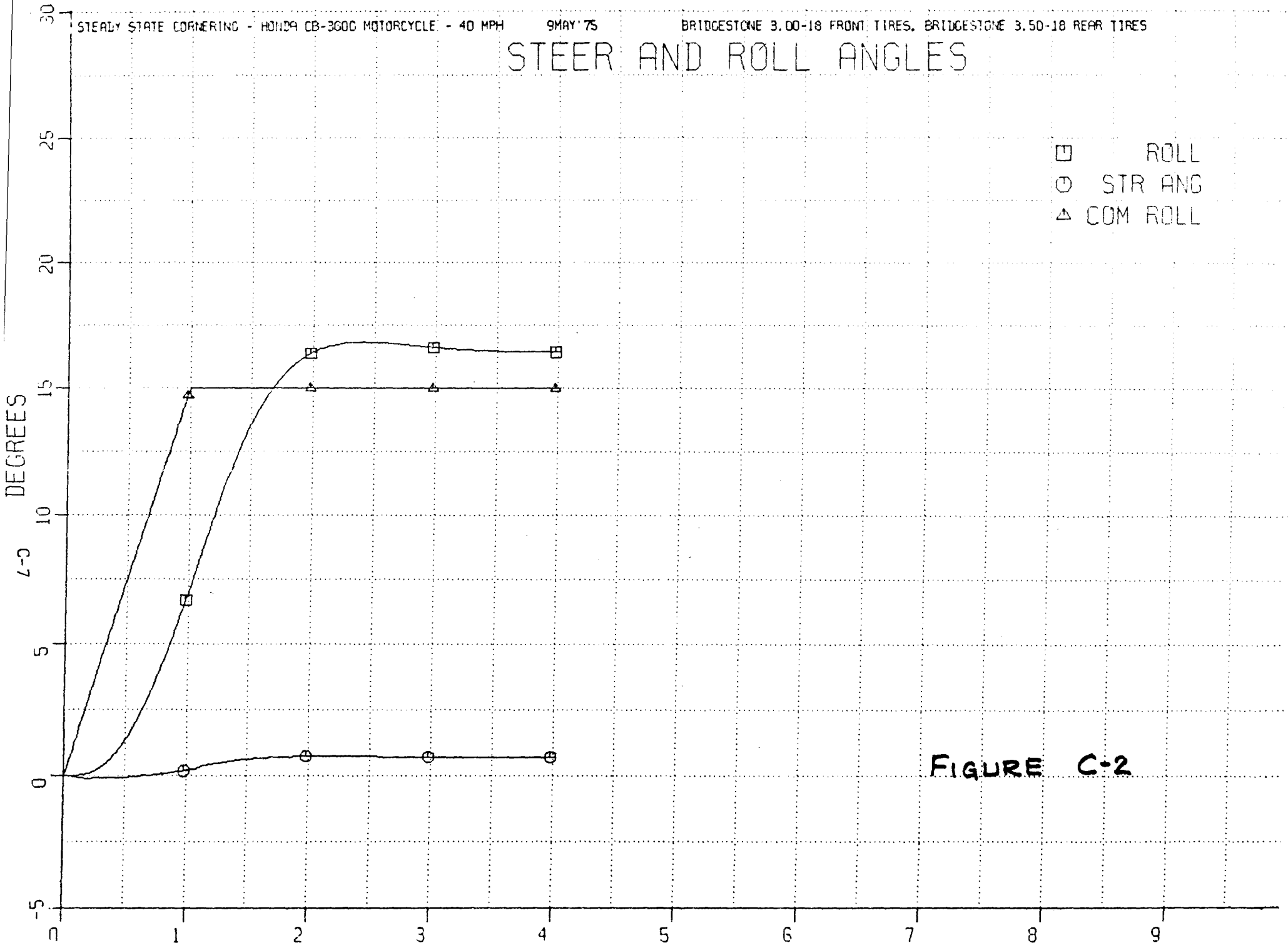
FIGURE C-1 (cont'd)

STEADY STATE CORNERING - HONDA CB-360C MOTORCYCLE - 40 MPH

9MAY '75

BRIDGESTONE 3.00-18 FRONT TIRES, BRIDGESTONE 3.50-18 REAR TIRES

# STEER AND ROLL ANGLES



□ ROLL  
○ STR ANG  
△ COM ROLL

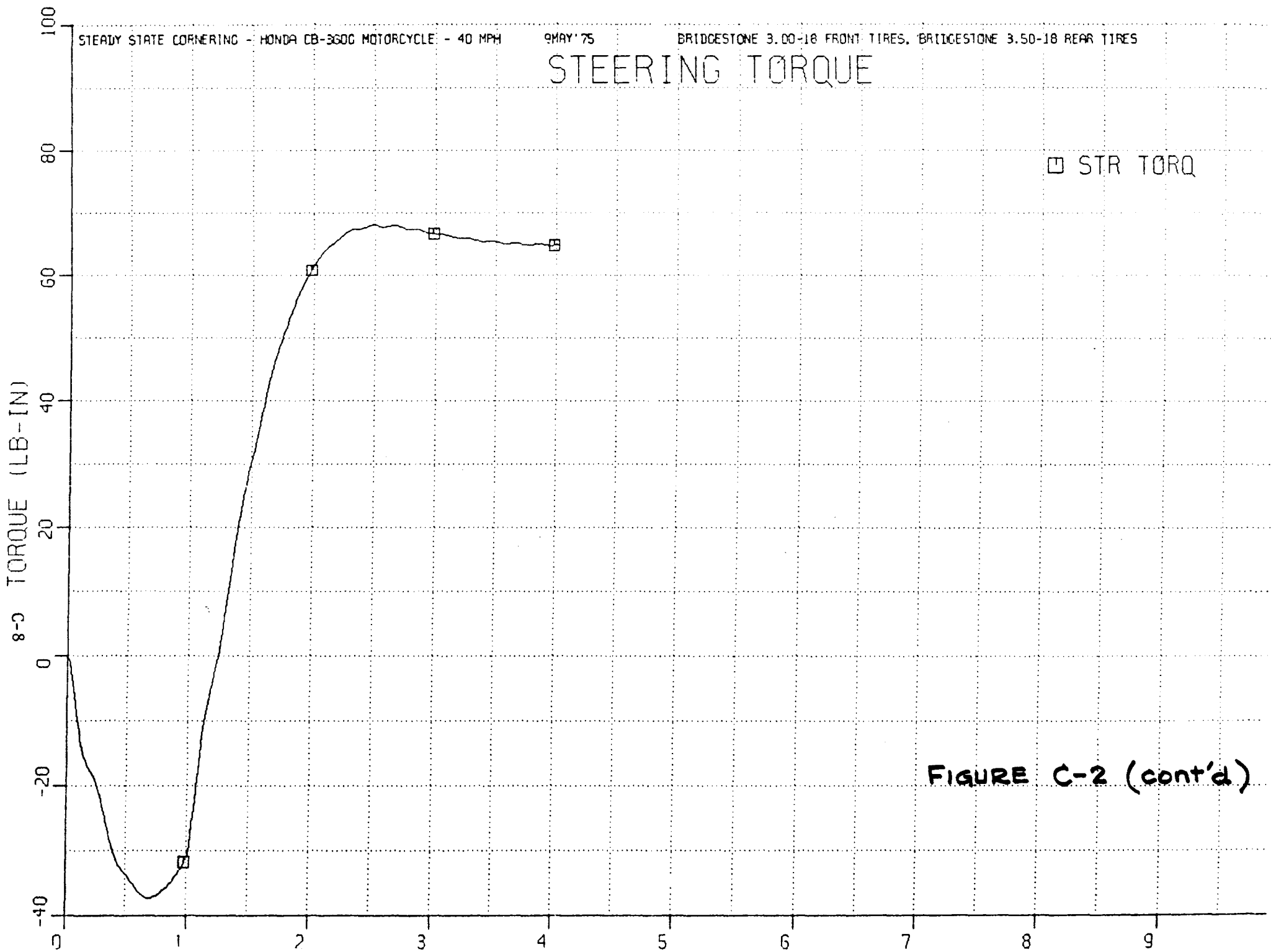
FIGURE C-2

STEADY STATE CORNERING - HONDA CB-360G MOTORCYCLE - 40 MPH

9MAY '75

BRIDGESTONE 3.00-18 FRONT TIRES, BRIDGESTONE 3.50-18 REAR TIRES

# STEERING TORQUE



□ STR TORQ

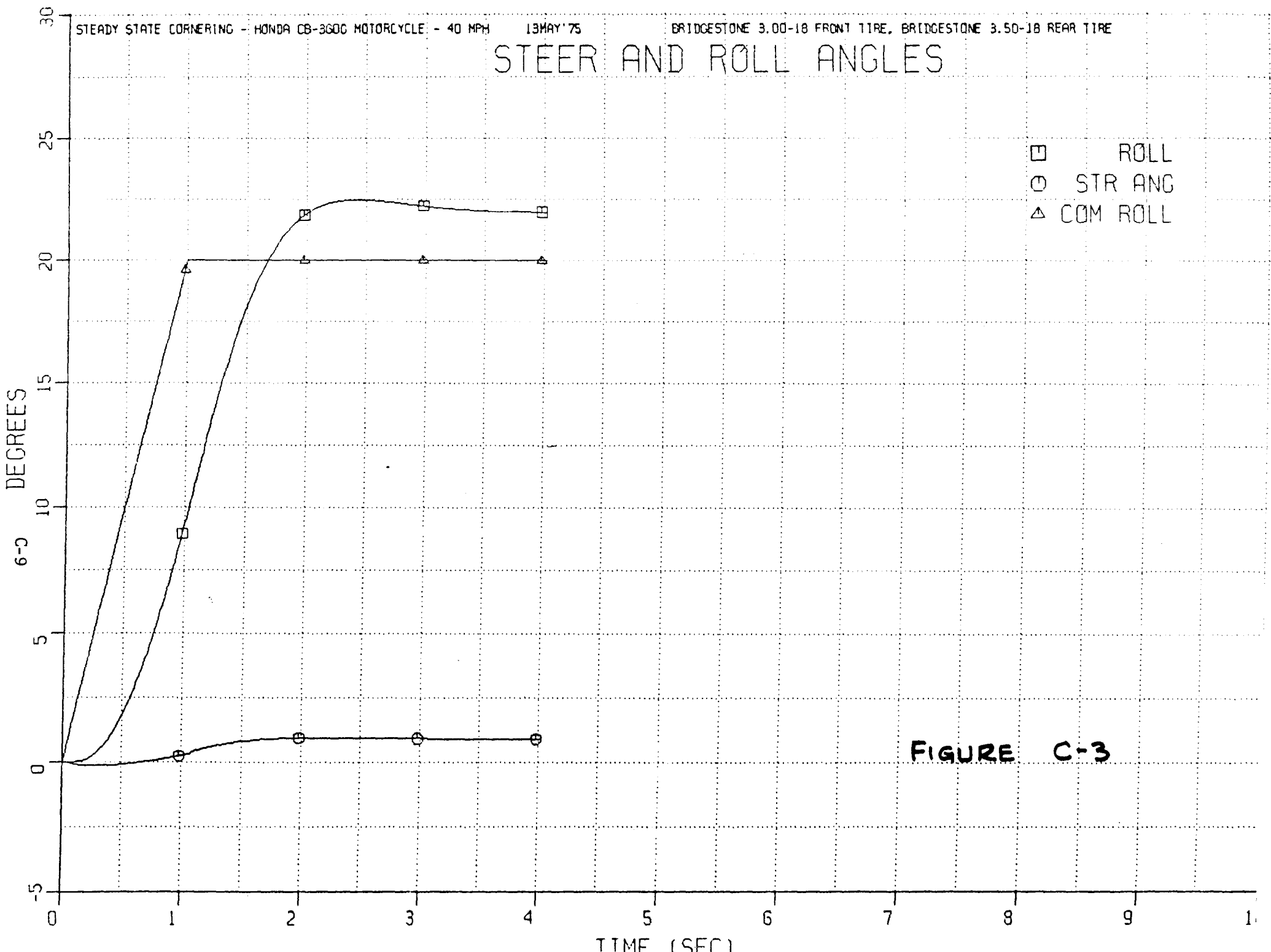
FIGURE C-2 (cont'd)

STEADY STATE CORNERING - HONDA CB-360C MOTORCYCLE - 40 MPH

13MAY '75

BRIDGESTONE 3.00-18 FRONT TIRE, BRIDGESTONE 3.50-18 REAR TIRE

# STEER AND ROLL ANGLES



□ ROLL  
○ STR ANG  
△ COM ROLL

FIGURE C-3

STEADY STATE CORNERING - HONDA CB-360G MOTORCYCLE - 40 MPH

13MAY '75

BRIDGESTONE 3.00-18 FRONT TIRE, BRIDGESTONE 3.50-18 REAR TIRE

# STEERING TORQUE

□ STR TORQ

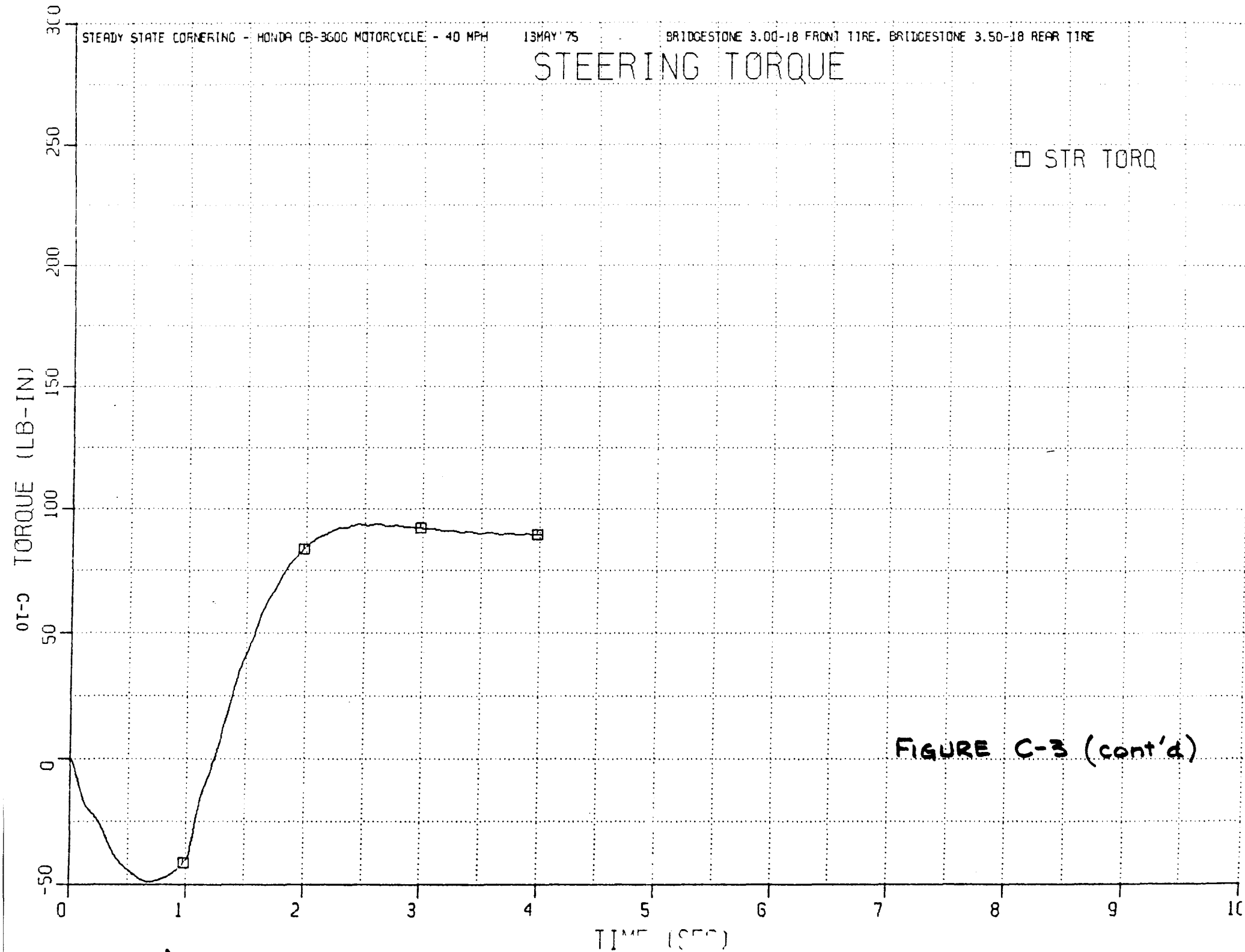


FIGURE C-3 (cont'd)

STEADY STATE CORNERING - HONDA CB-360C MOTORCYCLE - 40 MPH

9MAY'75

BRIDGESTONE 3.00-18 FRONT TIRES, BRIDGESTONE 3.50-18 REAR TIRES

# STEER AND ROLL ANGLES

- ROLL
- STR ANG
- △ COM ROLL

DEGREES

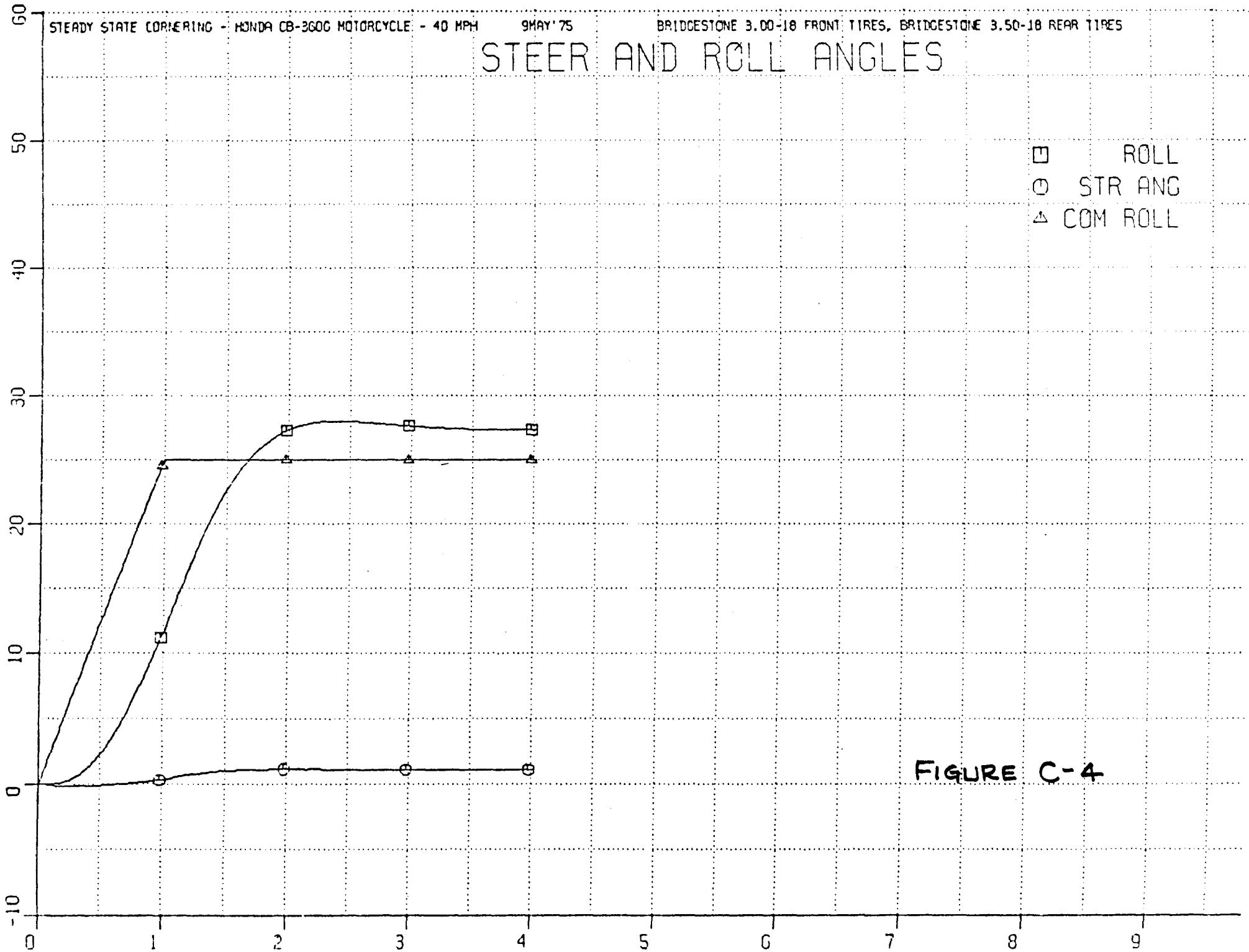


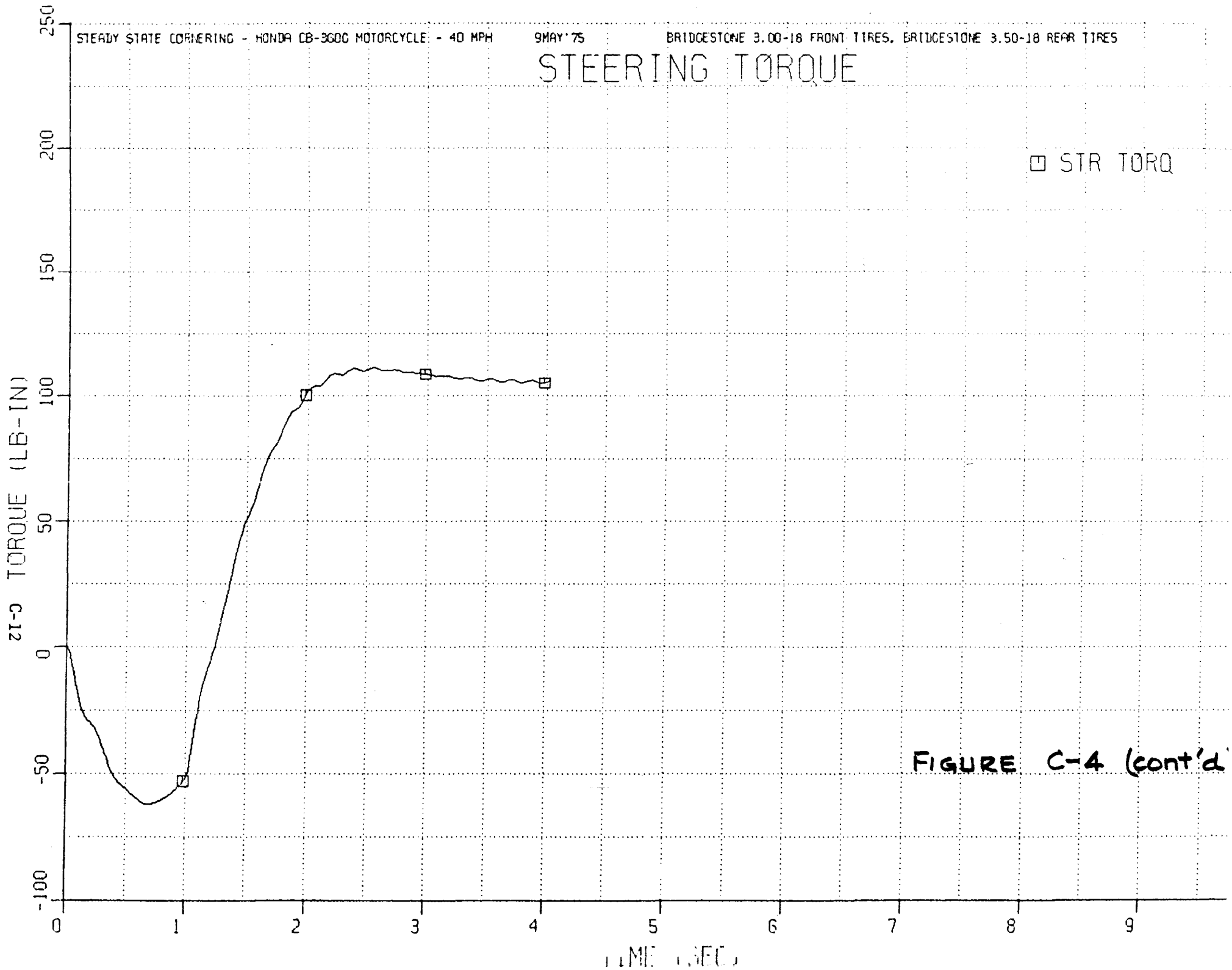
FIGURE C-4

STEADY STATE CORNERING - HONDA CB-360C MOTORCYCLE - 40 MPH

9MAY'75

BRIDGESTONE 3.00-18 FRONT TIRES, BRIDGESTONE 3.50-18 REAR TIRES

# STEERING TORQUE



□ STR TORQ

FIGURE C-4 (cont'd)

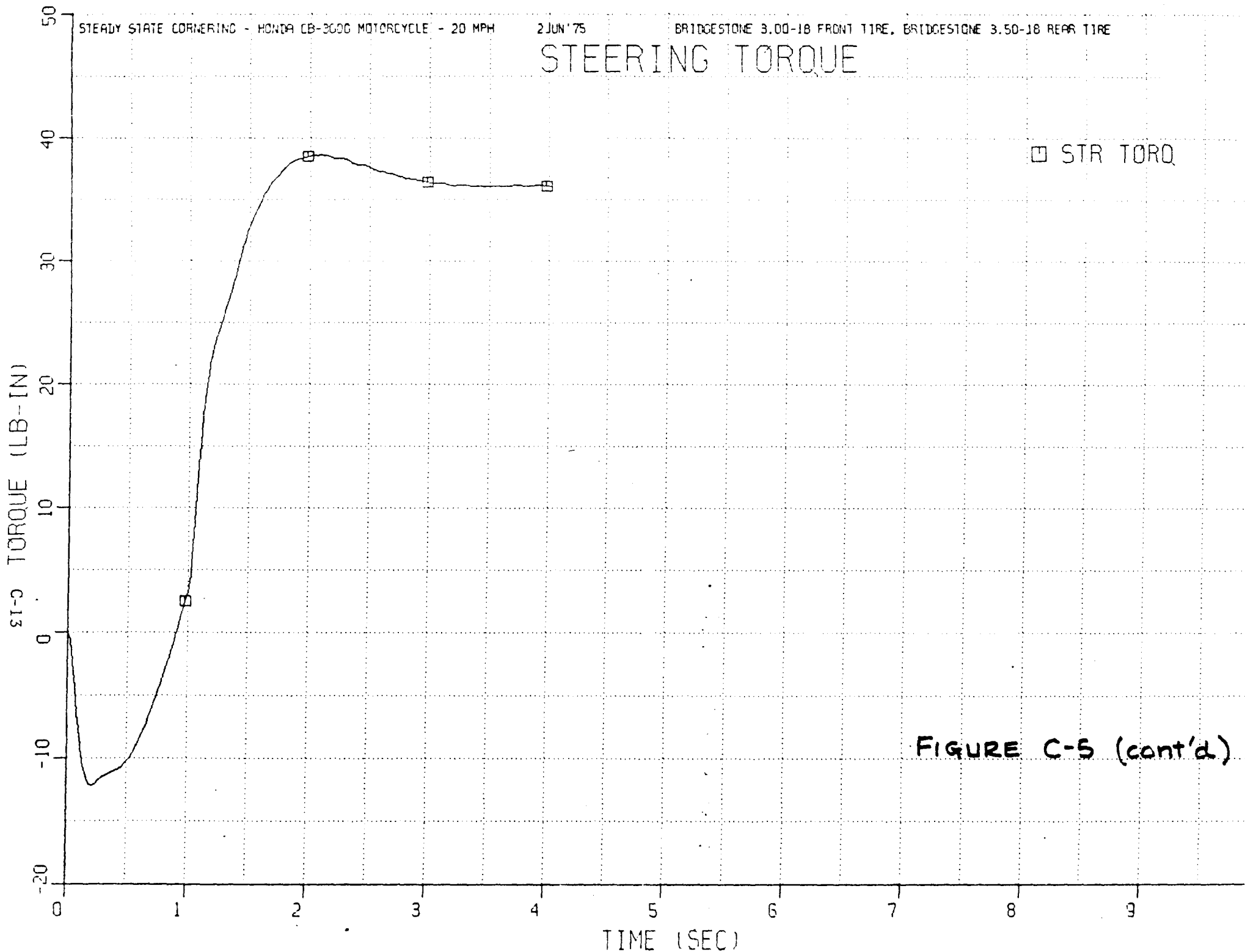


STEADY STATE CORNERING - HONDA CB-300C MOTORCYCLE - 20 MPH

2 JUN '75

BRIDGESTONE 3.00-18 FRONT TIRE, BRIDGESTONE 3.50-18 REAR TIRE

# STEERING TORQUE



□ STR TORQ

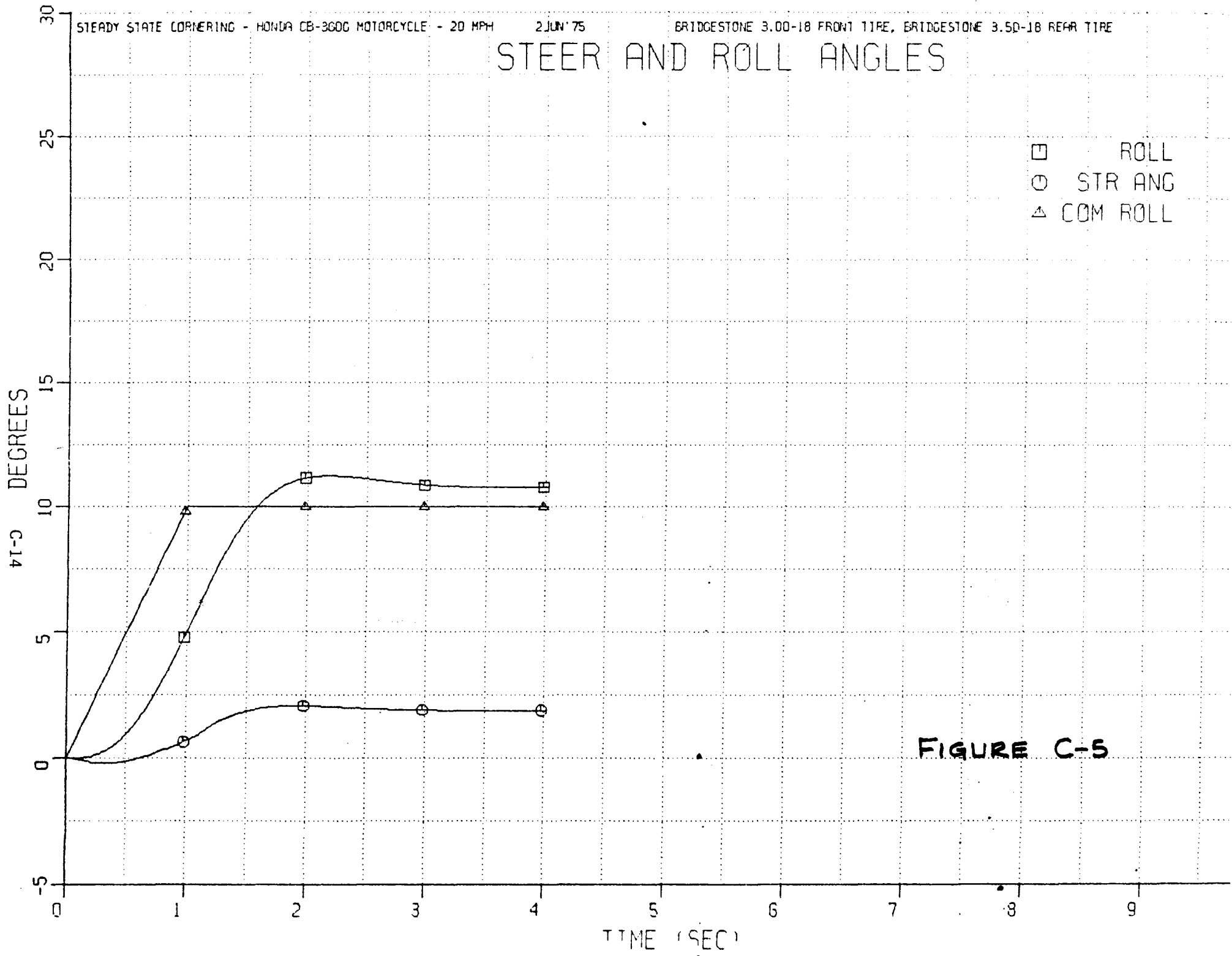
FIGURE C-5 (cont'd)

STEADY STATE CORNERING - HONDA CB-360C MOTORCYCLE - 20 MPH

2 JUN '75

BRIDGESTONE 3.00-18 FRONT TIRE, BRIDGESTONE 3.50-18 REAR TIRE

# STEER AND ROLL ANGLES



□ ROLL  
○ STR ANG  
△ COM ROLL

FIGURE C-5

STEADY STATE CORNERING - HONDA CB-360G MOTORCYCLE - 20 MPH

14MAY'75

BRIDGESTONE 3.00-18 FRONT TIRE, BRIDGESTONE 3.50-18 REAR TIRE

# STEERING TORQUE

ST-0 TORQUE (LB-IN)

□ STR TORQ

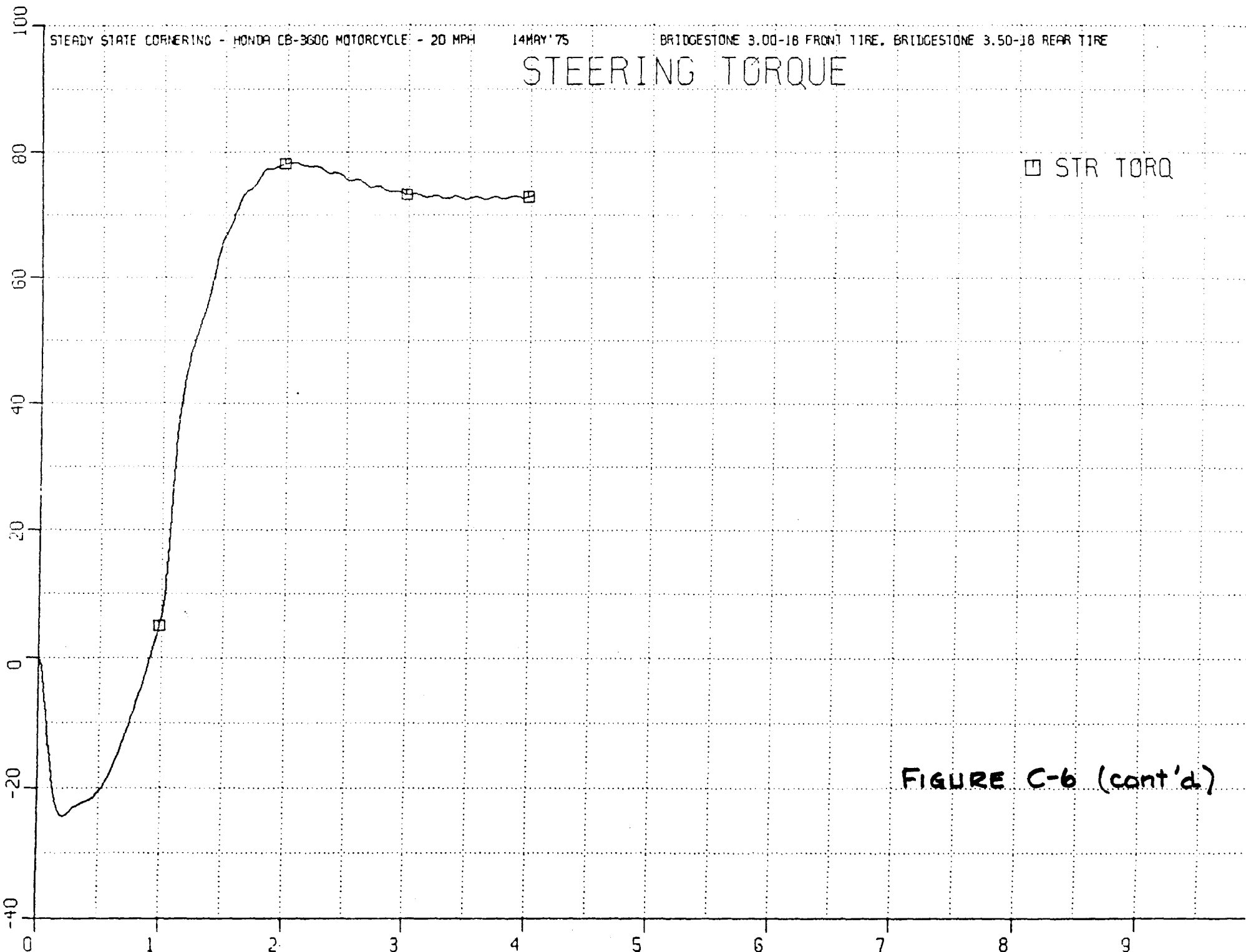


FIGURE C-6 (cont'd)

STEADY STATE CORNERING - HONDA CB-360C MOTORCYCLE - 20 MPH 14MAY'75

BRIDGESTONE 3.00-18 FRONT TIRE, BRIDGESTONE 3.50-18 REAR TIRE

# STEER AND ROLL ANGLES

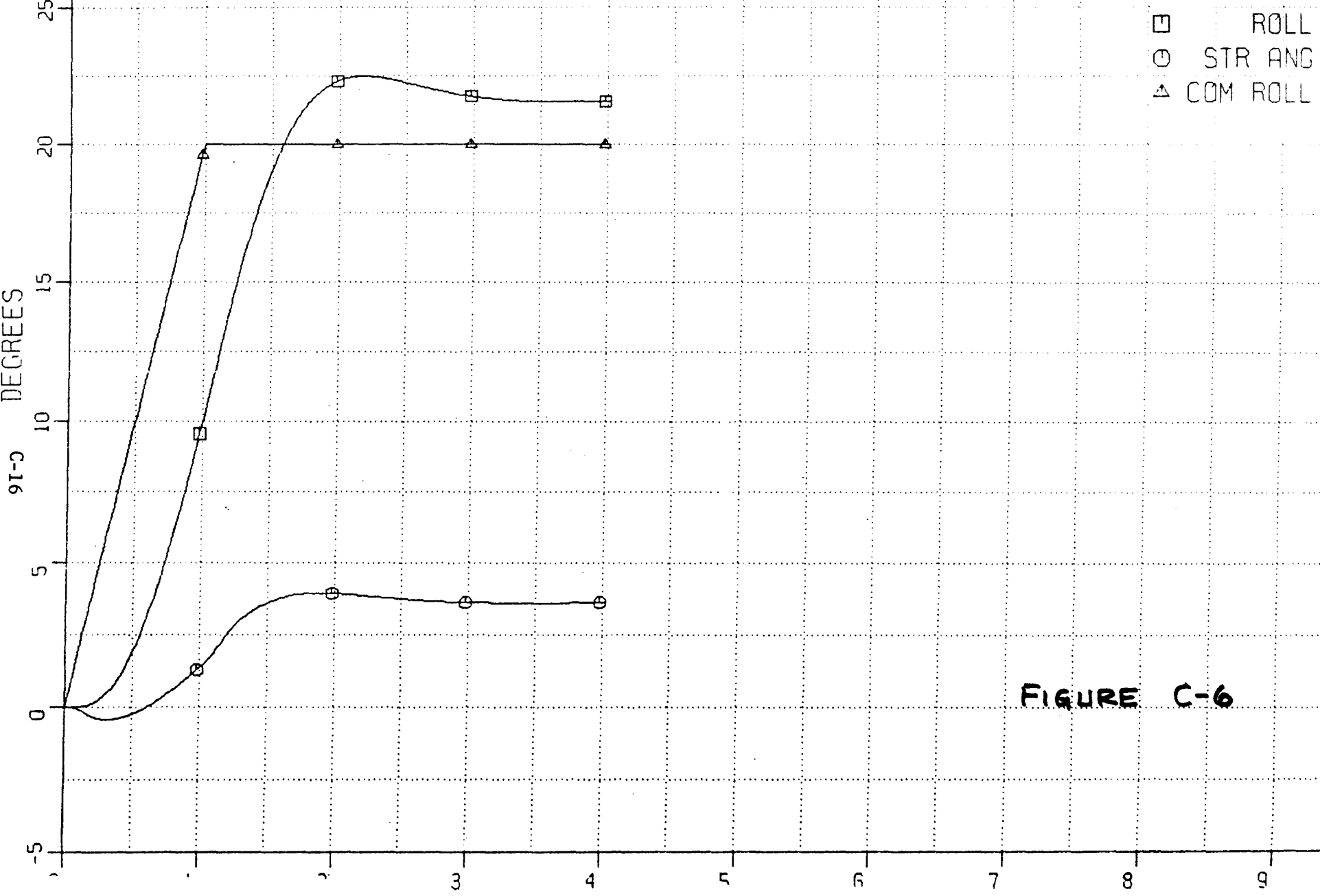


FIGURE C-6

STEADY STATE CORNERING - HONDA CB-360C MOTORCYCLE - 60 MPH

14MAY'75

BRIDGESTONE 3.00-18 FRONT TIRE, BRIDGESTONE 3.50-18 REAR TIRE

# STEER AND ROLL ANGLES

- ROLL
- STR ANG
- △ COM ROLL

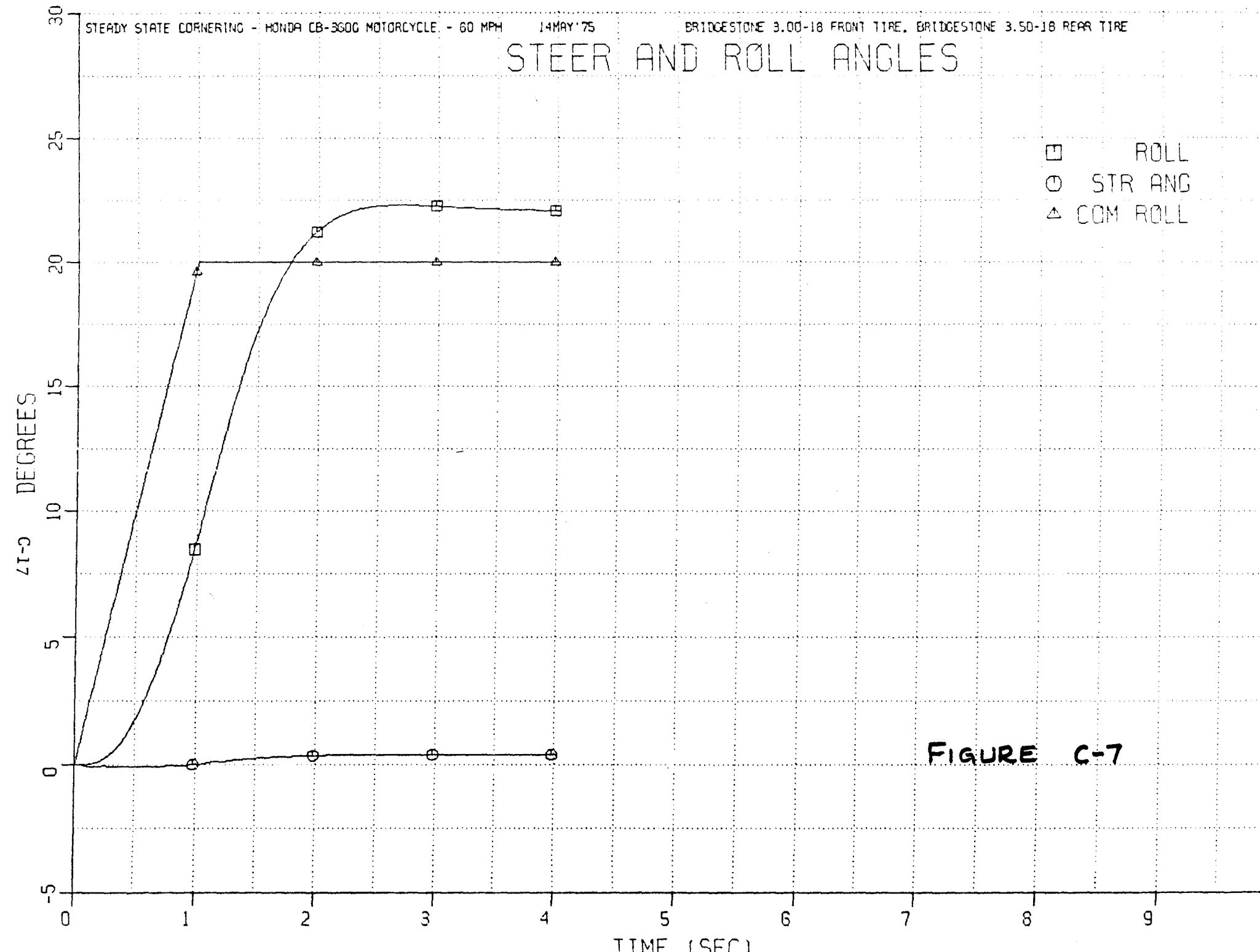


FIGURE C-7

STEADY STATE CORNERING - HONDA CB-360C MOTORCYCLE - 60 MPH

14 MAY '75

BRIDGESTONE 3.00-18 FRONT TIRE, BRIDGESTONE 3.50-18 REAR TIRE

# STEERING TORQUE

□ STR TORQ

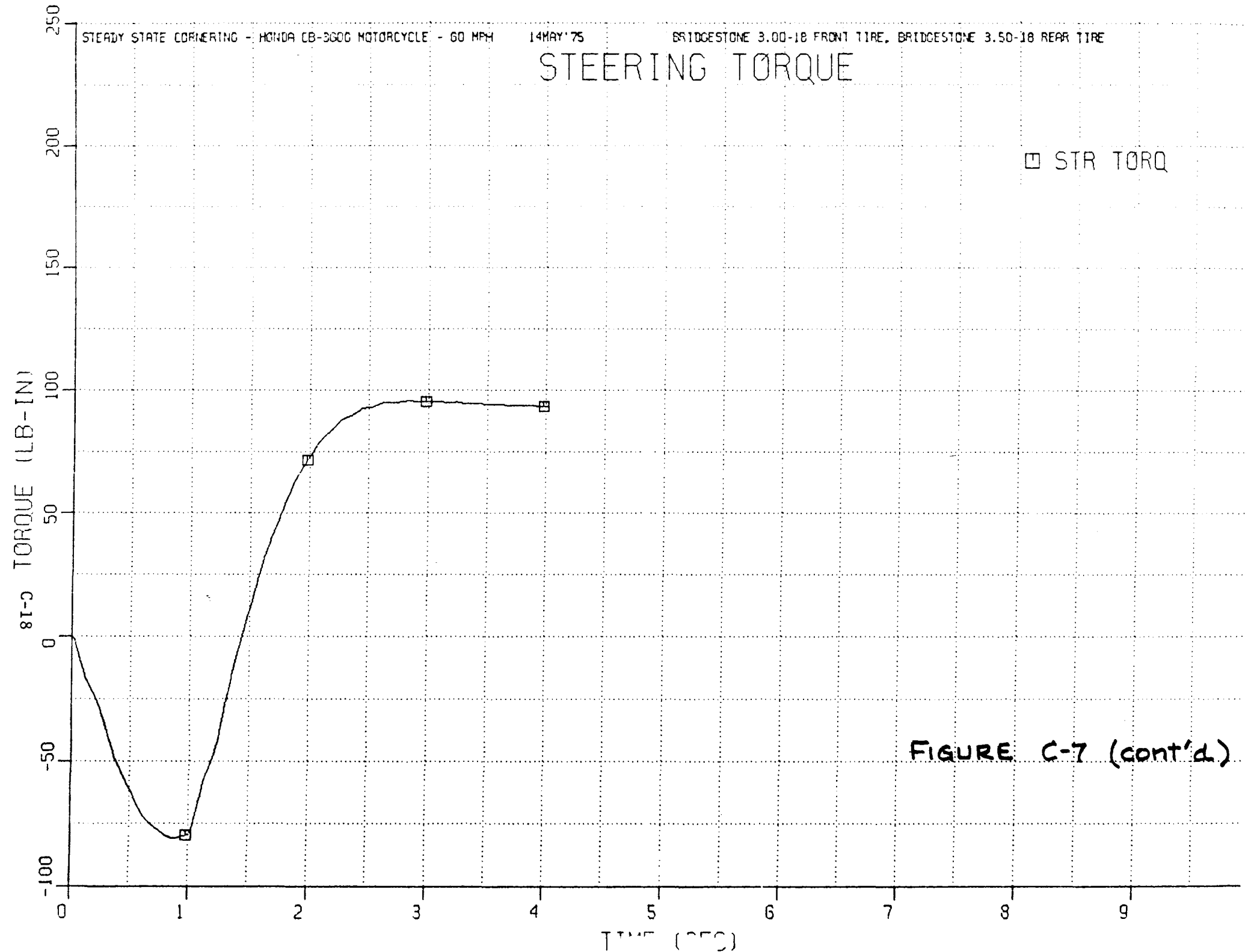


FIGURE C-7 (cont'd)

STEADY STATE CORNERING - HONDA CB-360C MOTORCYCLE - 5 MPH

14MAY'75

BRIDGESTONE 3.00-18 FRONT TIRE, BRIDGESTONE 3.50-18 REAR TIRE

# STEER AND ROLL ANGLES

- ROLL
- STR ANG
- △ COM ROLL

DEGREES

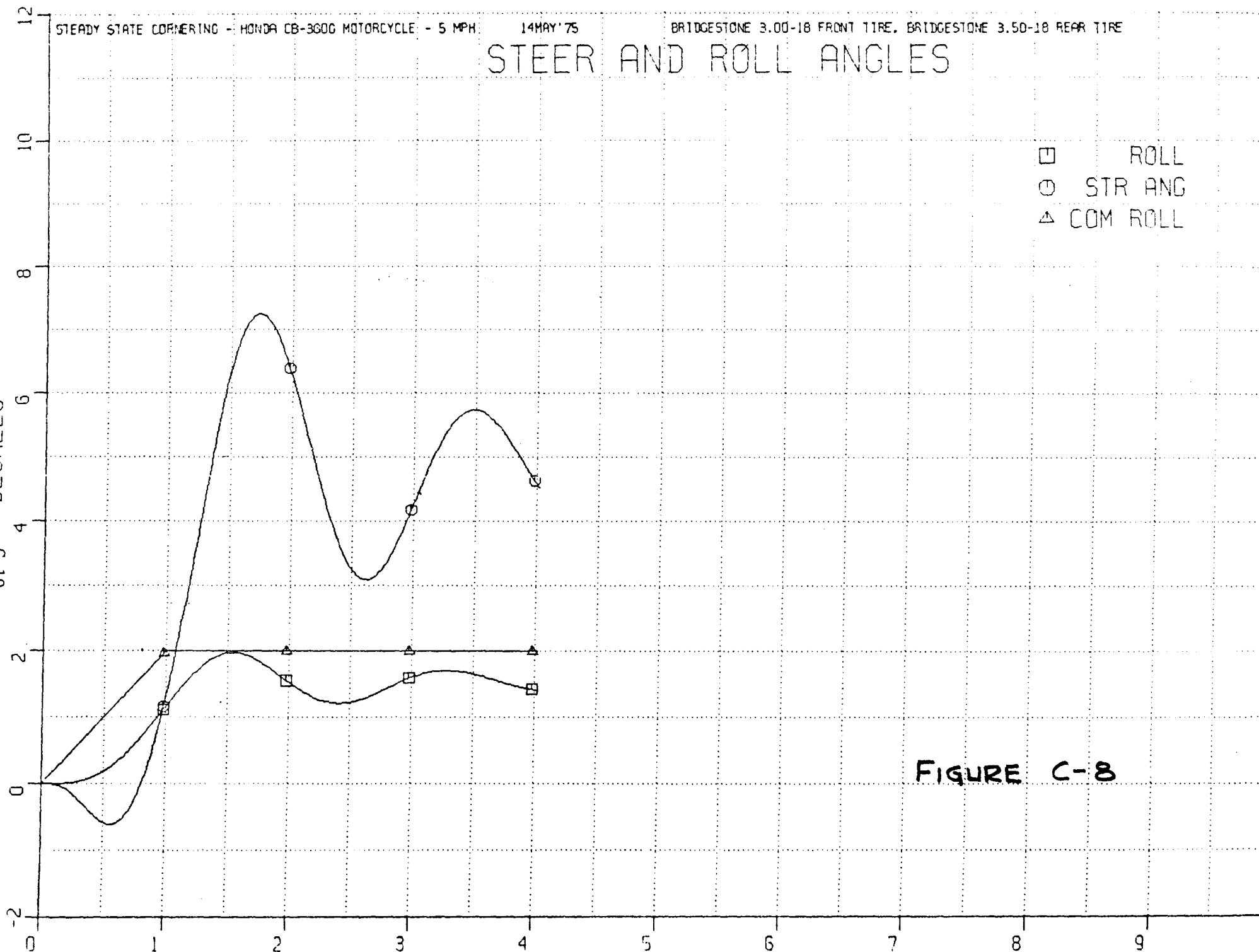


FIGURE C-8

STEADY STATE CORNERING - HONDA CB-360C MOTORCYCLE - 5 MPH

14 MAY '75

BRIDGESTONE 3.00-18 FRONT TIRE, BRIDGESTONE 3.50-18 REAR TIRE

# STEERING TORQUE

□ STR TORQ

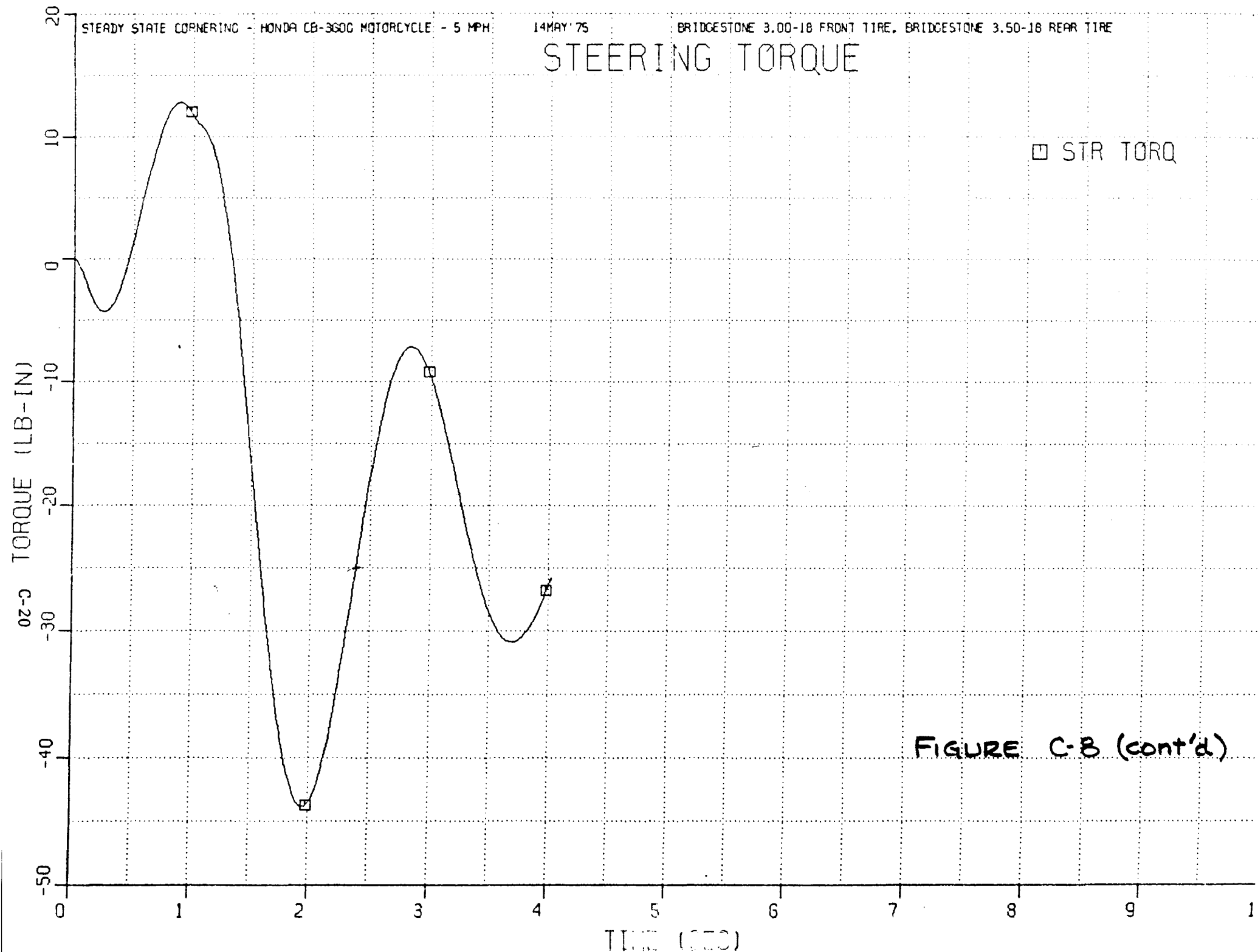


FIGURE C-8 (cont'd)



STEADY STATE CORNERING - HONDA CB-350C MOTORCYCLE - 20 MPH 6 JUN 75 BRIDGESTONE 3.00-18 FRONT TIRE, BRIDGESTONE 3.50-18 REAR TIRE

# STEER AND ROLL ANGLES

- ROLL
- STR ANG
- △ COM ROLL

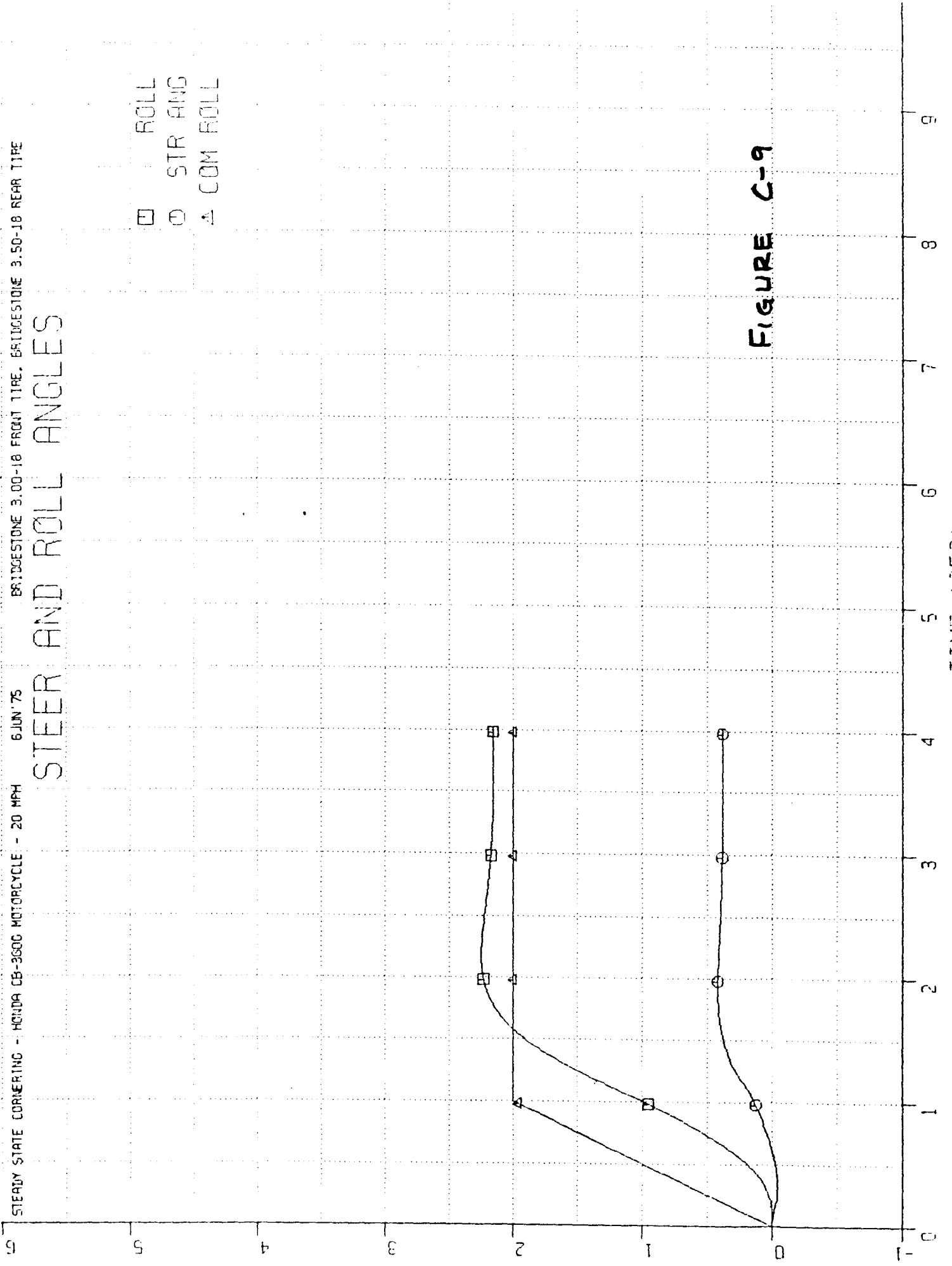


FIGURE C-9

STEADY STATE CORNERING - HONDA CB-500C MOTORCYCLE - 20 MPH

6 JUN 75

BRIDGESTONE 3.00-18 FRONT TIRE, BRIDGESTONE 3.50-18 REAR TIRE

# STEERING TORQUE

□ STR TORQ

22-C TORQUE (LB-IN)

TIME (SEC)

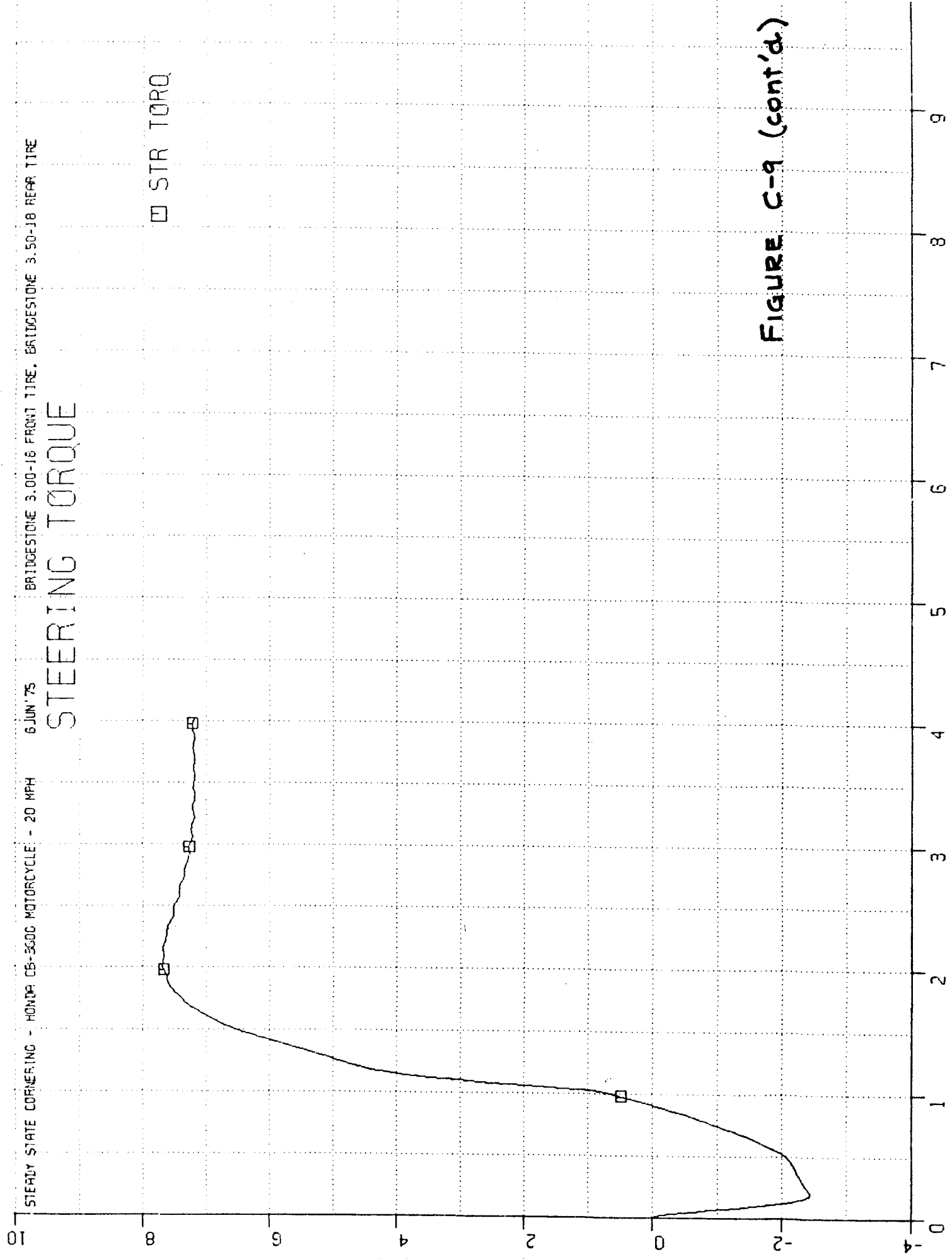


FIGURE C-9 (cont'd)

STEADY STATE CORNERING - HONDA CB-360C MOTORCYCLE - 40 MPH 6 JUN '75 BRIDGESTONE 3.00-18 FRONT TIRE, BRIDGESTONE 3.50-18 REAR TIRE

# STEER AND ROLL ANGLES

- ROLL
- STR ANG
- △ COM ROLL

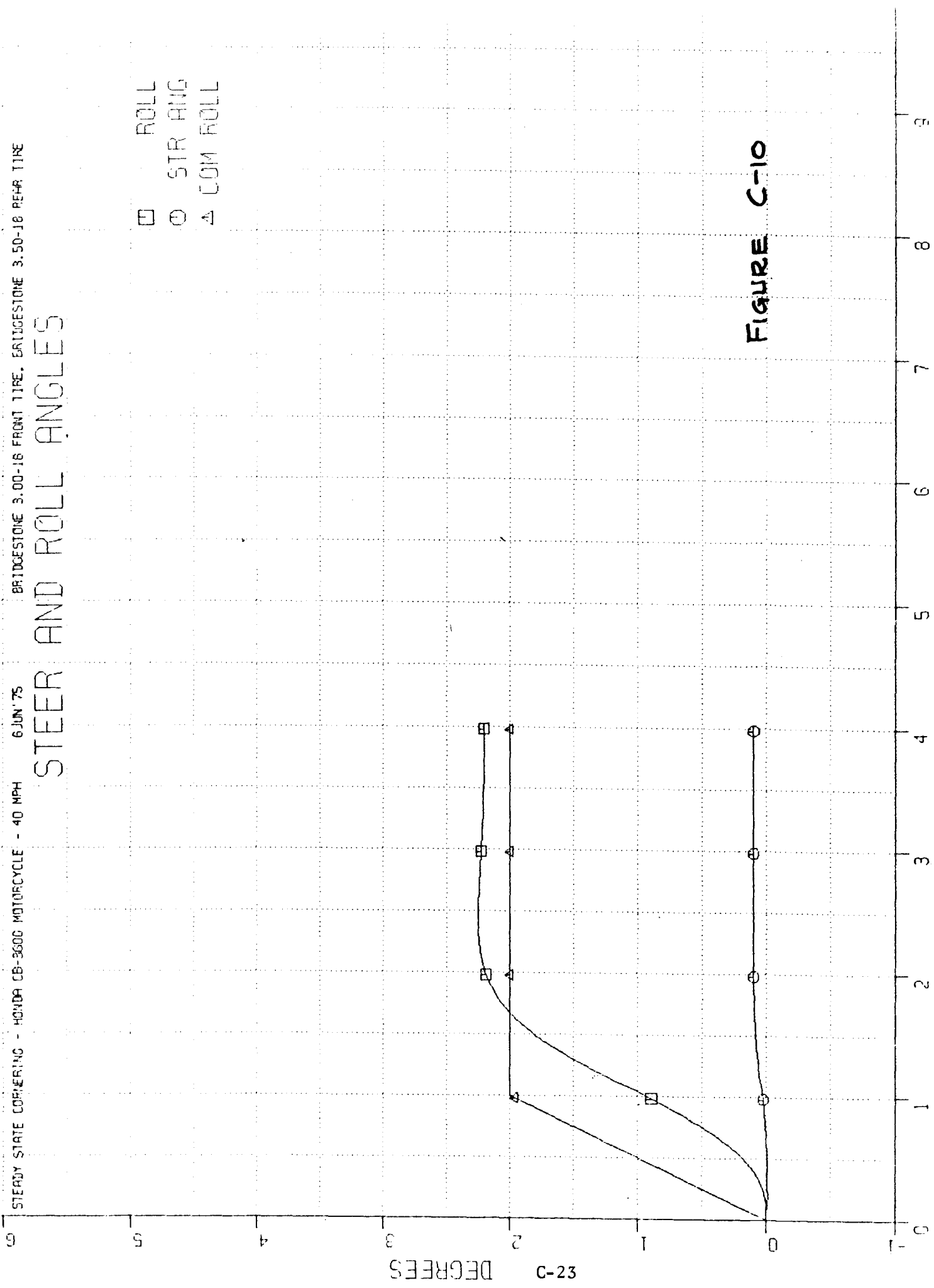


FIGURE C-10

STEADY STATE CORNERING - HONDA CB-360C MOTORCYCLE - 40 MPH

6 JUN '75

BRIDGESTONE 3.00-18 FRONT TIRE, BRIDGESTONE 3.50-18 REAR TIRE

# STEERING TORQUE

□ STR TORQ

C-24  
TORQUE (LB-IN)

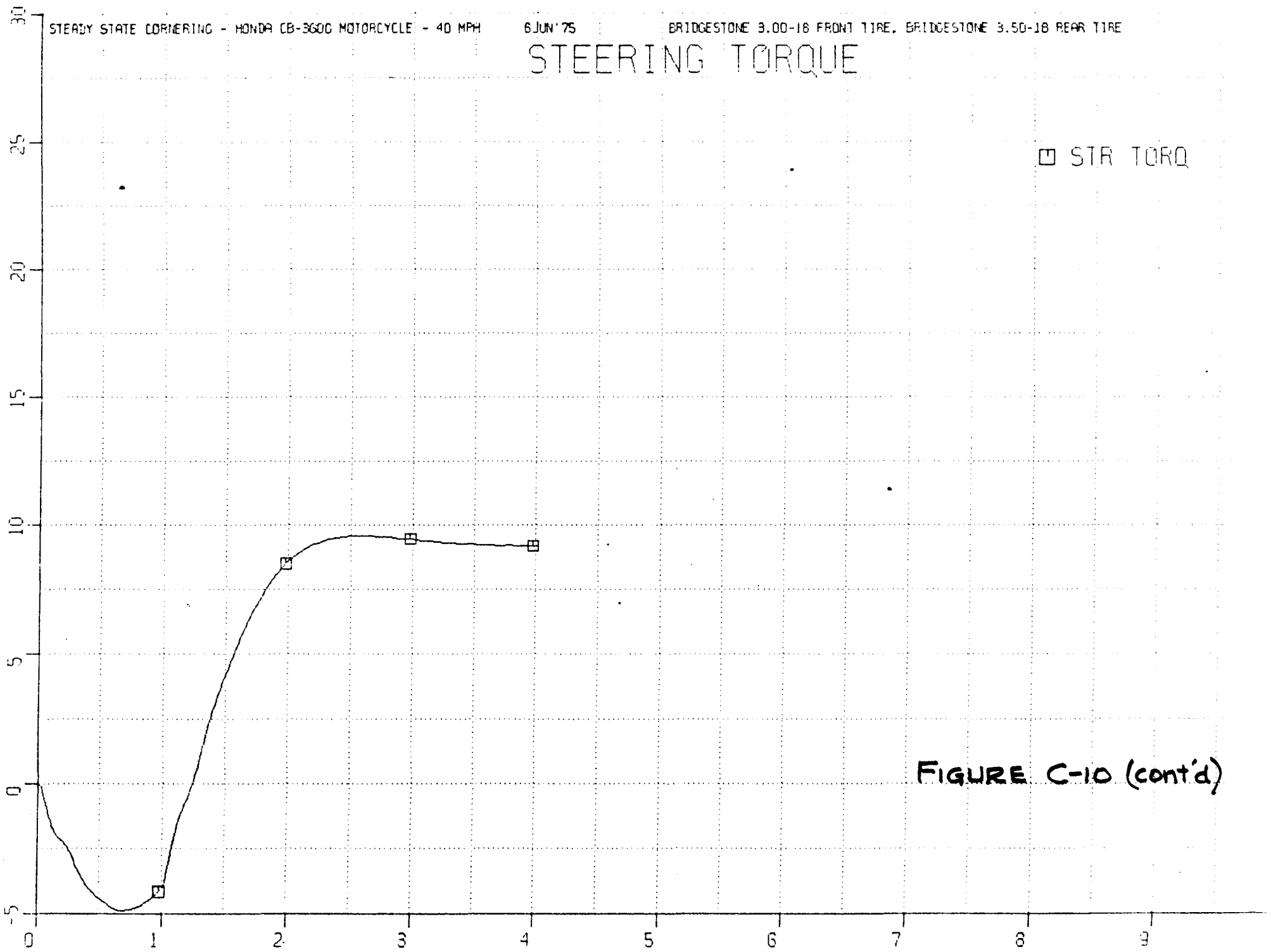


FIGURE C-10 (cont'd)

TIME (SEC)



NEW YORK CONCEPTS - HONDA FORTINO MOTORCYCLE - 40 MPH - 10 JUN 75 - BRIDGEVIEW N.C. 1165 FRONT & REAR, METRIC STEERING PILES  
STEERING TORQUE

□ STR TORQ

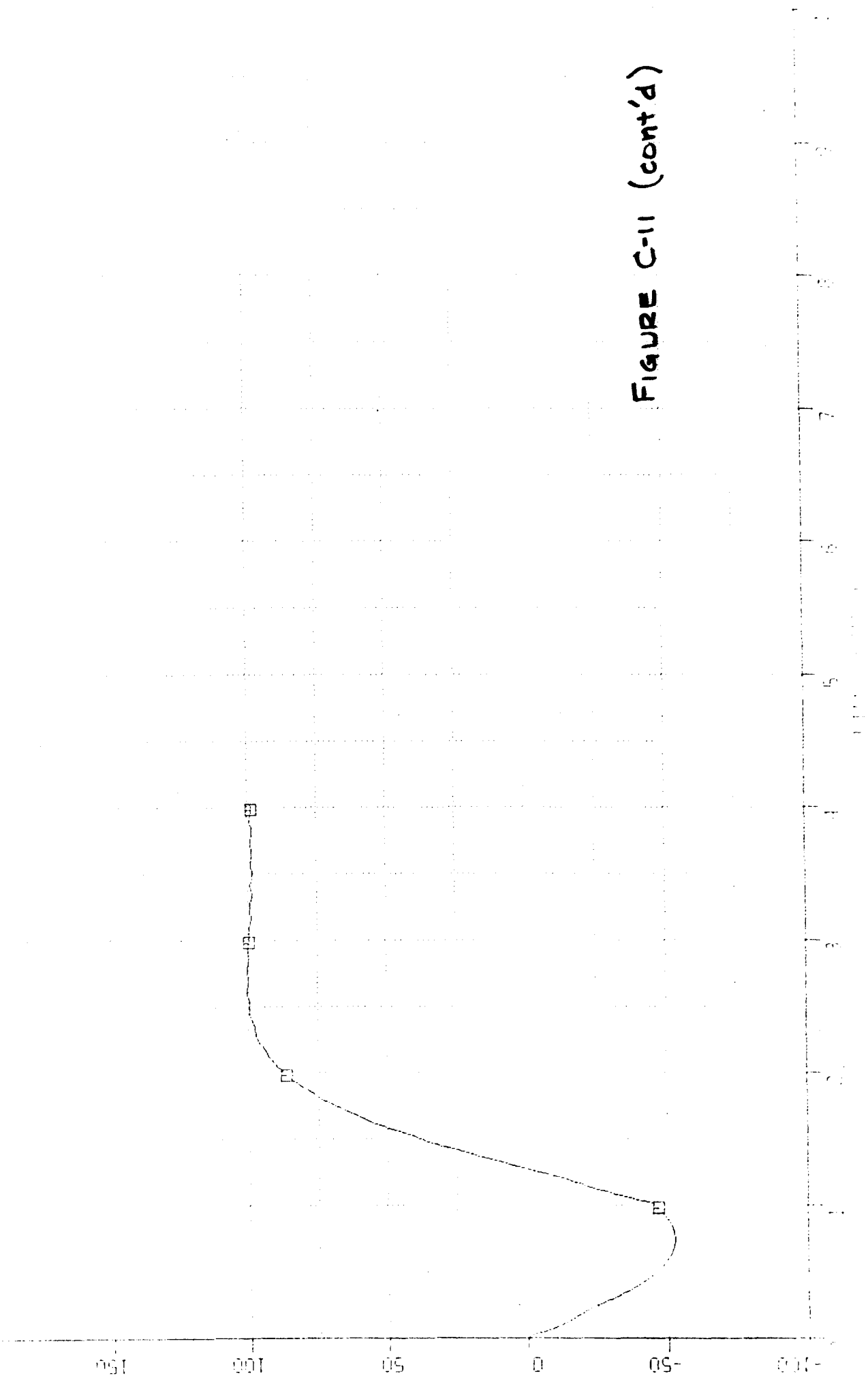


FIGURE C-11 (cont'd)

STEERS STATE CORNERING - 103104 UB-2 AND 3 WINDSICLE - 40 MPH 16 JUN 75 ESTIMATING D.E. TURES FROM 2 REAR, INDEPENDENT OF THE 30 RING

# STEER AND ROLL ANGLES

- ROLL
- STR ANG
- △ COM ROLL

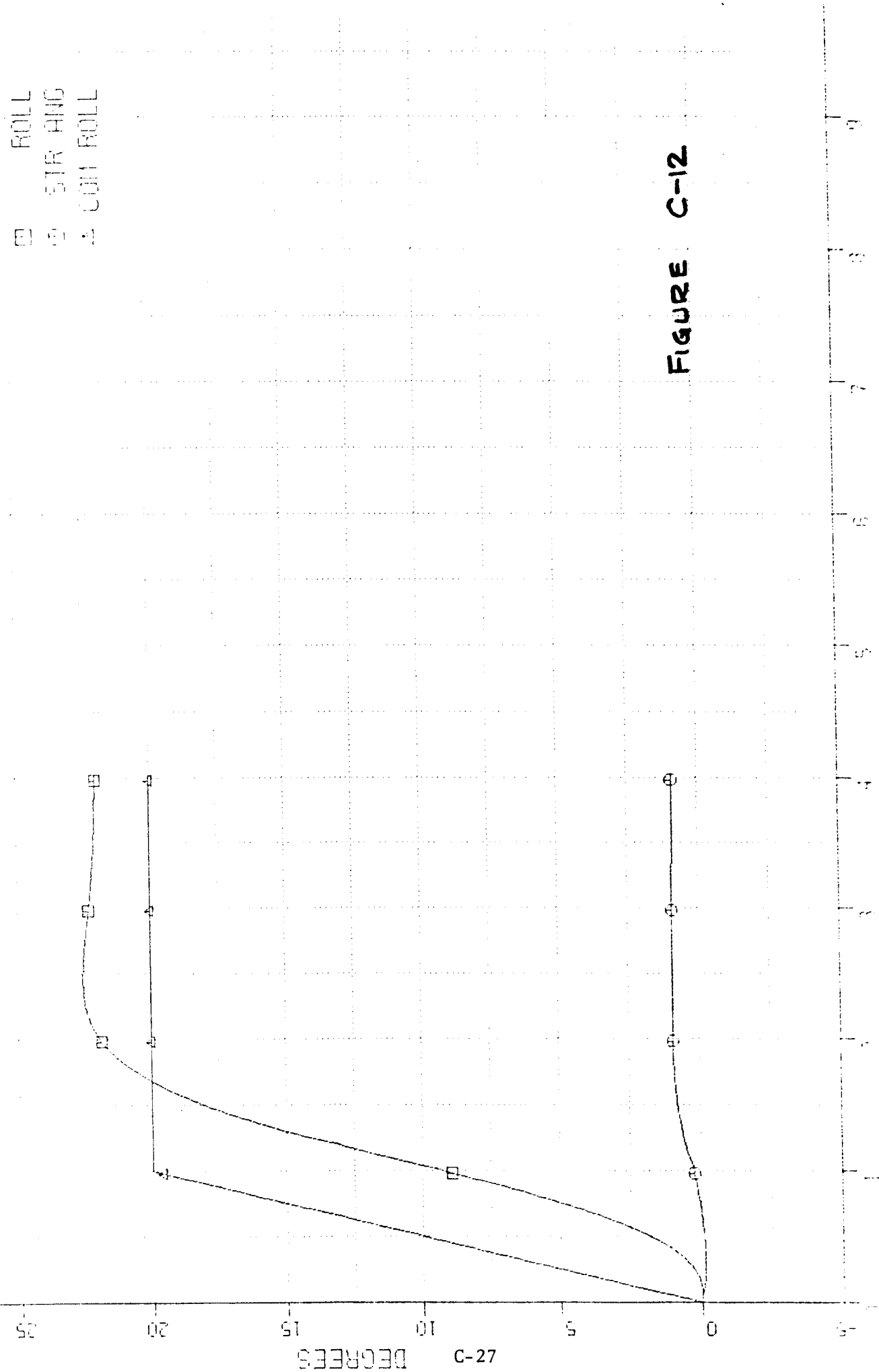


FIGURE C-12

STEADY STATE CORNERING - HONDA CB-500 MOTORCYCLE - 40 MPH

16 JUNE 75

BRIMSTONE OIL, TIRES FRONT & REAR, INTERMEDIATE STIFFNESS RIDER

# STEERING TORQUE

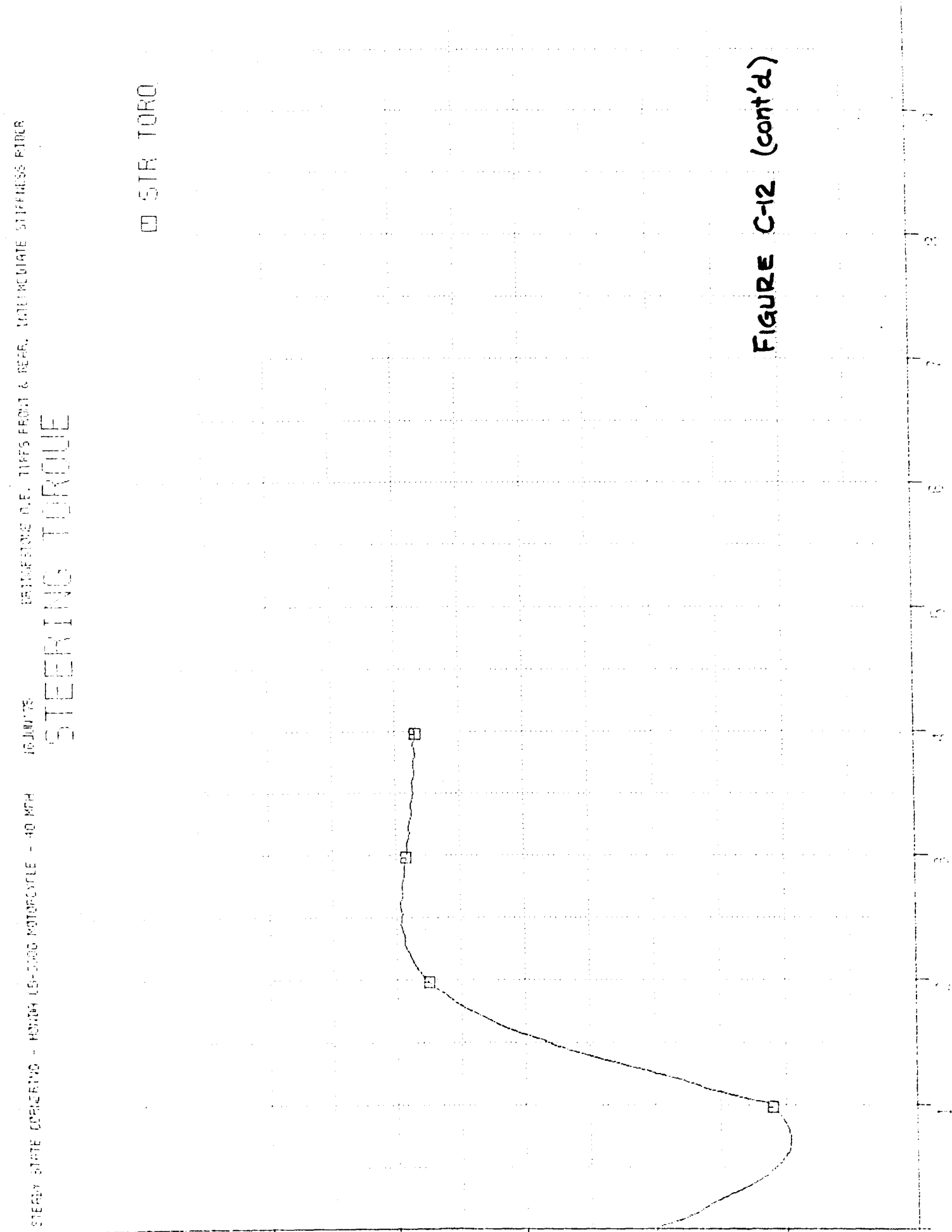
□ STR TORQ

C-28 TORQUE (LB-IN)

250  
200  
150  
100  
50  
0  
-50  
-100

1 2 3 4 5 6 7 8 9

FIGURE C-12 (cont'd)





DATE: 10/15/54 TIME: 10:00 AM

17 INCHES

40 MPH

WIND DIRECTION: 100 DEGREES

10

# STEER AND ROLL ANGLES

- ROLL
- STEER
- △ COM ROLL

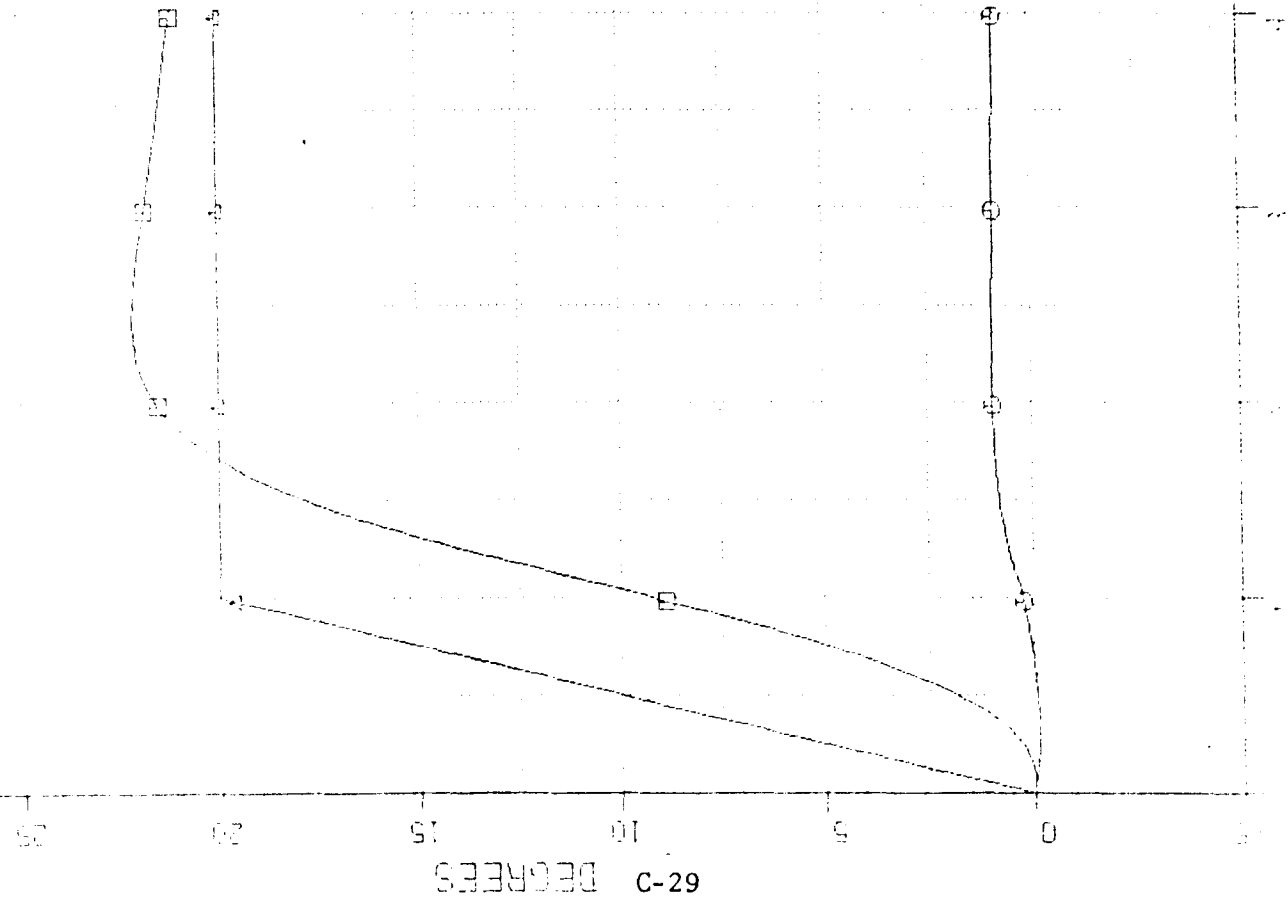


FIGURE C-13

# STEERING TORQUE

W STR TORQ

C-30

250  
200  
150  
100  
50  
0  
-50  
-100

0 10 20 30 40 50 60 70 80 90 100

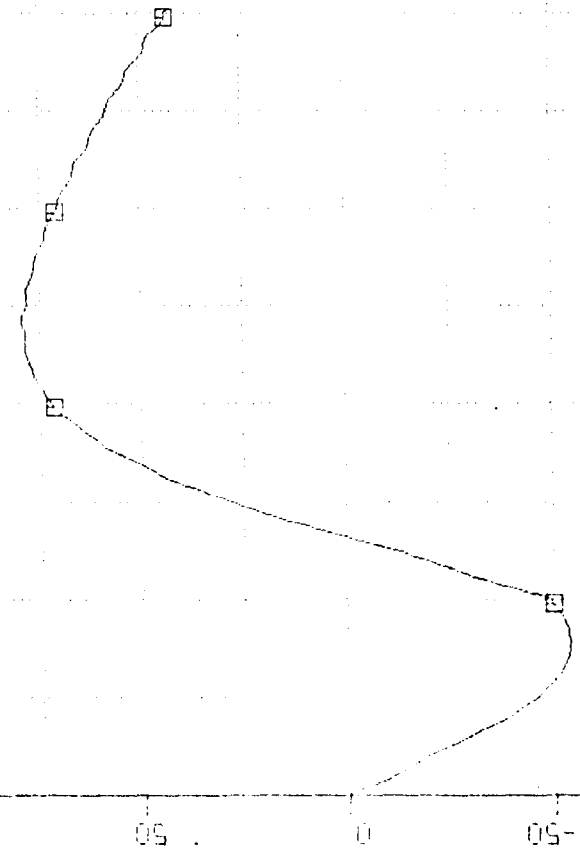
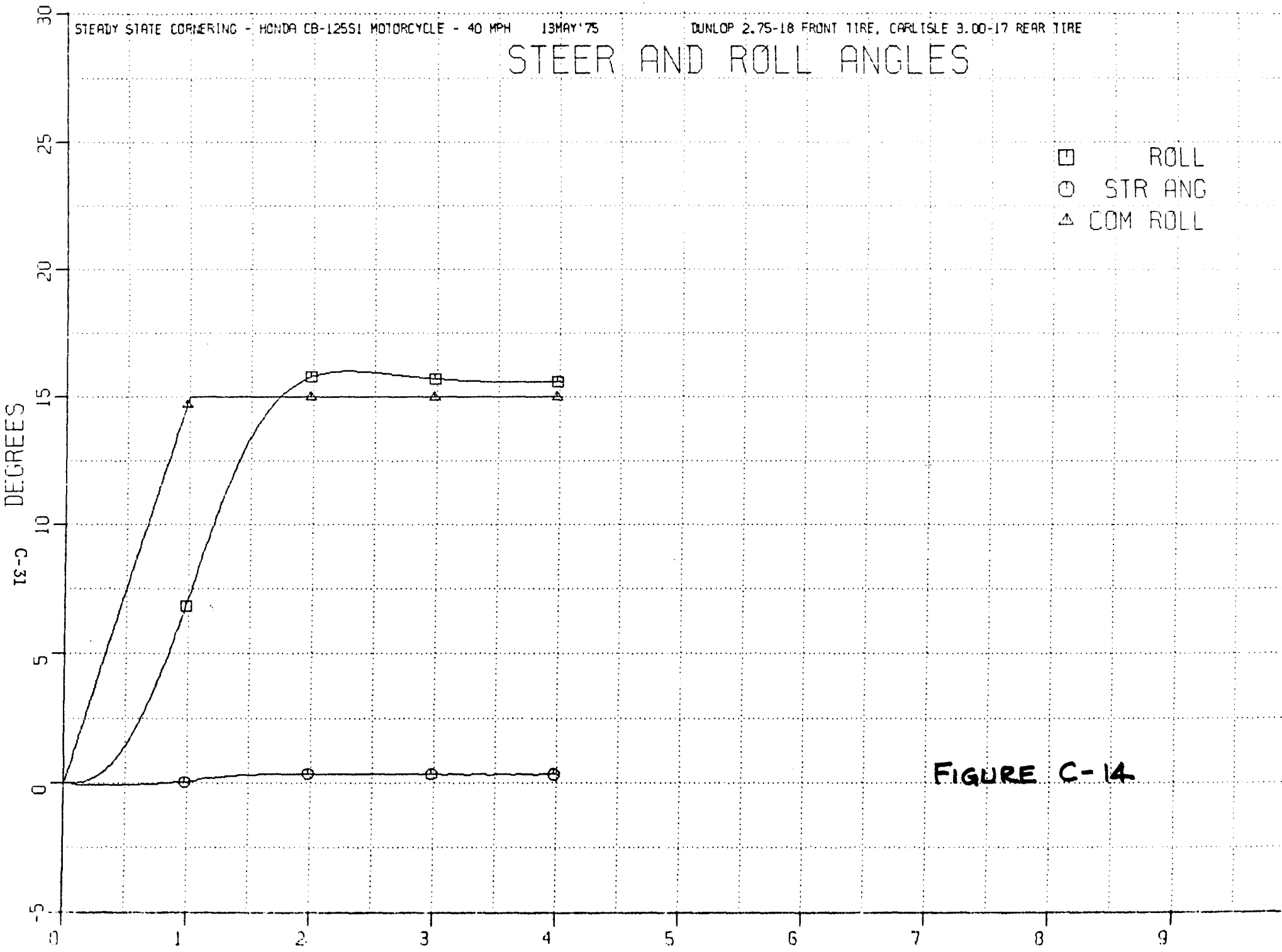


FIGURE C-13 (cont'd)

STEADY STATE CORNERING - HONDA CB-125S1 MOTORCYCLE - 40 MPH 13MAY 75

DUNLOP 2.75-18 FRONT TIRE, CARLISLE 3.00-17 REAR TIRE

# STEER AND ROLL ANGLES



□ ROLL  
○ STR ANG  
△ COM ROLL

FIGURE C-14

STEADY STATE CORNERING - HONDA CB-125SI MOTORCYCLE - 40 MPH

13MAY'75

DUNLOP 2.75-18 FRONT TIRE, CARLISLE 3.00-17 REAR TIRE

# STEERING TORQUE

□ STR TORQ

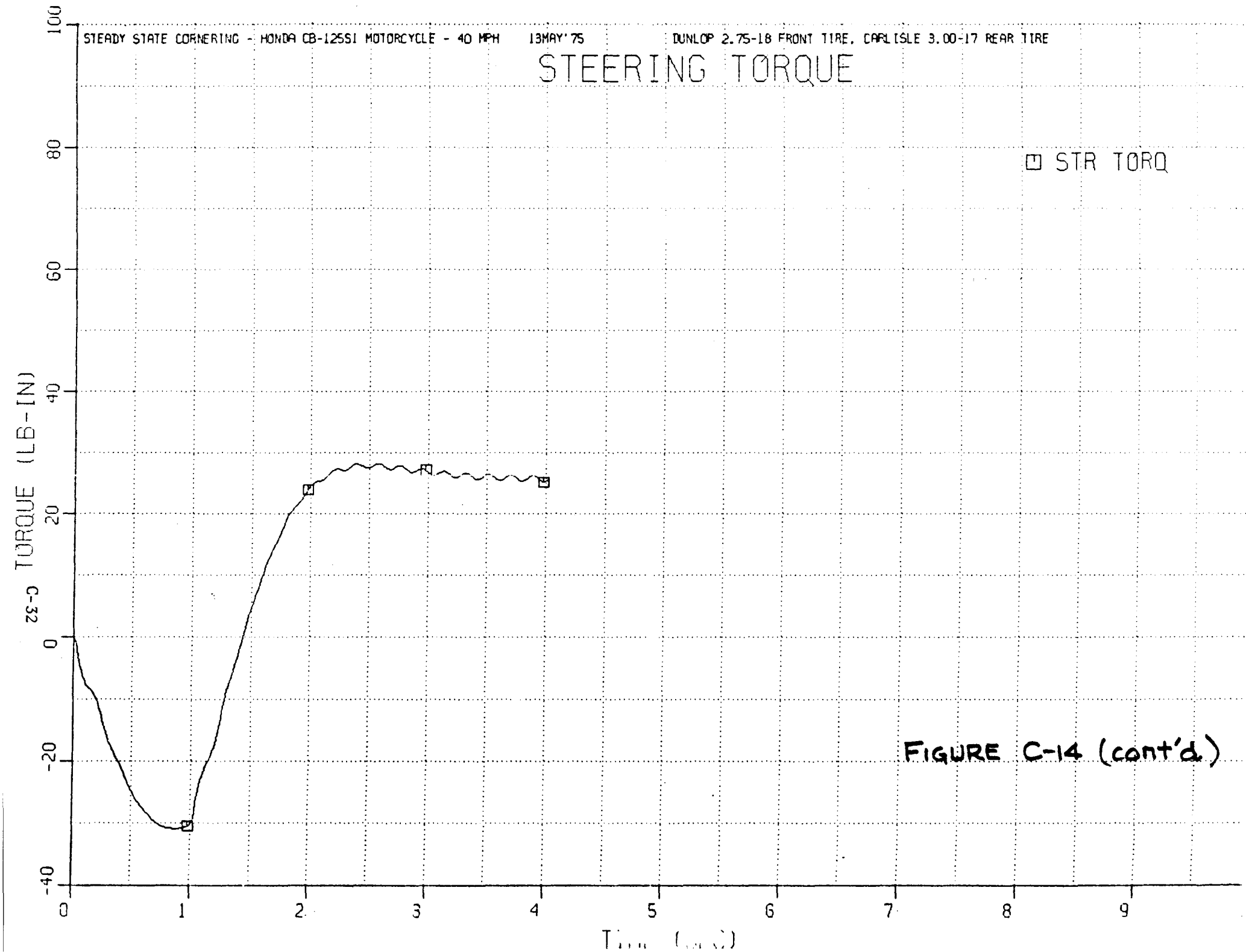
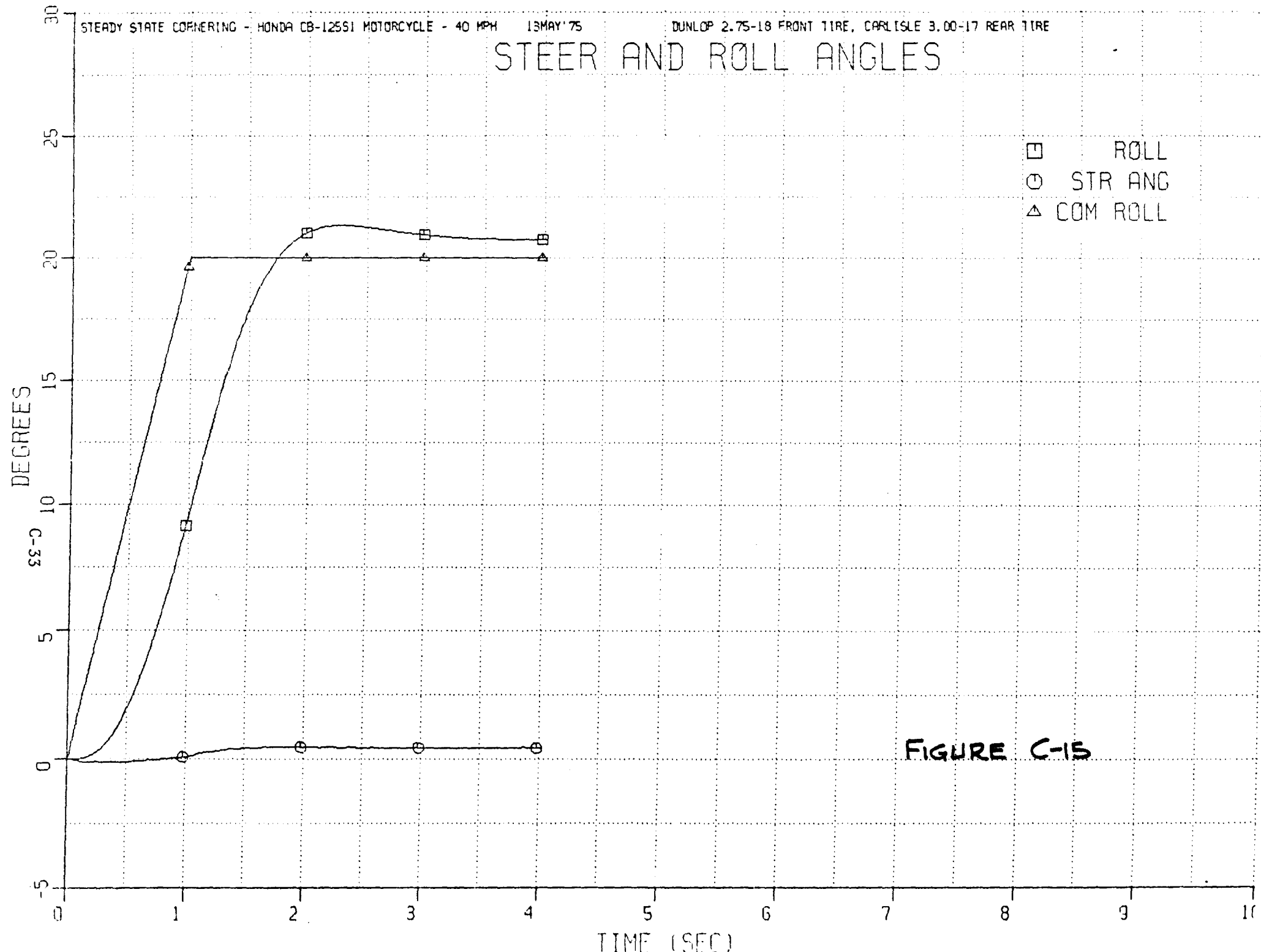


FIGURE C-14 (cont'd.)

STEADY STATE CORNERING - HONDA CB-125S1 MOTORCYCLE - 40 MPH 13MAY'75

DUNLOP 2.75-18 FRONT TIRE, CARLISLE 3.00-17 REAR TIRE

# STEER AND ROLL ANGLES



□ ROLL  
○ STR ANG  
△ COM ROLL

FIGURE C-15

STEADY STATE CORNERING - HONDA CB-125SI MOTORCYCLE - 40 MPH 13MAY'75 DUNLOP 2.75-18 FRONT TIRE, CARLISLE 3.00-17 REAR TIRE

# STEERING TORQUE

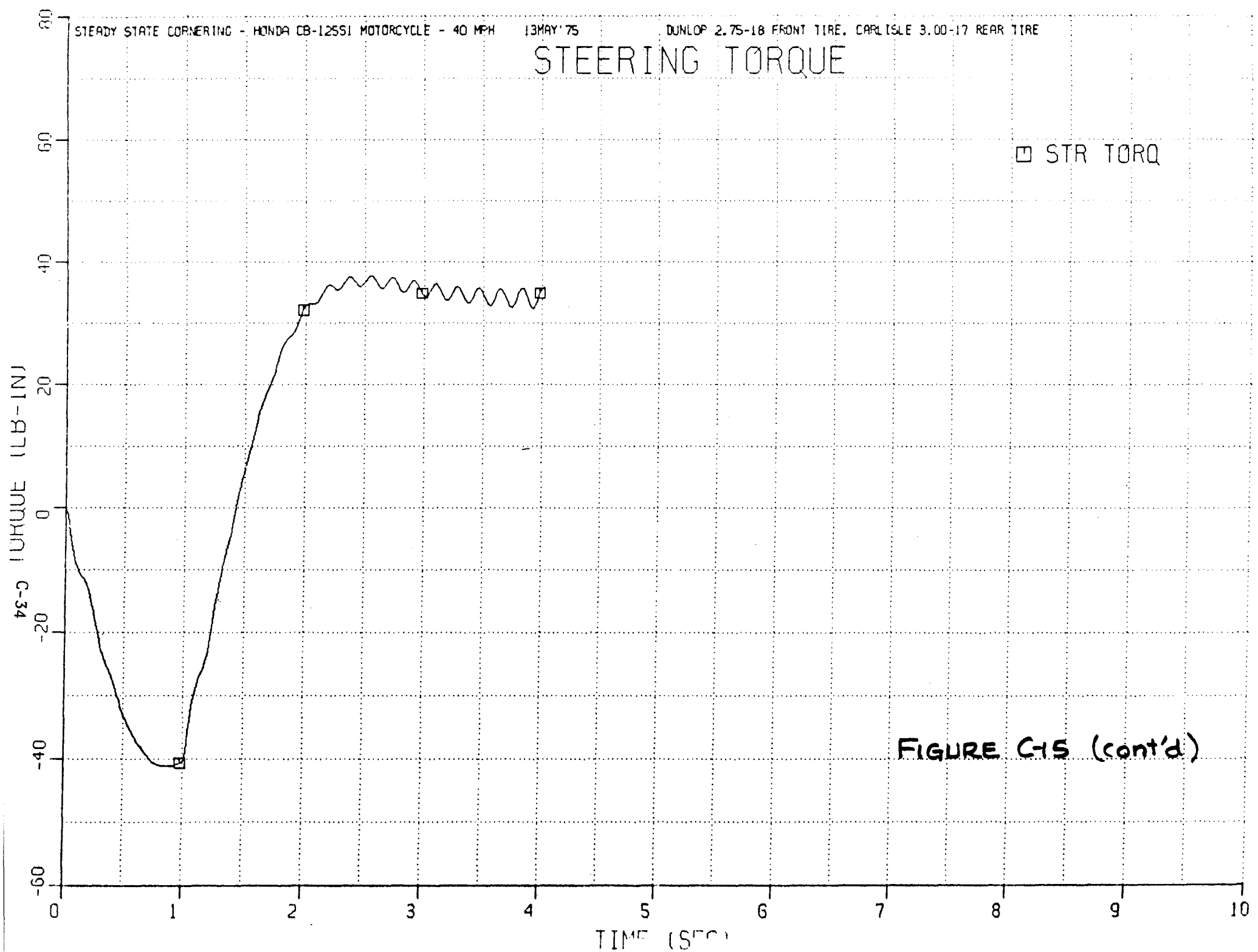


FIGURE C-15 (cont'd)

STEADY STATE CORNERING - HONDA CB-125S1 MOTORCYCLE - 40 MPH 13MAY '75

DUNLOP 2.75-18 FRONT TIRE, CARLISLE 3.00-17 REAR TIRE

# STEER AND ROLL ANGLES

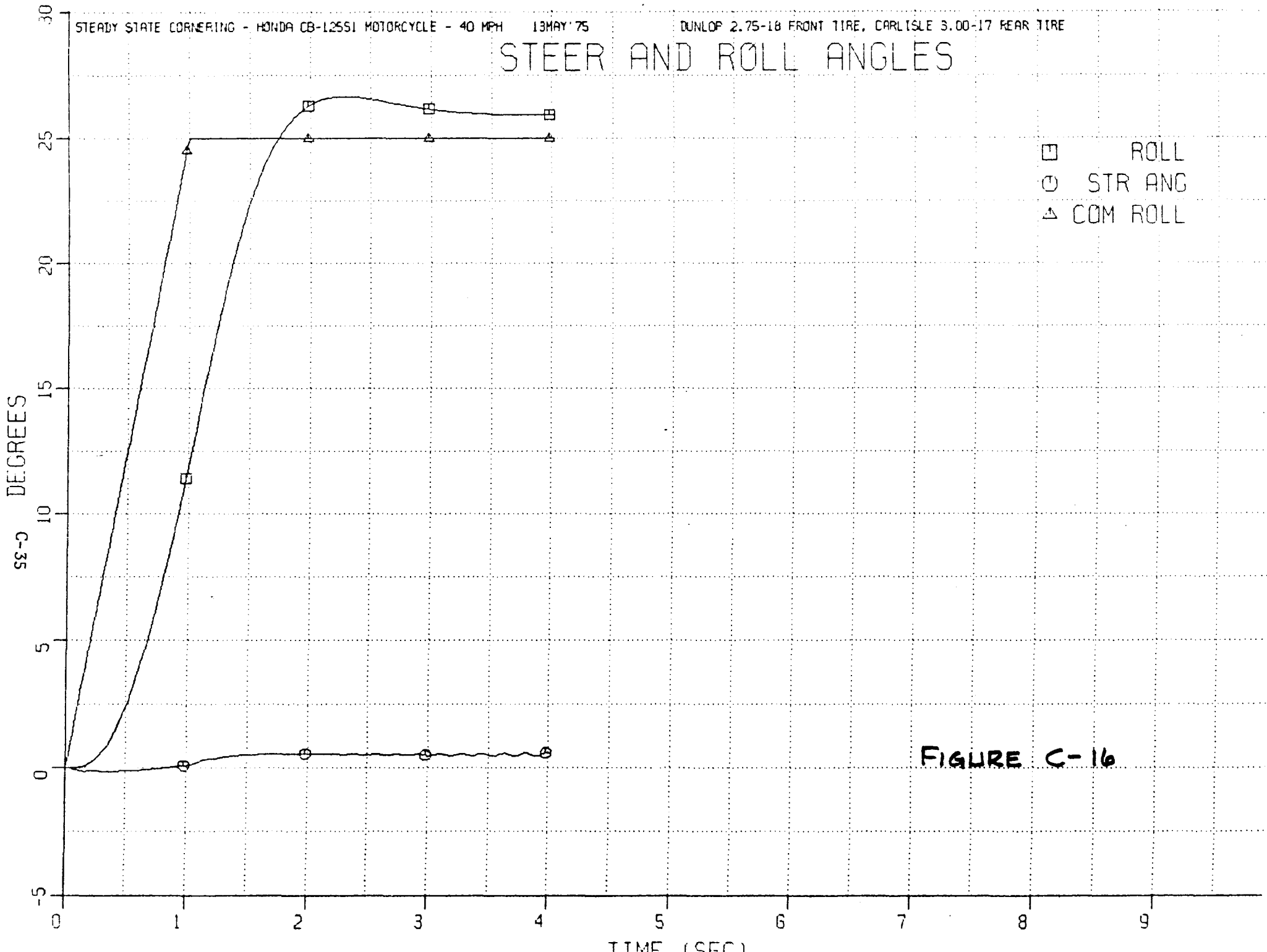


FIGURE C-16

STEADY STATE CORNERING - HONDA CB-125S1 MOTORCYCLE - 40 MPH

13MAY '75

DUNLOP 2.75-18 FRONT TIRE, CARLISLE 3.00-17 REAR TIRE

# STEERING TORQUE

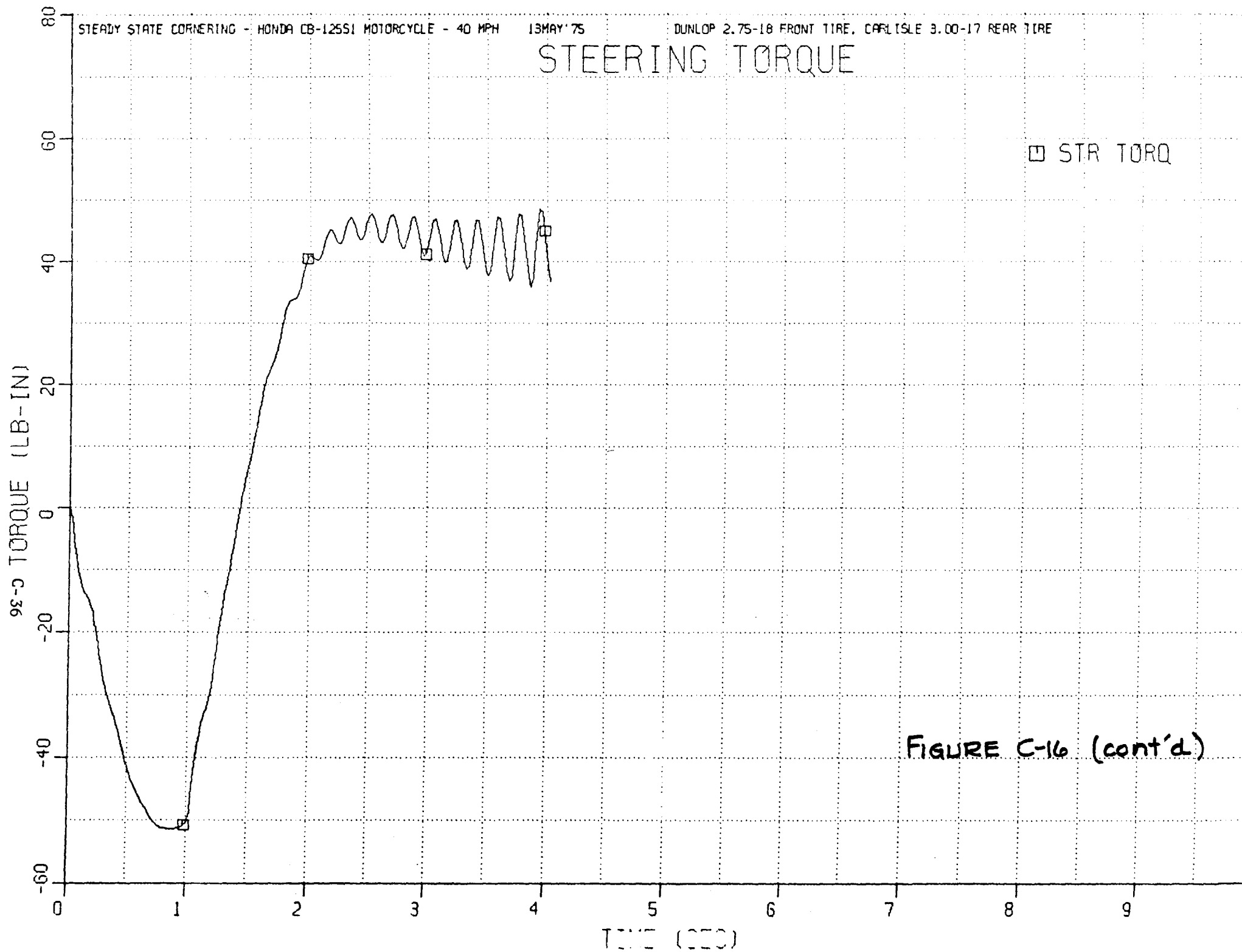


FIGURE C-16 (cont'd)

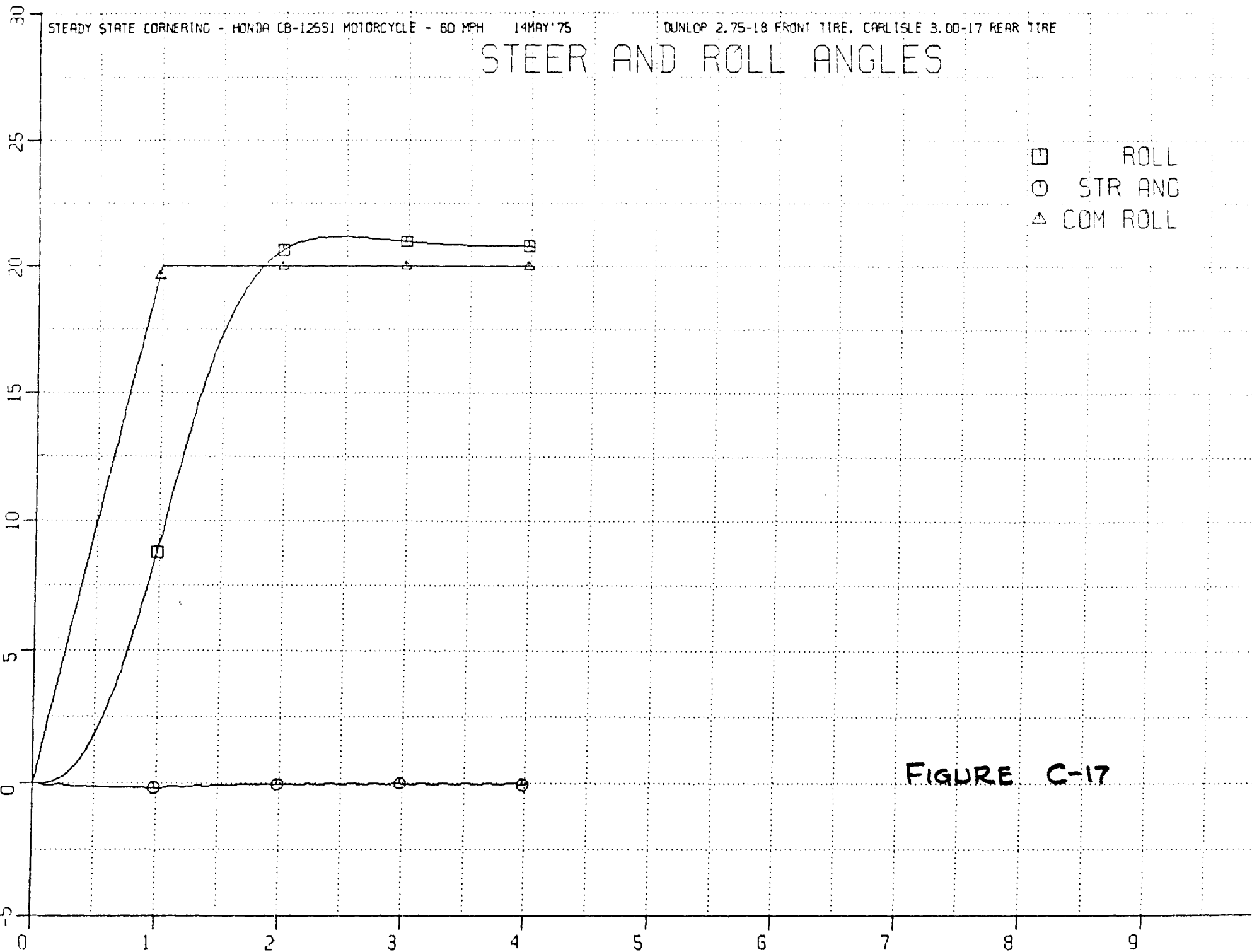


STEADY STATE CORNERING - HONDA CB-125SI MOTORCYCLE - 60 MPH 14MAY'75

DUNLOP 2.75-18 FRONT TIRE, CARLISLE 3.00-17 REAR TIRE

# STEER AND ROLL ANGLES

45-0 DEGREES



- ROLL
- STR ANG
- △ COM ROLL

FIGURE C-17

STEADY STATE CORNERING - HONDA CB-125SI MOTORCYCLE - 60 MPH 14 MAY '75

DUNLOP 2.75-18 FRONT TIRE, CARLISLE 3.00-17 REAR TIRE

# STEERING TORQUE

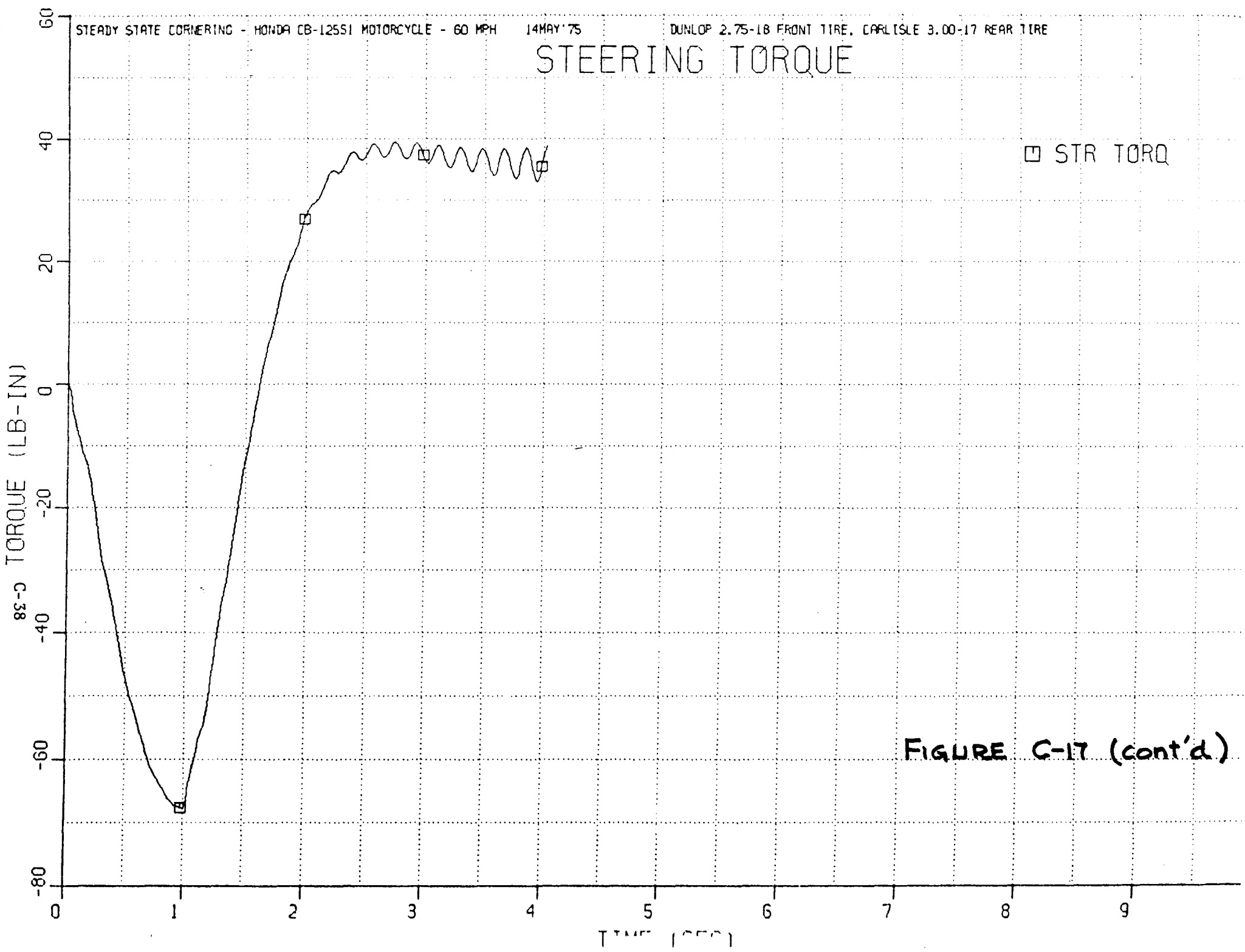
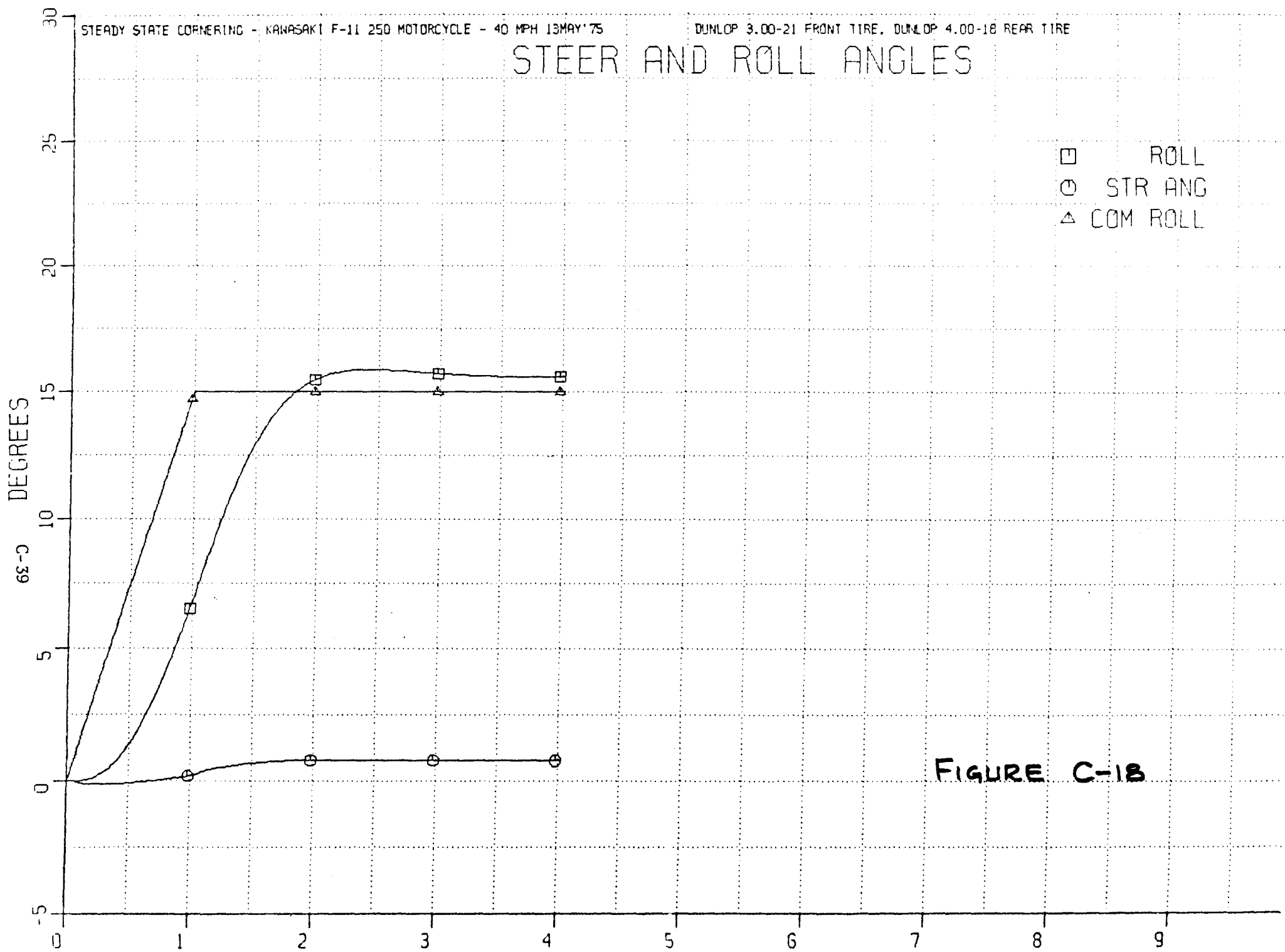


FIGURE C-17 (cont'd)

STEADY STATE CORNERING - KAWASAKI F-11 250 MOTORCYCLE - 40 MPH 13MAY'75

DUNLOP 3.00-21 FRONT TIRE, DUNLOP 4.00-18 REAR TIRE

# STEER AND ROLL ANGLES



- ROLL
- STR ANG
- △ COM ROLL

FIGURE C-18

STEADY STATE CORNERING - KAWASAKI F-11 250 MOTORCYCLE - 40 MPH 13MAY 75

DUNLOP 3.00-21 FRONT TIRE, DUNLOP 4.00-18 REAR TIRE

# STEERING TORQUE

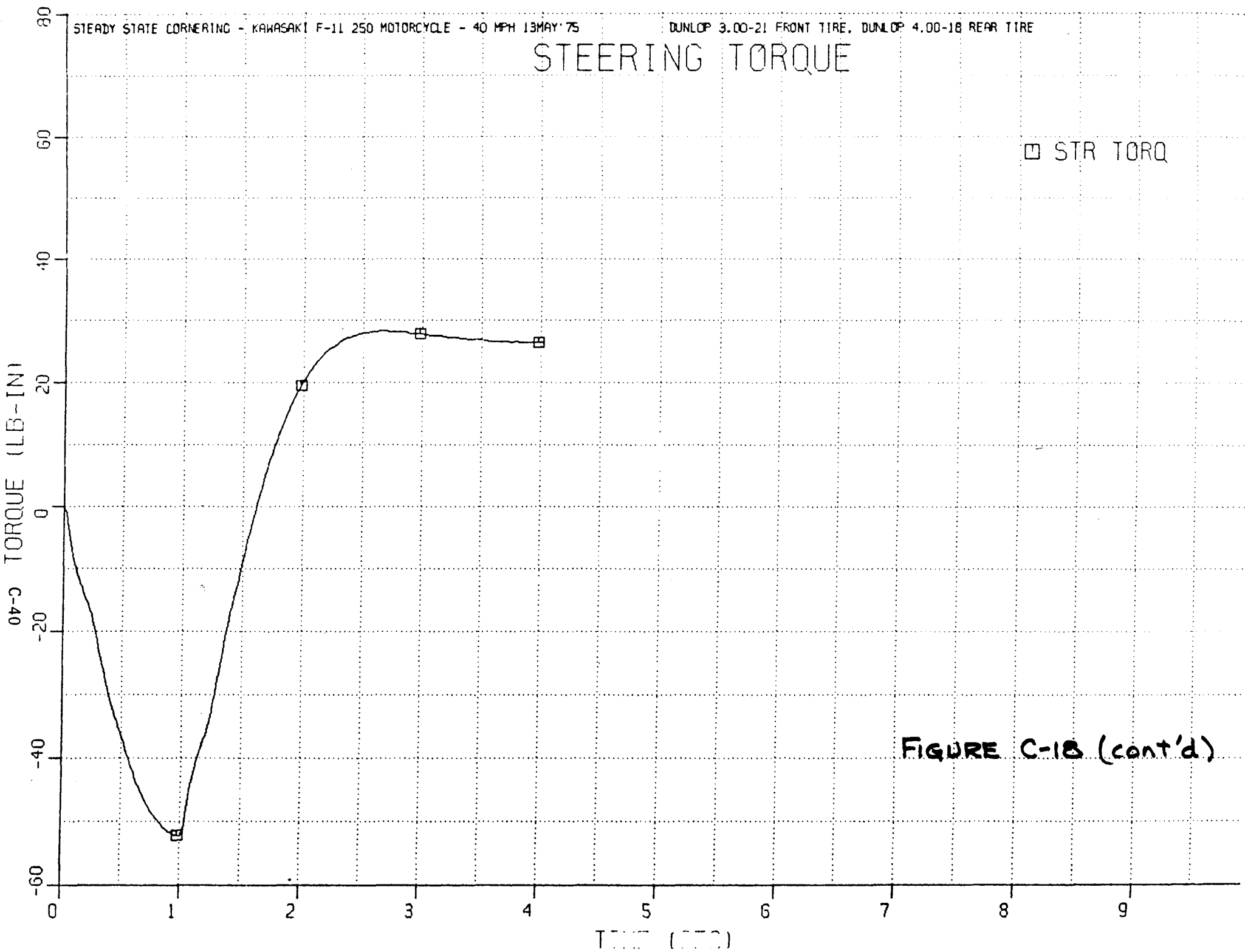


FIGURE C-18 (cont'd)

STEADY STATE CORNERING - KAWASAKI F-11 250 MOTORCYCLE - 40 MPH 13MAY '75

DUNLOP 3.00-21 FRONT TIRE, DUNLOP 4.00-18 REAR TIRE

# STEER AND ROLL ANGLES

DEGREES  
C-41

- ROLL
- STR ANG
- △ COM ROLL

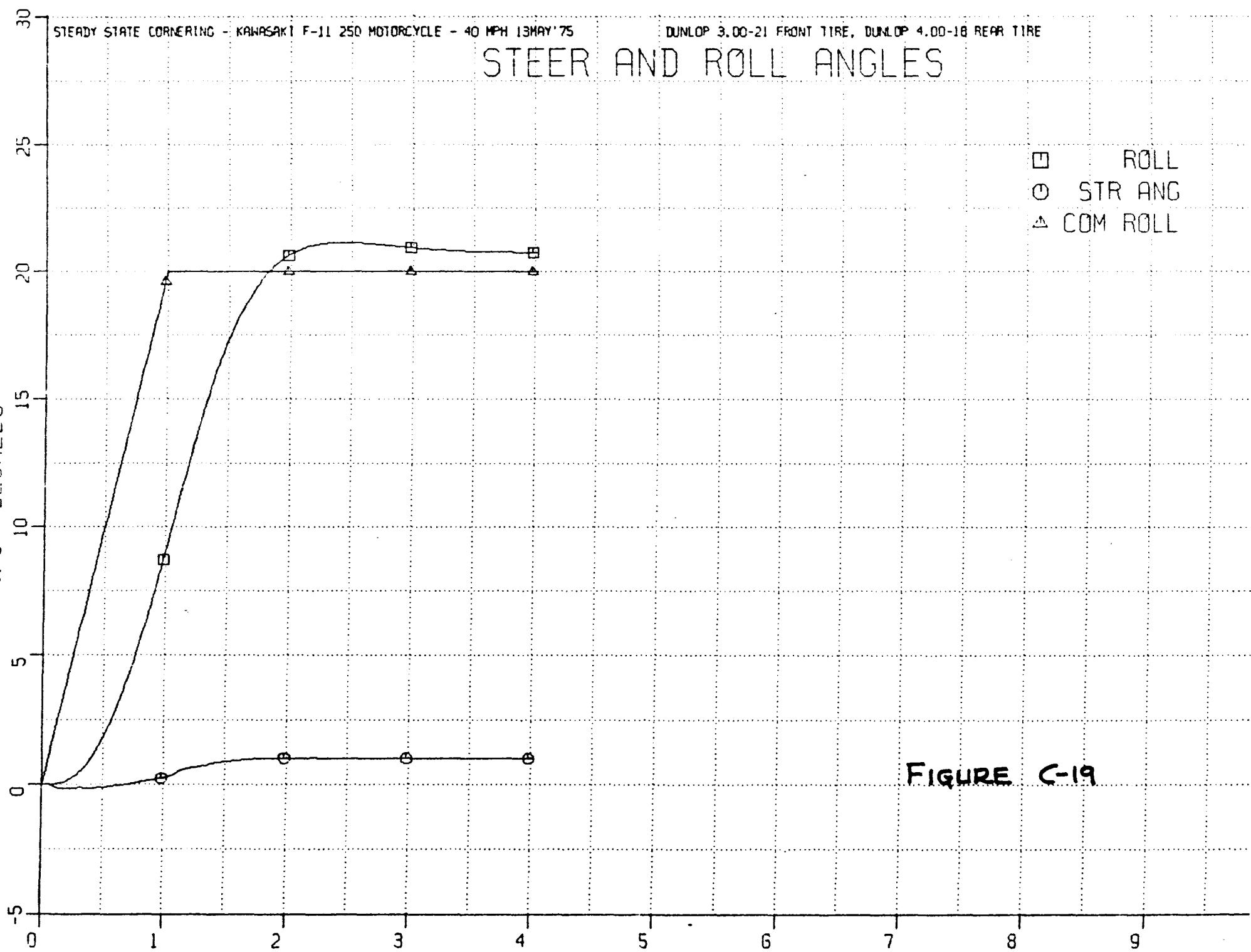


FIGURE C-19

STEADY STATE CORNERING - KAWASAKI F-11 250 MOTORCYCLE - 40 MPH 13MAY'75

DUNLOP 3.00-21 FRONT TIRE, DUNLOP 4.00-18 REAR TIRE

# STEERING TORQUE

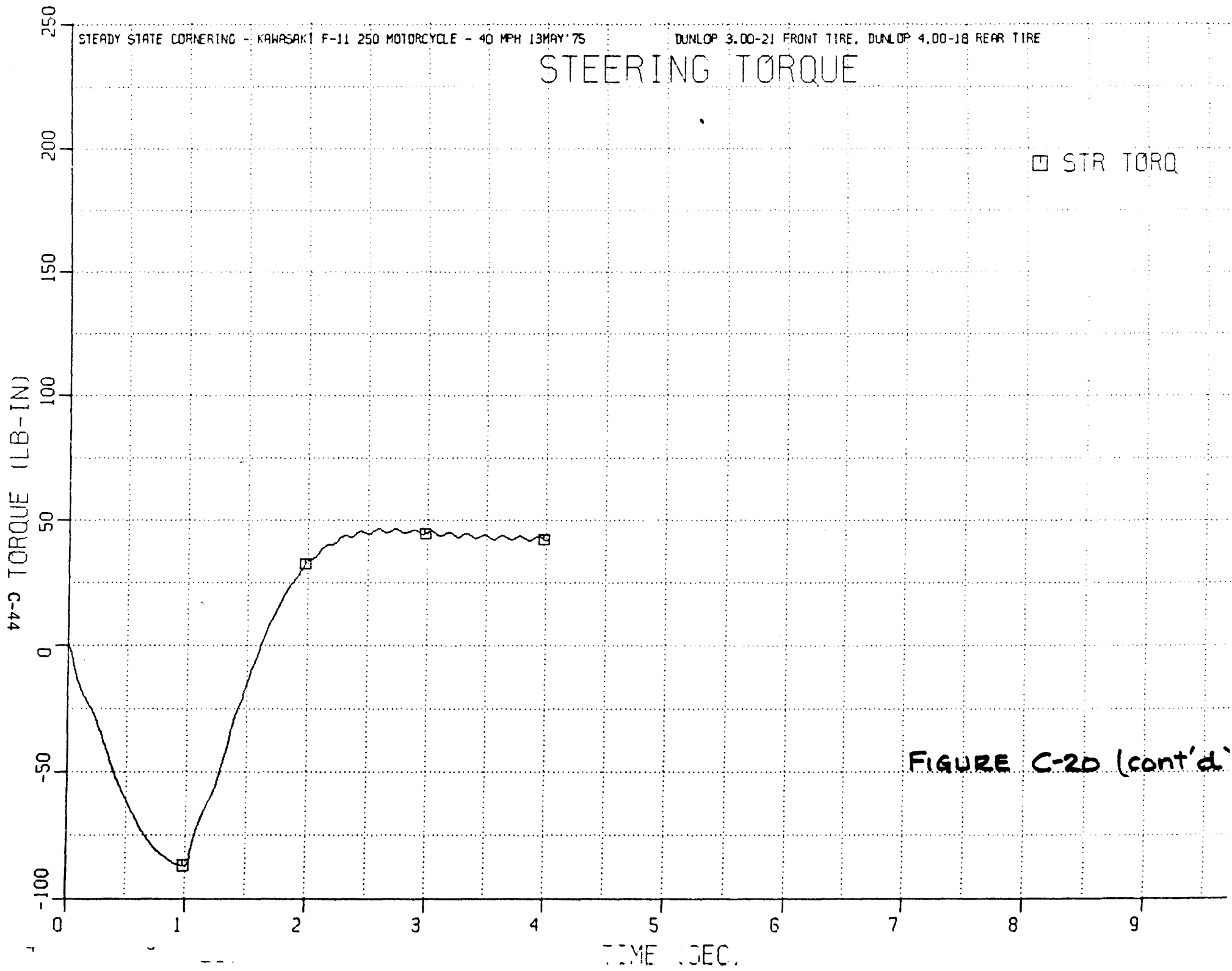
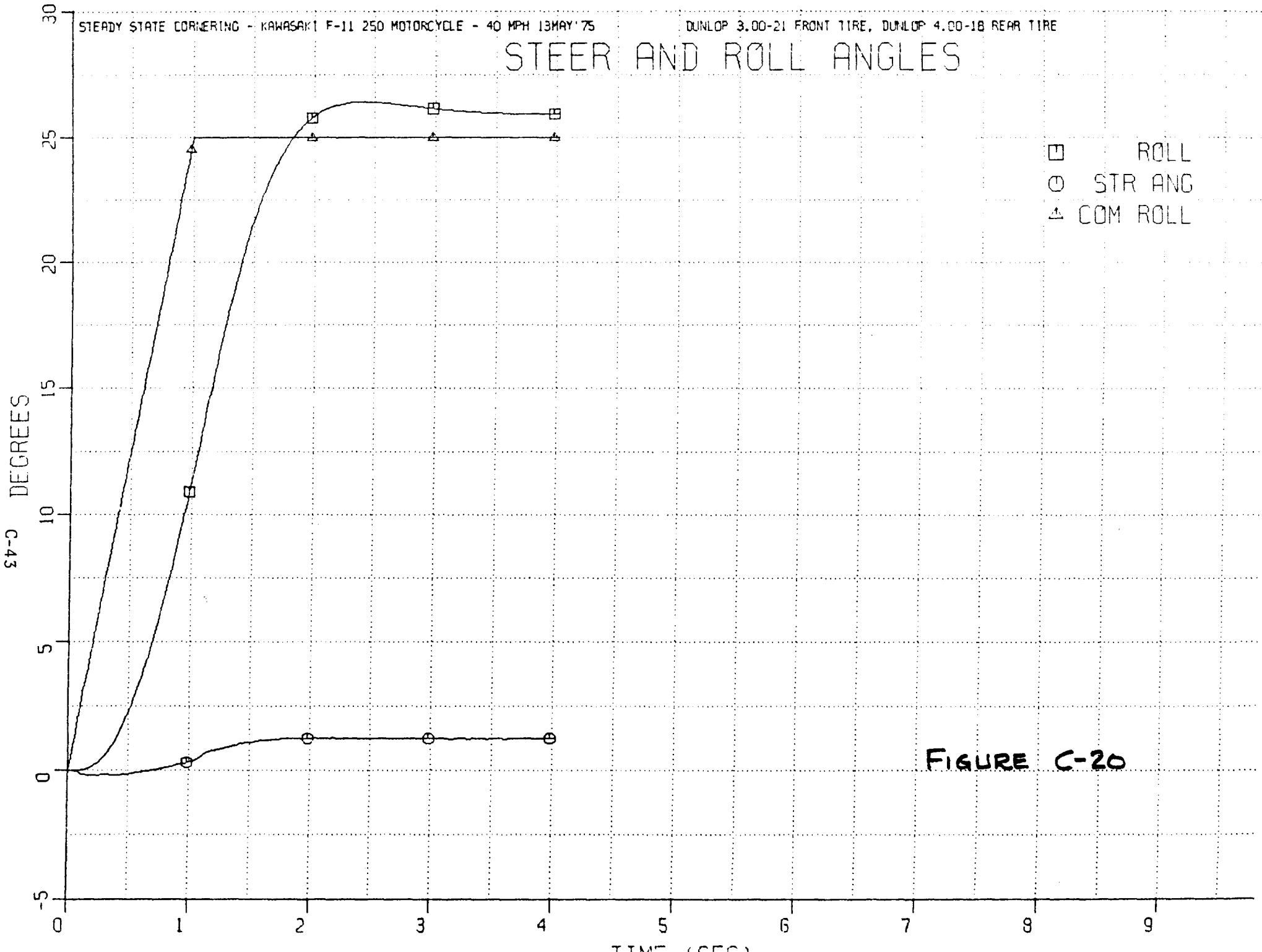


FIGURE C-20 (cont'd)

STEADY STATE CORNERING - KAWASAKI F-11 250 MOTORCYCLE - 40 MPH 13MAY '75

DUNLOP 3.00-21 FRONT TIRE, DUNLOP 4.00-18 REAR TIRE

# STEER AND ROLL ANGLES



- ROLL
- STR ANG
- △ COM ROLL

FIGURE C-20

STEADY STATE CORNERING -- YAMAHA XS-2 650 MOTORCYCLE -- 40 MPH 9 JUN '75

YOKOHAMA 3.50-19 FRONT TIRE, YOKOHAMA 4.00-18 REAR TIRE

# STEER AND ROLL ANGLES

- ROLL
- STR ANG
- △ COM ROLL

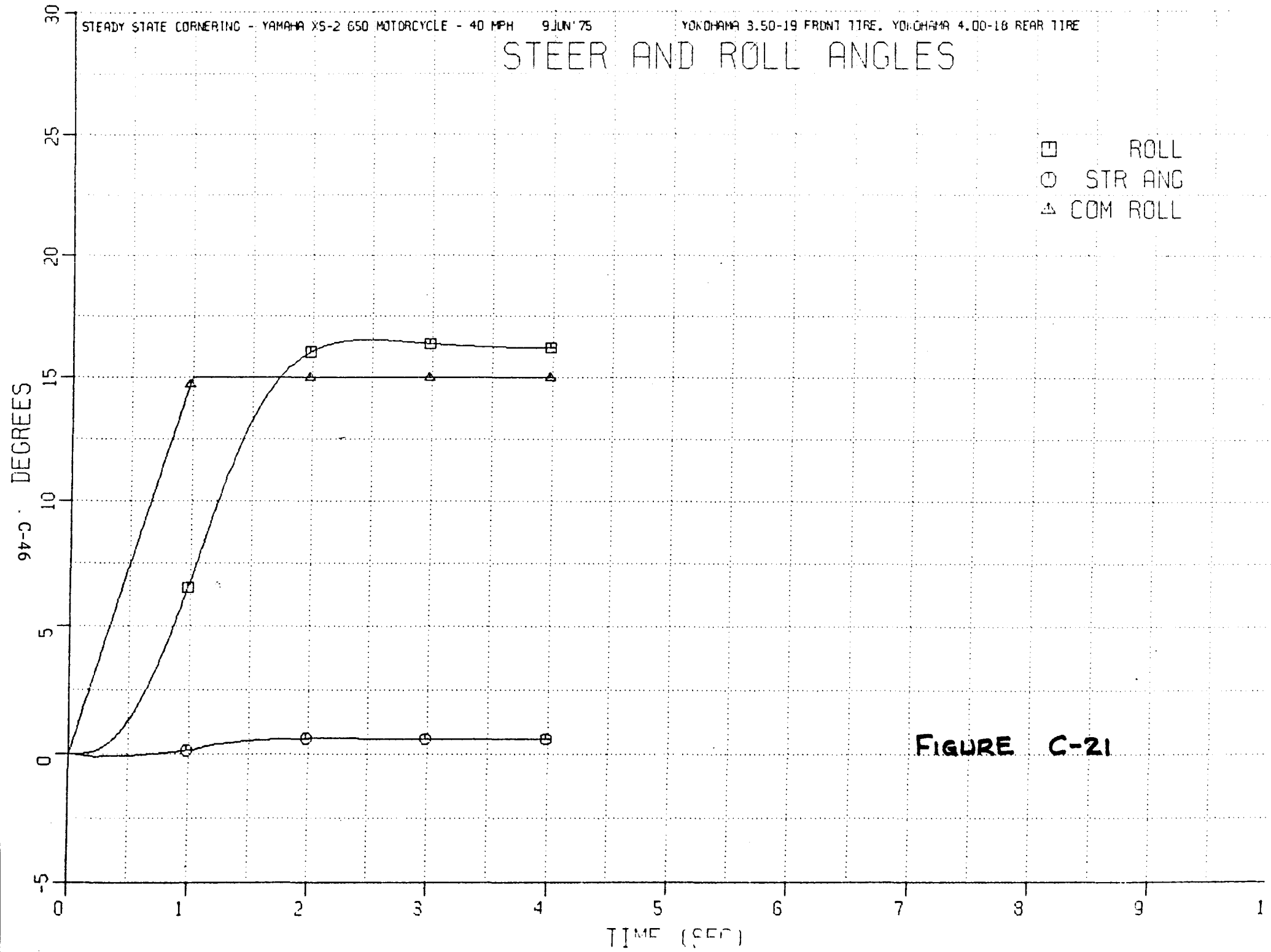


FIGURE C-21



STEADY STATE CORNERING - YAMAHA XS-2 650 MOTORCYCLE - 40 MPH

9 JUN '75

YOKOHAMA 3.50-19 FRONT TIRE, YOKOHAMA 4.00-18 REAR TIRE

# STEERING TORQUE

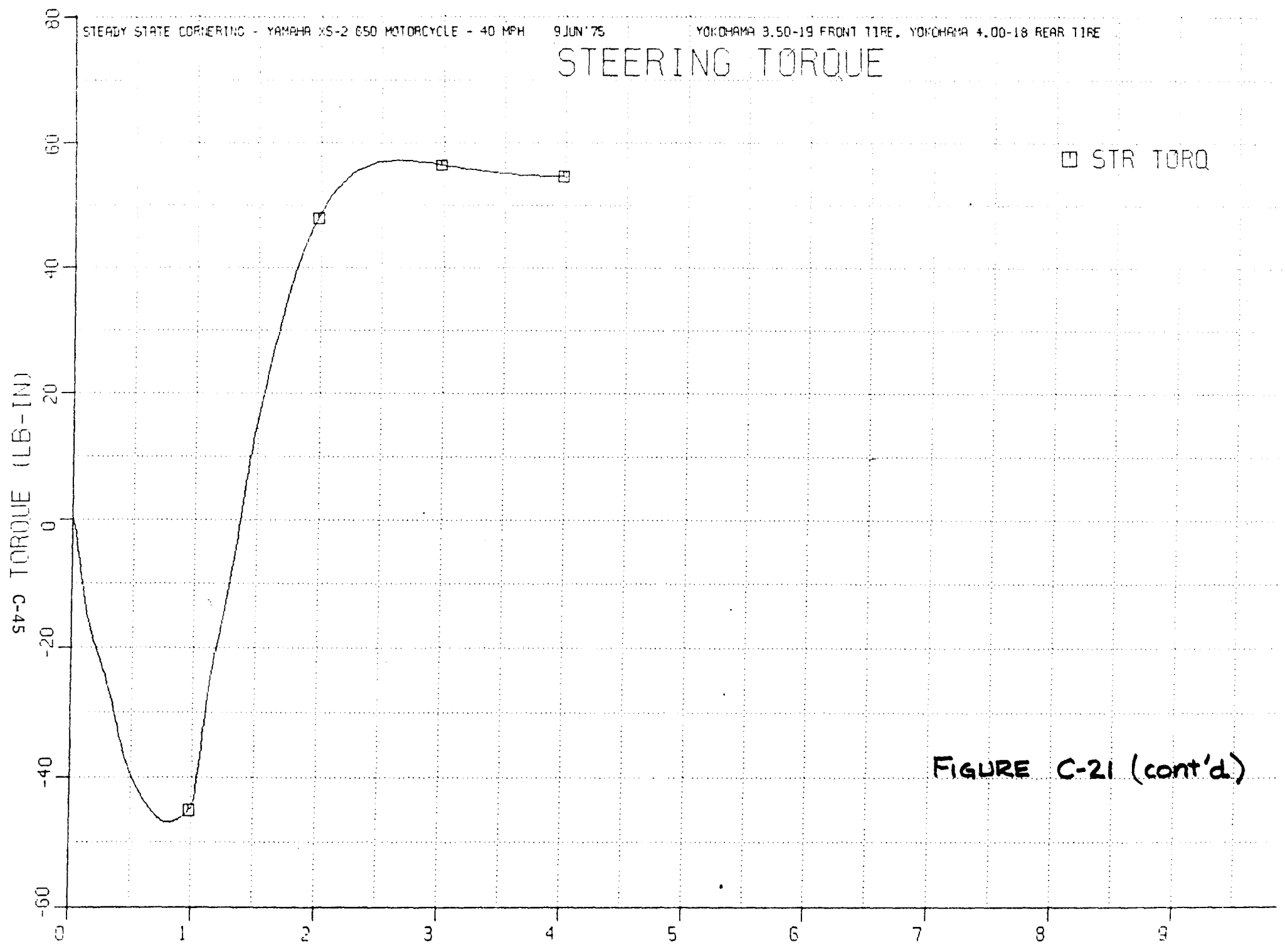


FIGURE C-21 (cont'd)

STEADY STATE CORNERING - YAMAHA XS-2 650 MOTORCYCLE - 40 MPH 9 JUN '75 YOKOHAMA 3.50-19 FRONT TIRE, YOKOHAMA 4.00-18 REAR TIRE

# STEERING TORQUE

□ STR TORQ

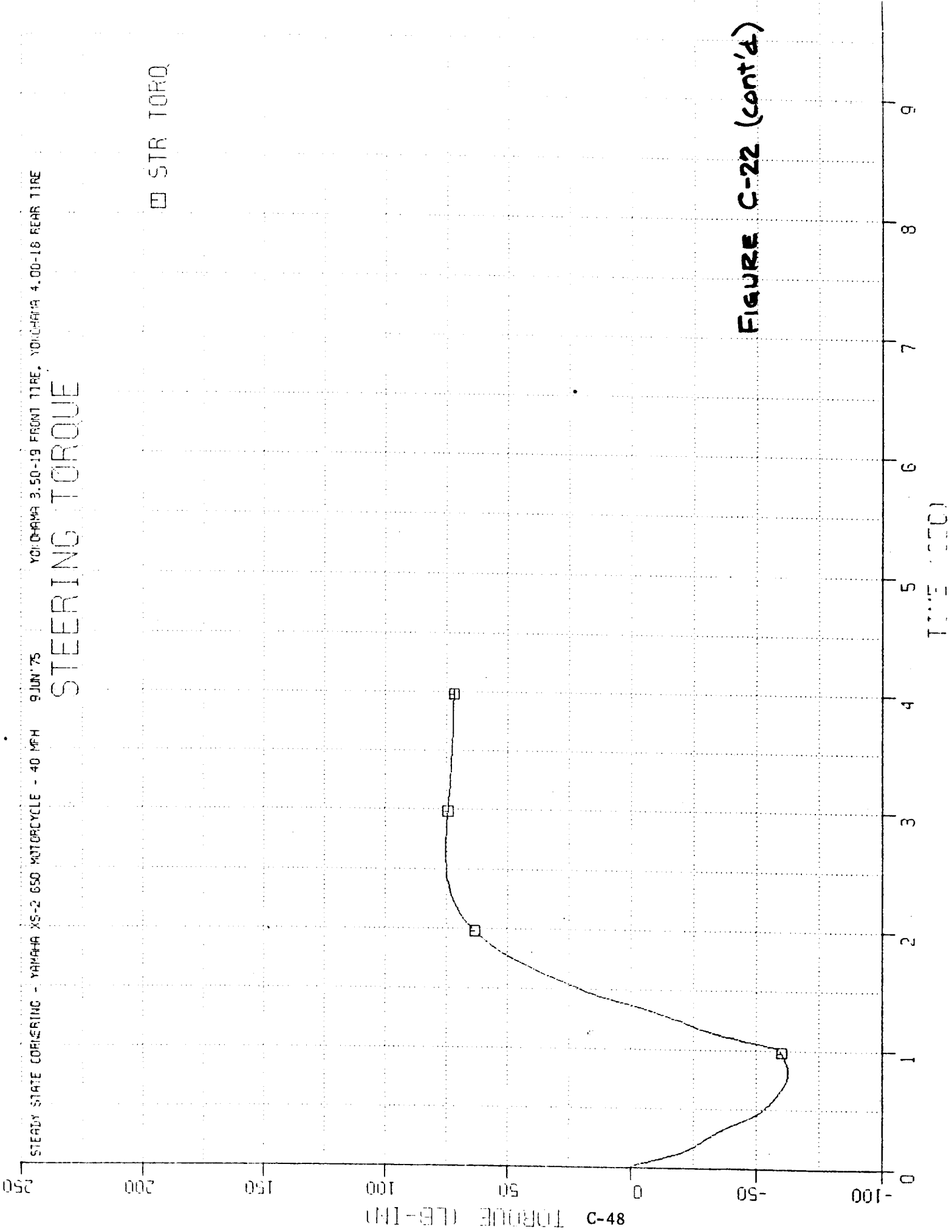


FIGURE C-22 (cont'd)

STEADY STATE CORNERING -- YAMAHA XS-2 650 MOTORCYCLE - 40 MPH 9 JUN '75

YOKOHAMA 3.50-19 FRONT TIRE. YOKOHAMA 4.00-16 REAR TIRE

# STEER AND ROLL ANGLES

- ROLL
- STR ANG
- △ COM ROLL

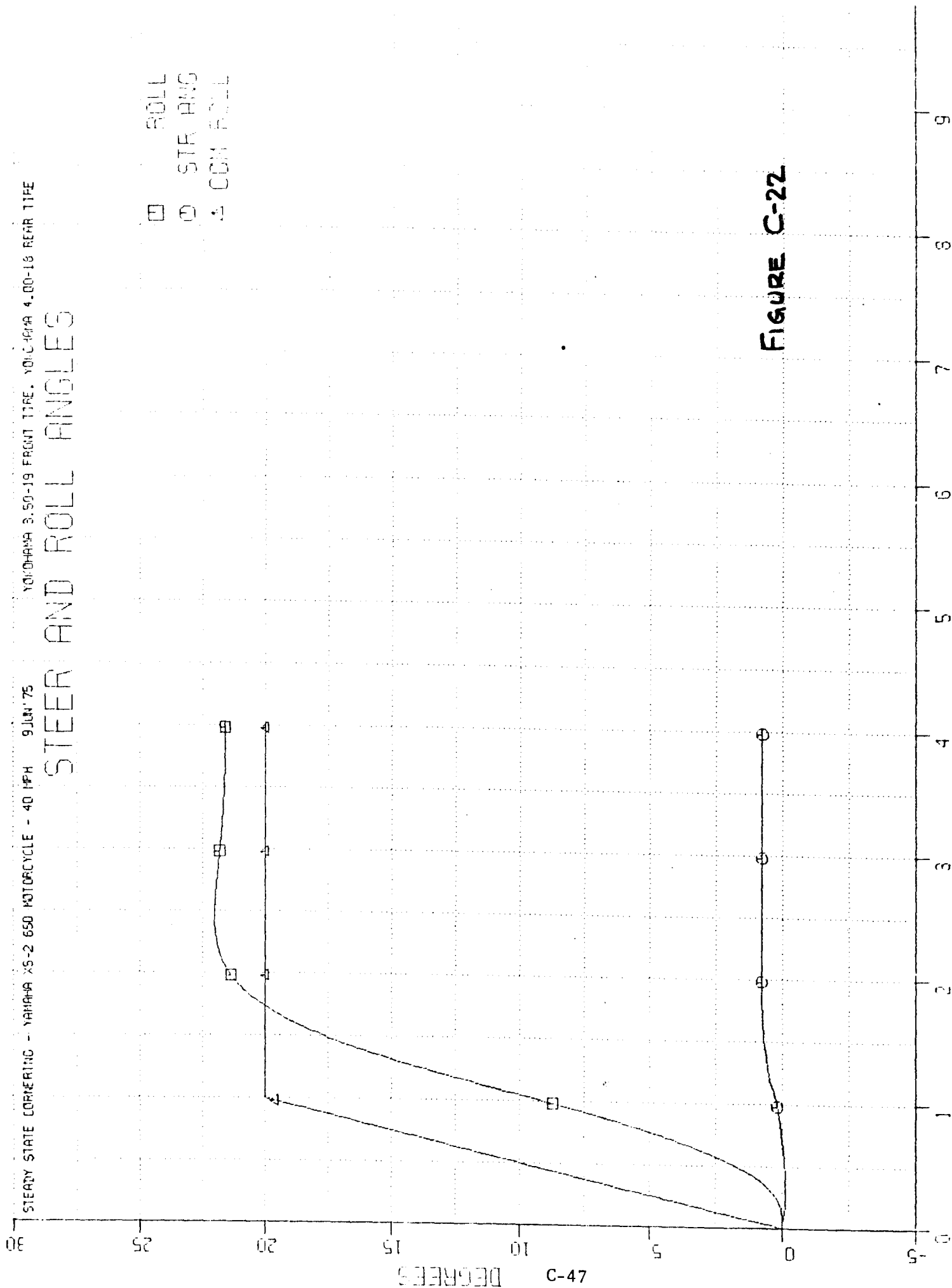


FIGURE C-22

STEADY STATE CORNERING - YAMAHA XS-2 650 MOTORCYCLE - 40 MPH 9 JUN '75

YOKOHAMA 3.50-19 FRONT TIRE, YOKOHAMA 4.00-18 REAR TIRE

# STEERING TORQUE

□ STR TORQ

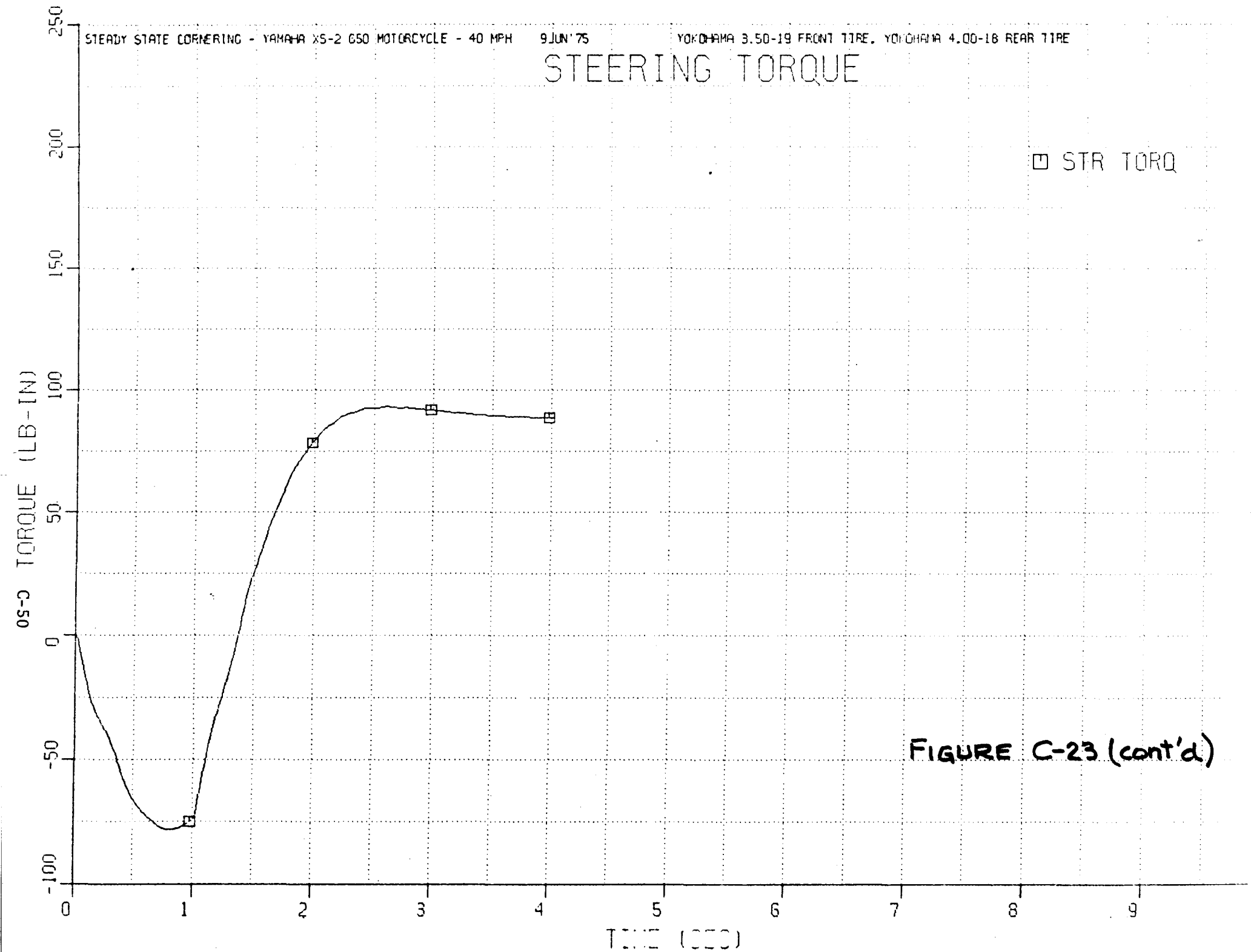


FIGURE C-23 (cont'd)

STEADY STATE CORNERING - YAMAHA XS-2 650 MOTORCYCLE - 40 MPH 9 JUN '75

YOKOHAMA 3.50-19 FRONT TIRE, YOKOHAMA 4.00-16 REAR TIRE

# STEER AND ROLL ANGLES

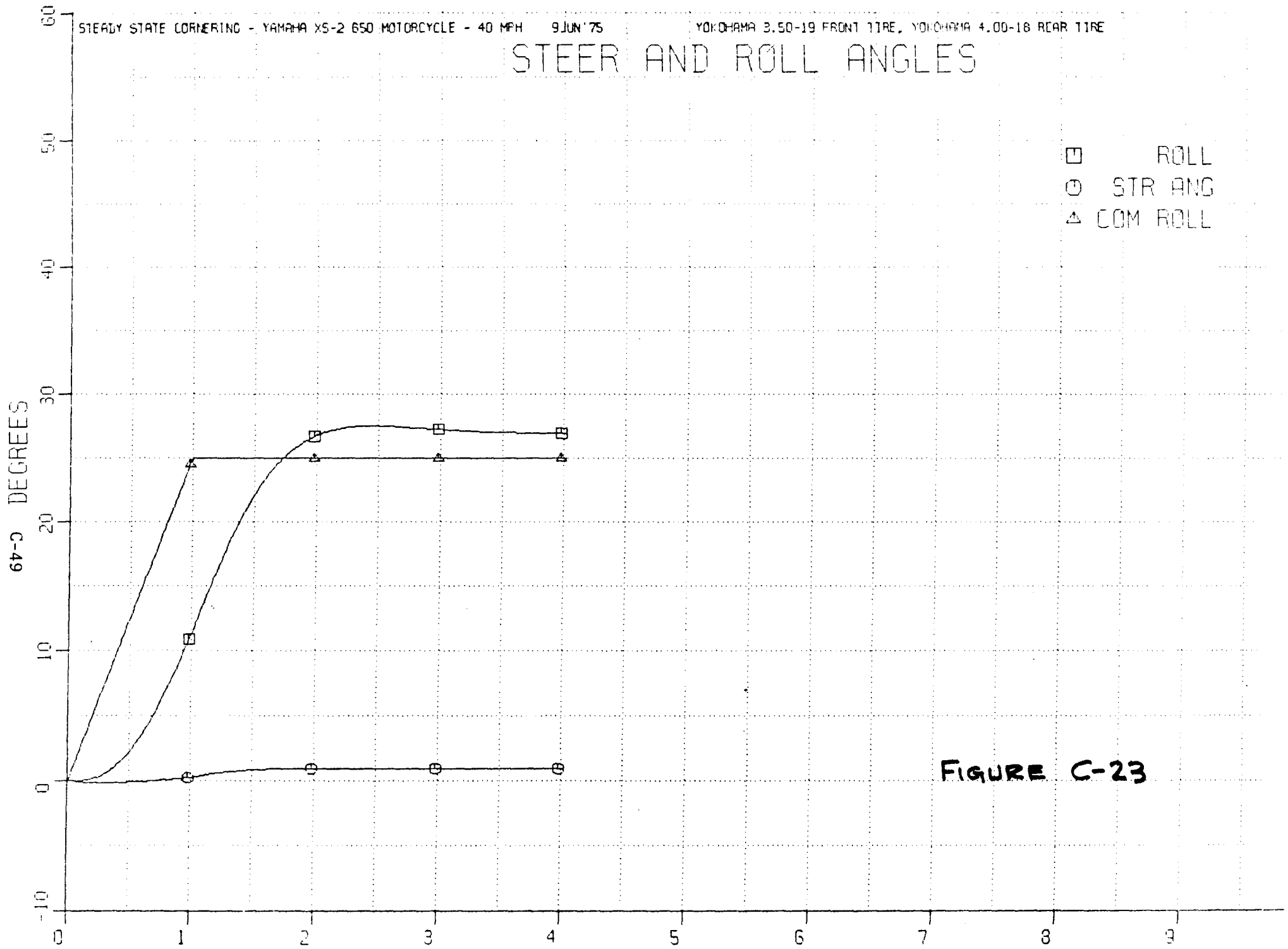
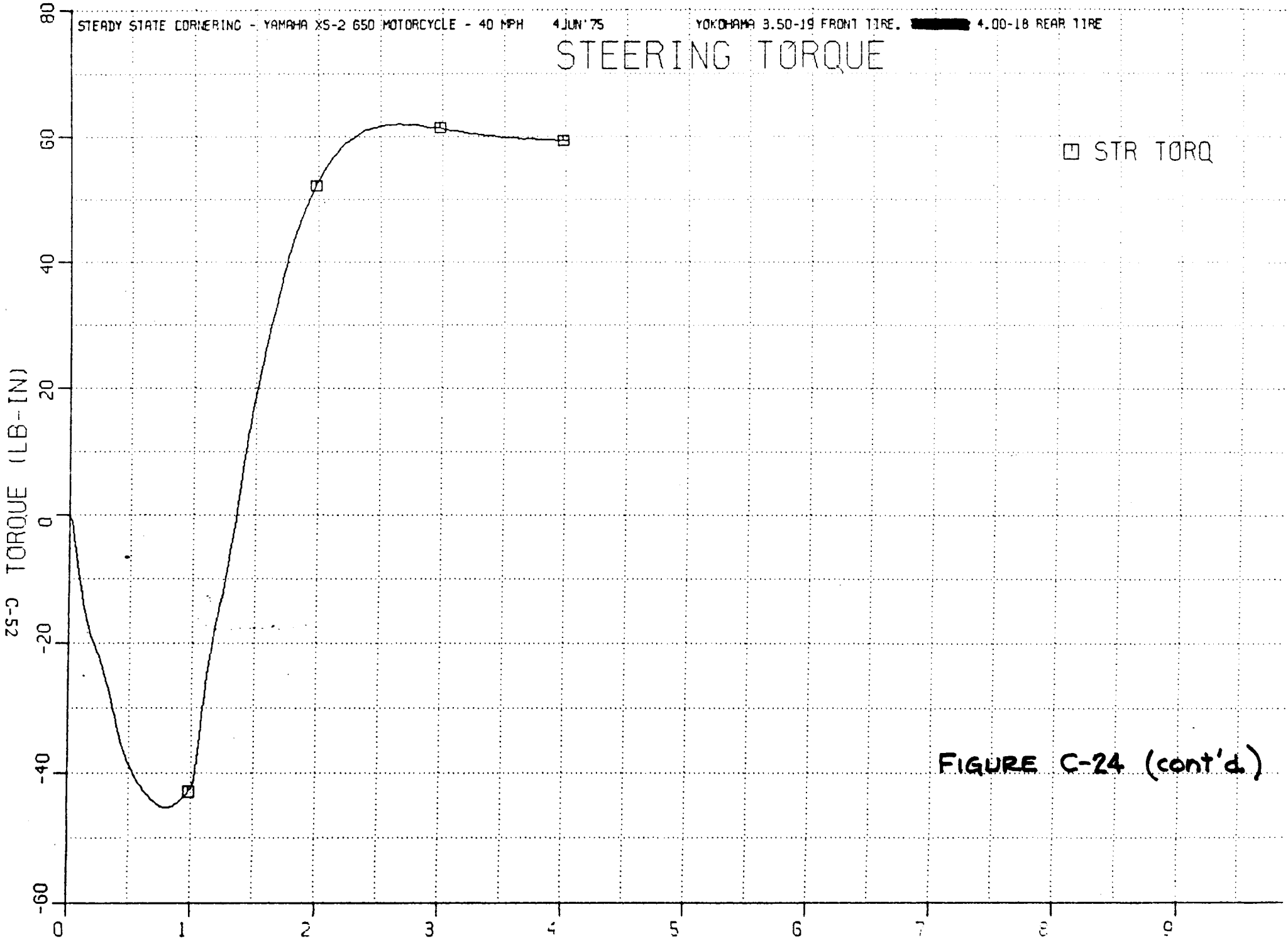


FIGURE C-23

STEADY STATE CORNERING - YAMAHA XS-2 650 MOTORCYCLE - 40 MPH 4 JUN '75

YOKOHAMA 3.50-19 FRONT TIRE. ██████████ 4.00-18 REAR TIRE

# STEERING TORQUE



□ STR TORQ

FIGURE C-24 (cont'd)

STEADY STATE CORNERING - YAMAHA X5-2 650 MOTORCYCLE - 40 MPH 4 JUN '75

YOKOHAMA 3.50-19 FRONT TIRE. ██████████ 4.00-18 REAR TIRE

# STEER AND ROLL ANGLES

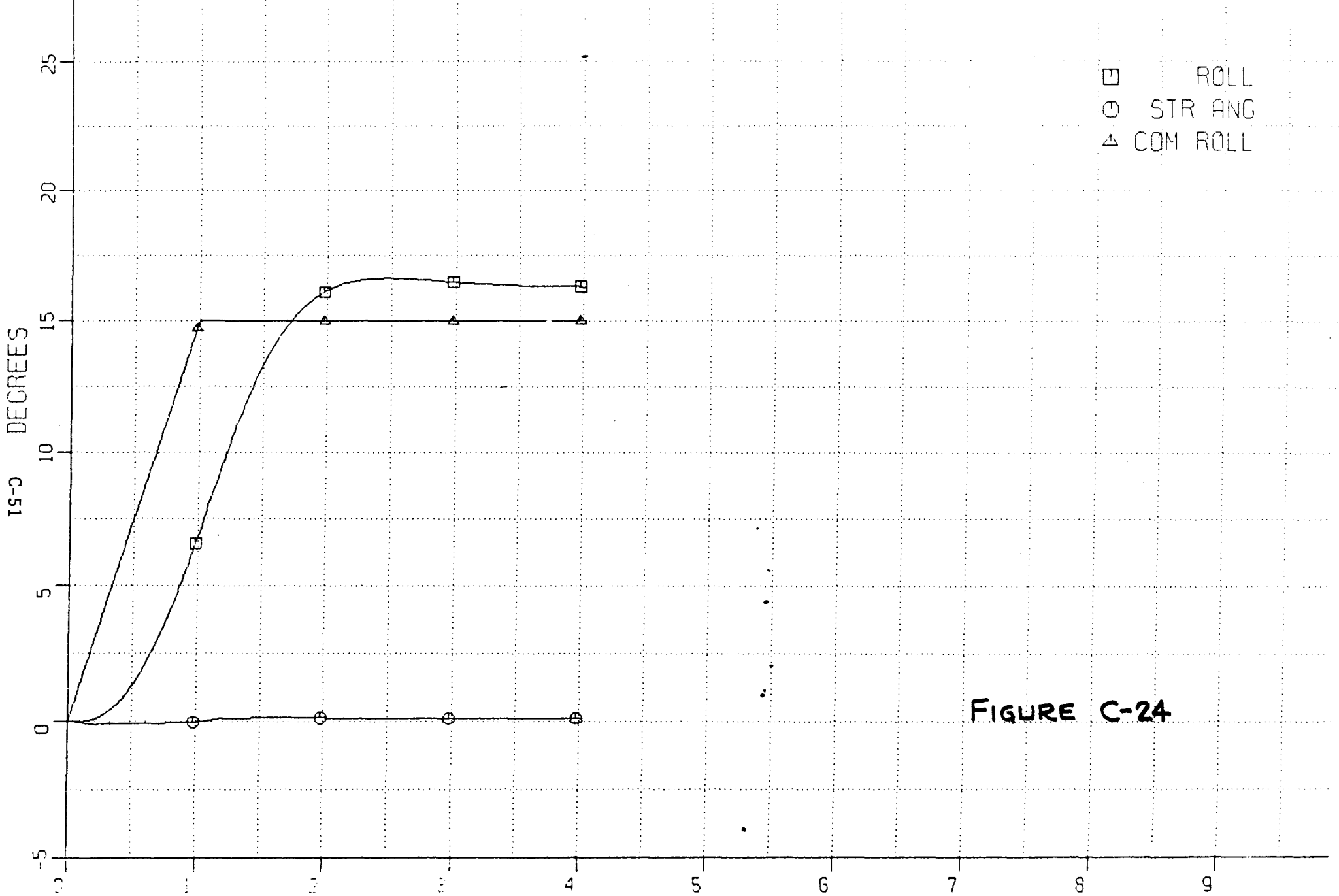


FIGURE C-24

STEADY STATE CORNERING - YAMAHA XS-2 650 MOTORCYCLE - 40 MPH 4 JUN '75

YOKOHAMA 3.50-19 FRONT TIRE, ██████████ 4.00-18 REAR TIRE

# STEERING TORQUE

□ STR TORQ

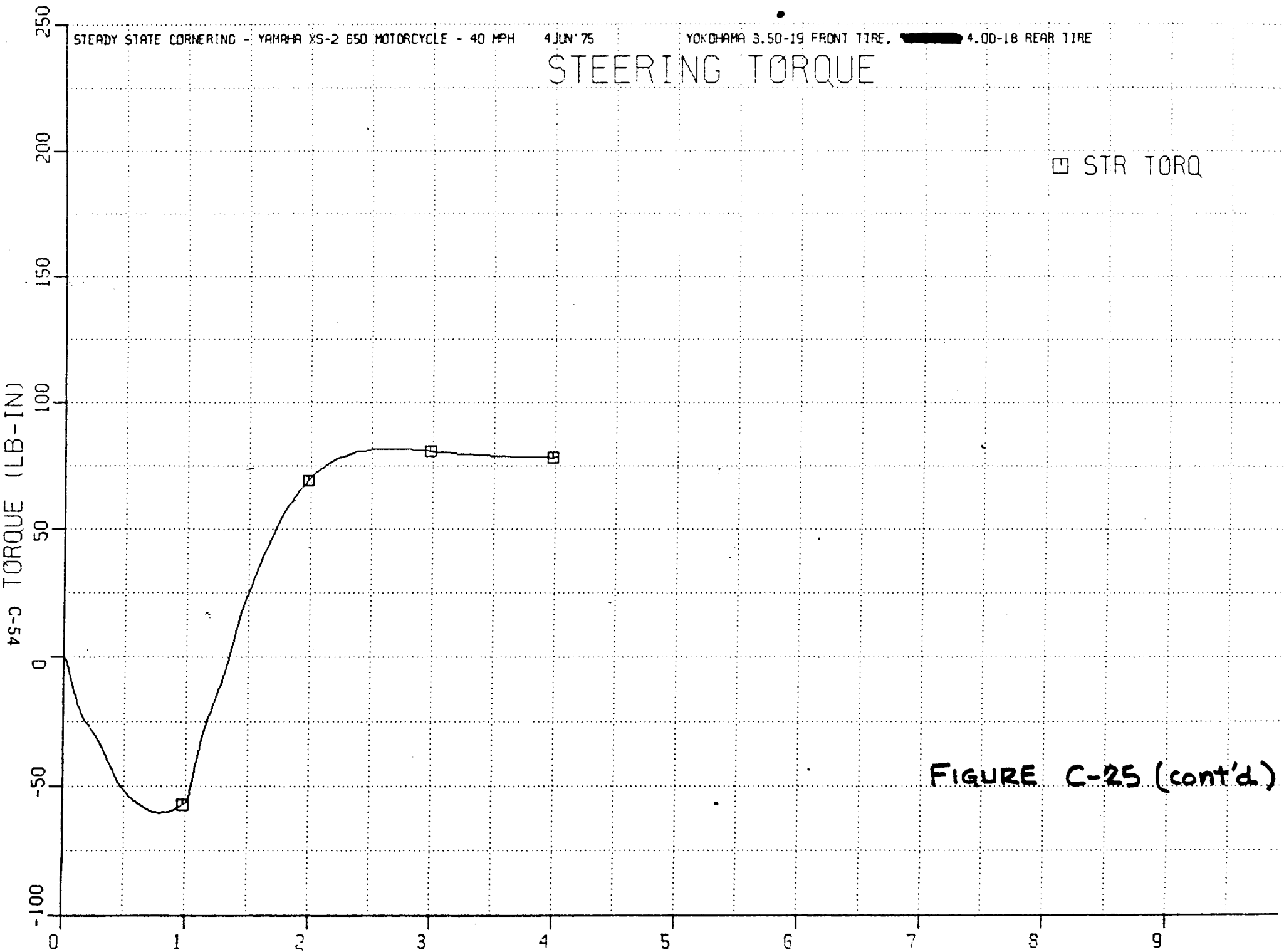


FIGURE C-25 (cont'd.)



STEADY STATE CORNERING - YAMAHA XS-2 650 MOTORCYCLE - 40 MPH 4 JUN 75 YOKOHAMA 3.50-19 FRONT TIRE, 4.00-16 REAR TIRE

# STEER AND ROLL ANGLES

- ROLL
- STR ANG
- △ COM ROLL

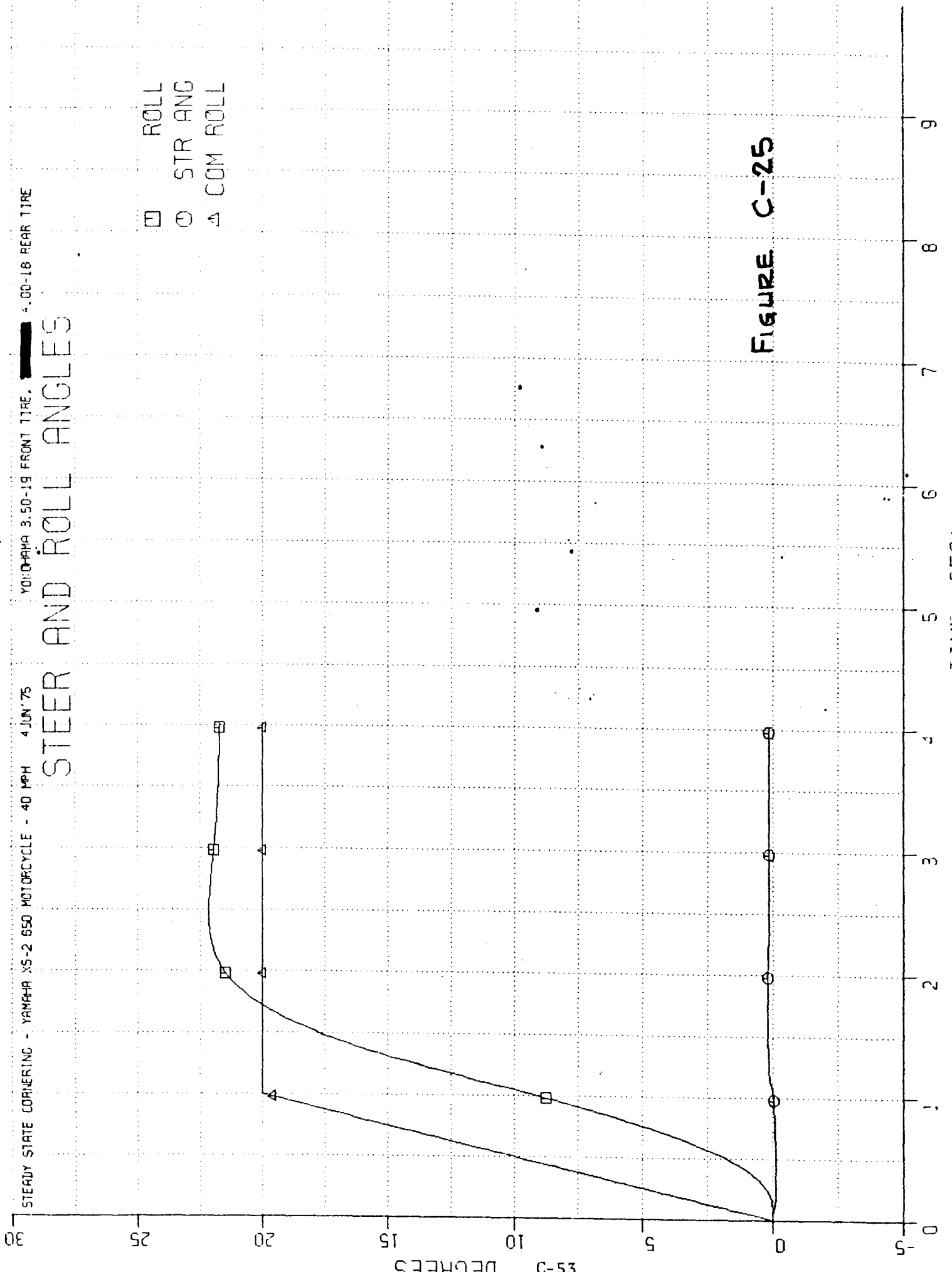


FIGURE C-25

STEADY STATE CORNERING - YAMAHA XS-2 650 MOTORCYCLE - 40 MPH

4 JUN '75

YOKOHAMA 3.50-19 FRONT TIRE, ██████████ 4.00-18 REAR TIRE

# STEERING TORQUE

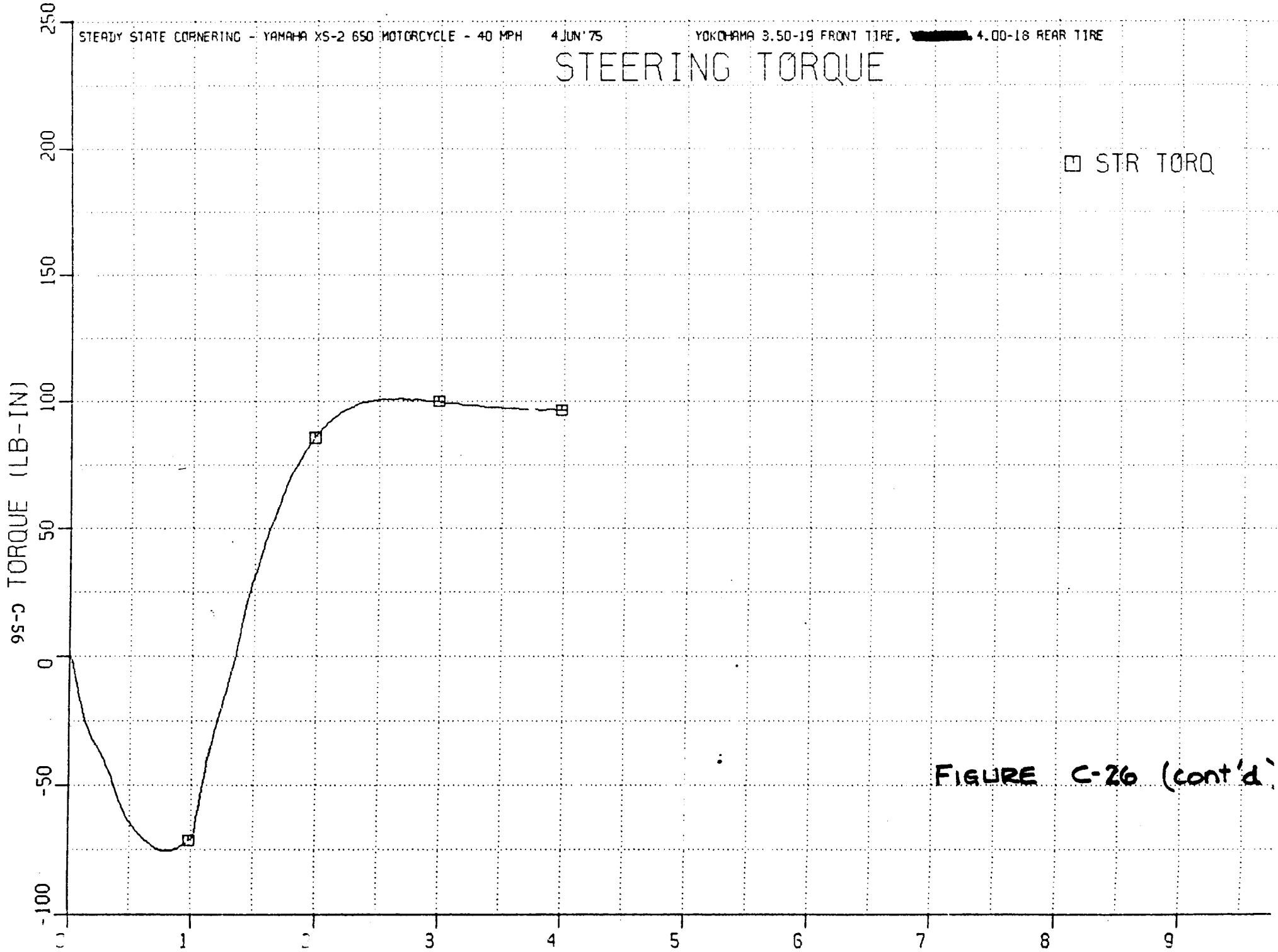


FIGURE C-26 (cont'd)

STEADY STATE CORNERING - YAMAHA XS-2 650 MOTORCYCLE - 40 MPH 4 JUN '75

YOKOHAMA 3.50-19 FRONT TIRE. ██████████ 4.00-18 REAR TIRE

# STEER AND ROLL ANGLES

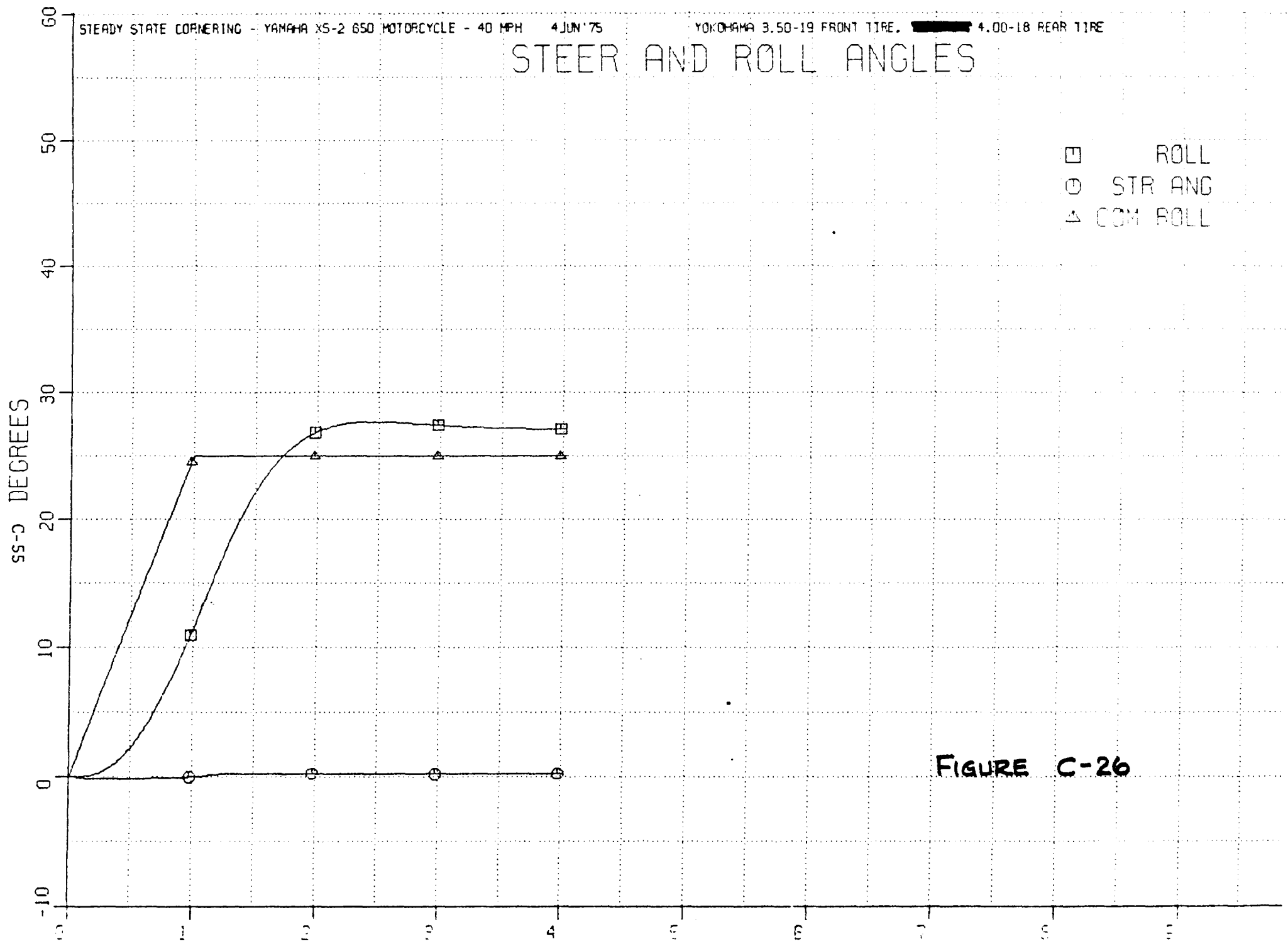


FIGURE C-26

STEADY STATE CORNERING - YAMAHA XS-2 650 MOTORCYCLE - 60 MPH 6 JUN '75 YOKOHAMA 3.50-19 FRONT TIRE, YOKOHAMA 4.00-18 REAR TIRE

# STEERING TORQUE

□ STR TORQ

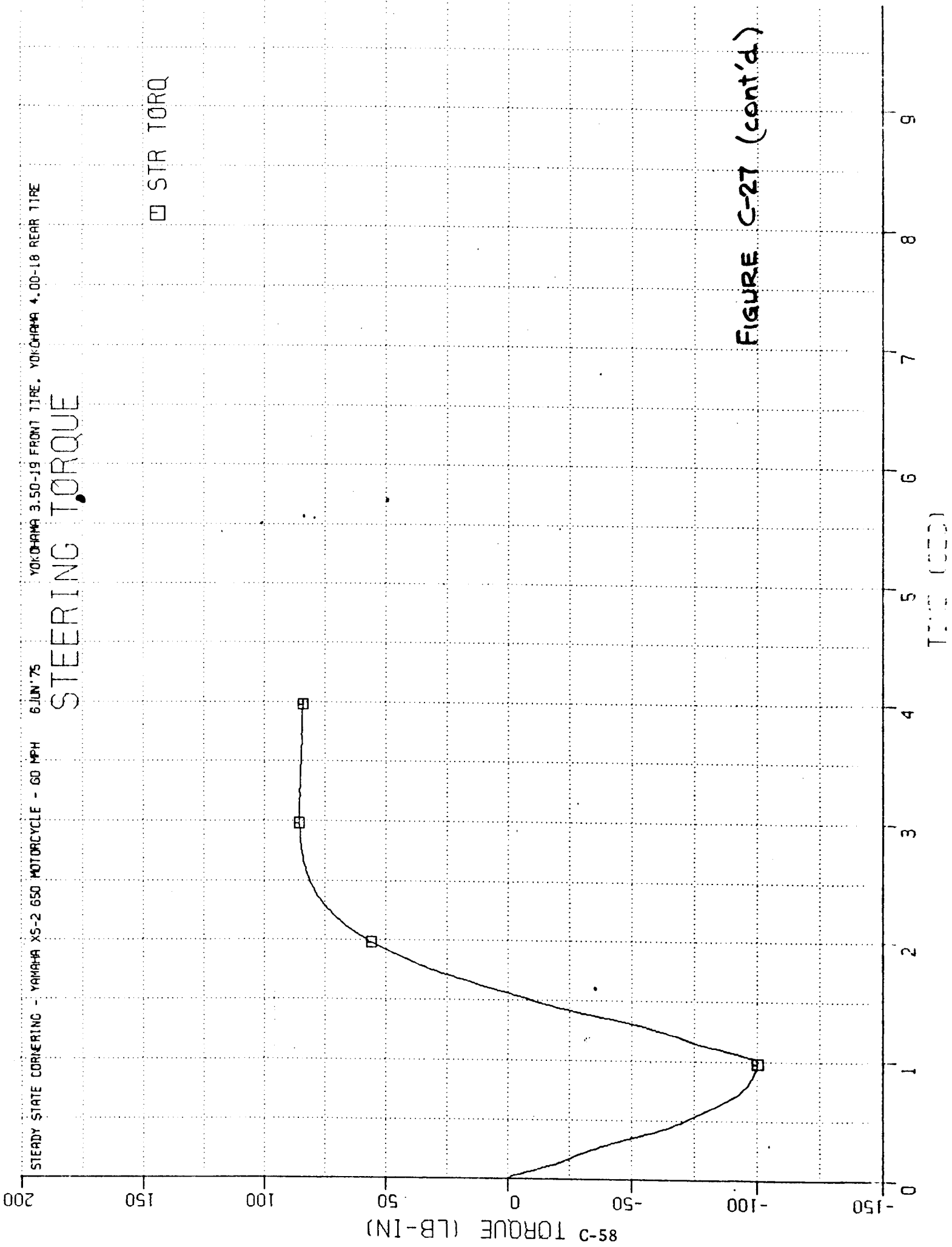


FIGURE C-27 (cont'd)

STEADY STATE CORNERING - YAMAHA XS-2 650 MOTORCYCLE - 60 MPH 6 JUN '75

YOKOHAMA 3.50-19 FRONT TIRE, YOKOHAMA 4.00-18 REAR TIRE

# STEER AND ROLL ANGLES

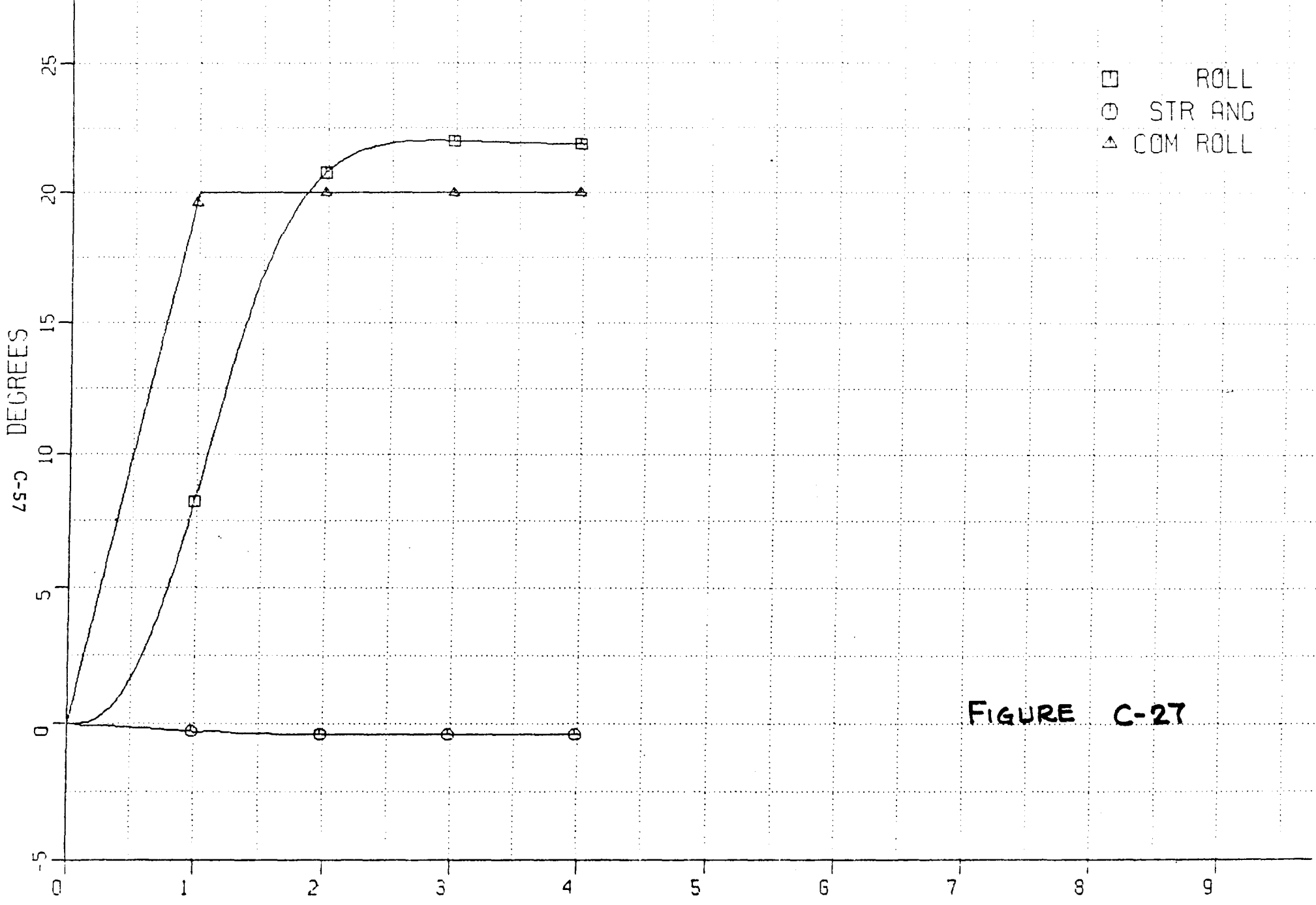


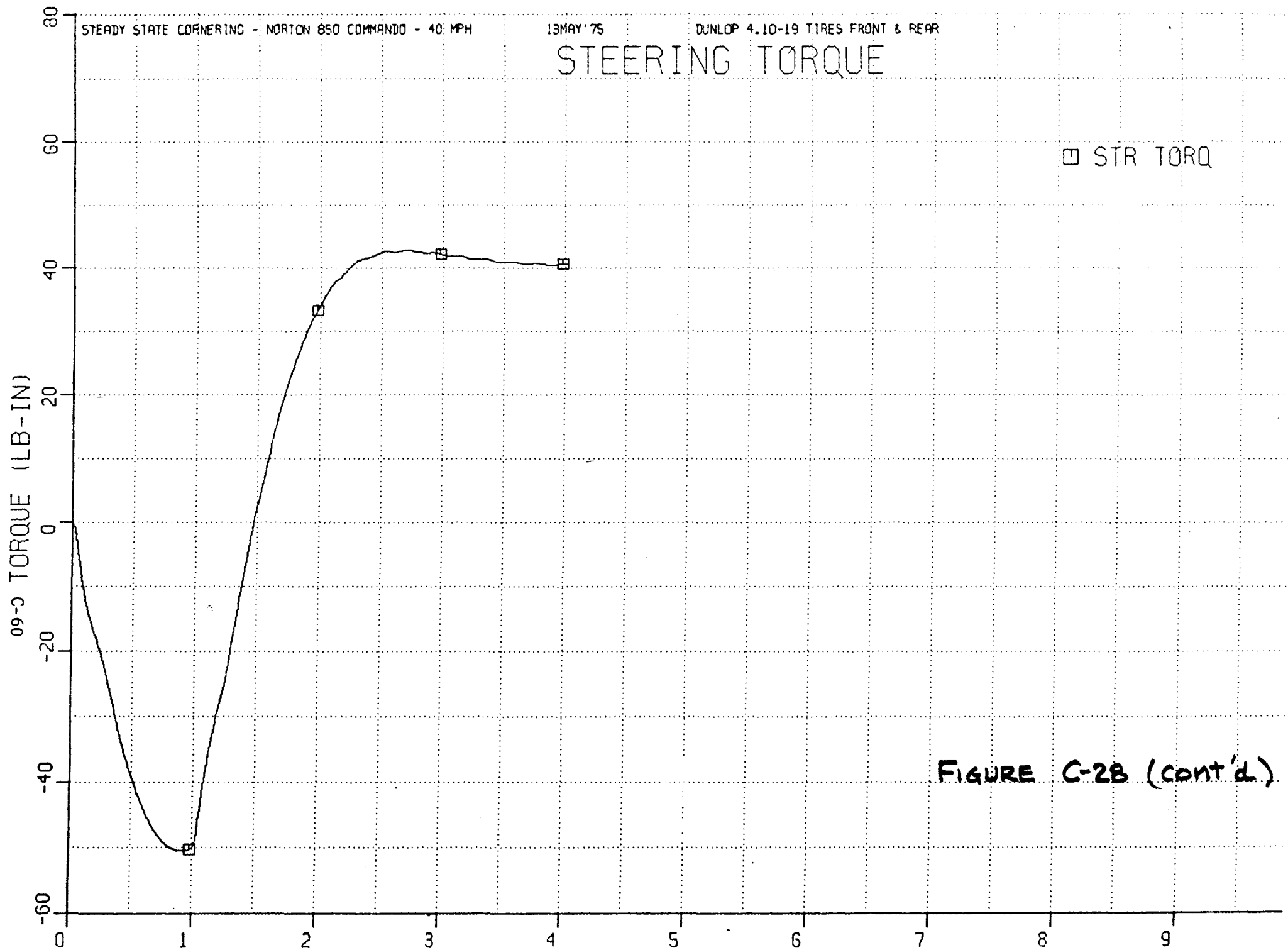
FIGURE C-27

STEADY STATE CORNERING - NORTON 850 COMMANDO - 40 MPH

13MAY'75

DUNLOP 4.10-19 TIRES FRONT & REAR

# STEERING TORQUE



□ STR TORQ

FIGURE C-28 (cont'd)

STEADY STATE CORNERING - NORTON 850 COMMANDO - 40 MPH

13MAY '75

DUNLOP 4.10-19 TIRES FRONT & REAR

# STEER AND ROLL ANGLES

65-0 DEGREES

- ROLL
- STR ANG
- △ COM ROLL

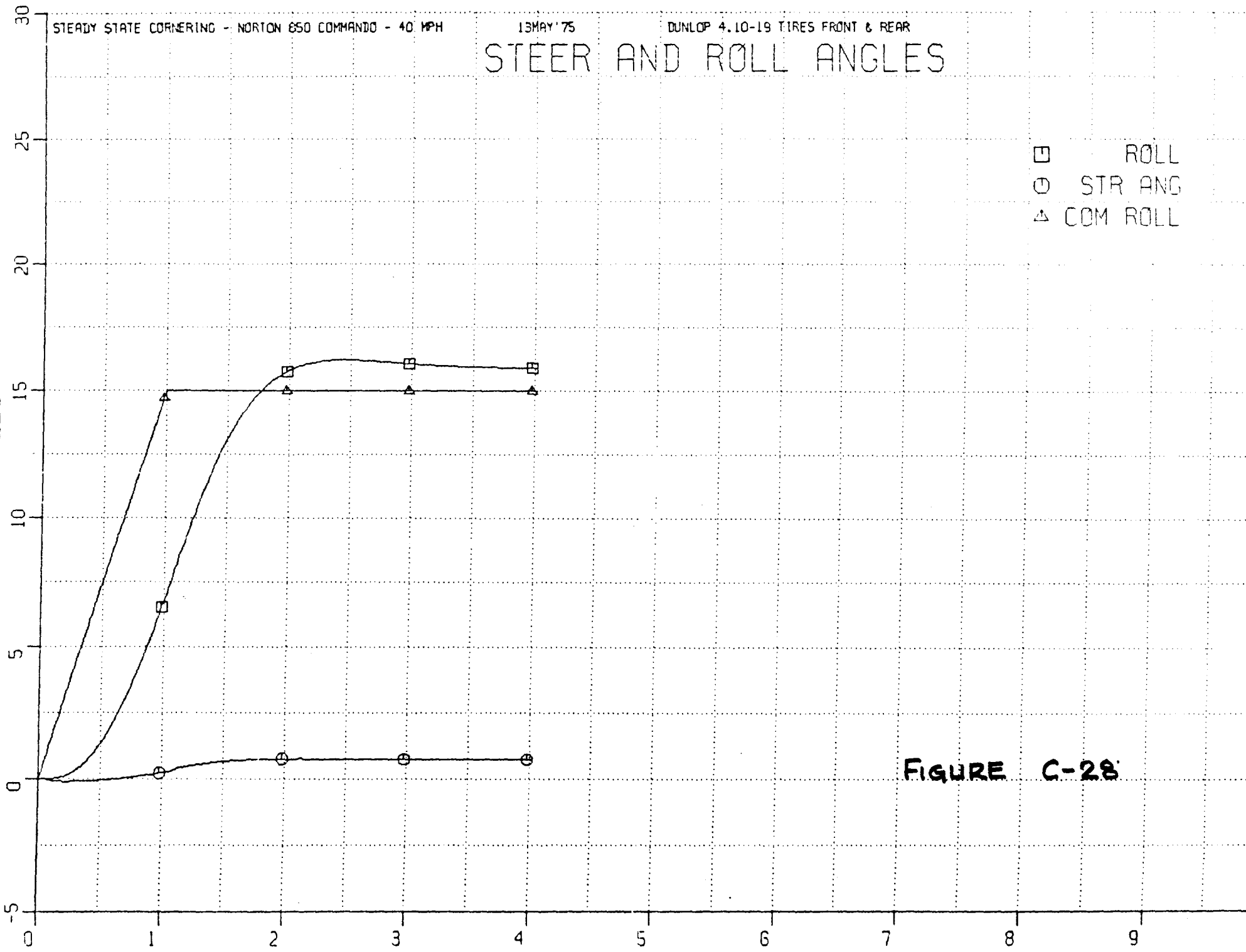


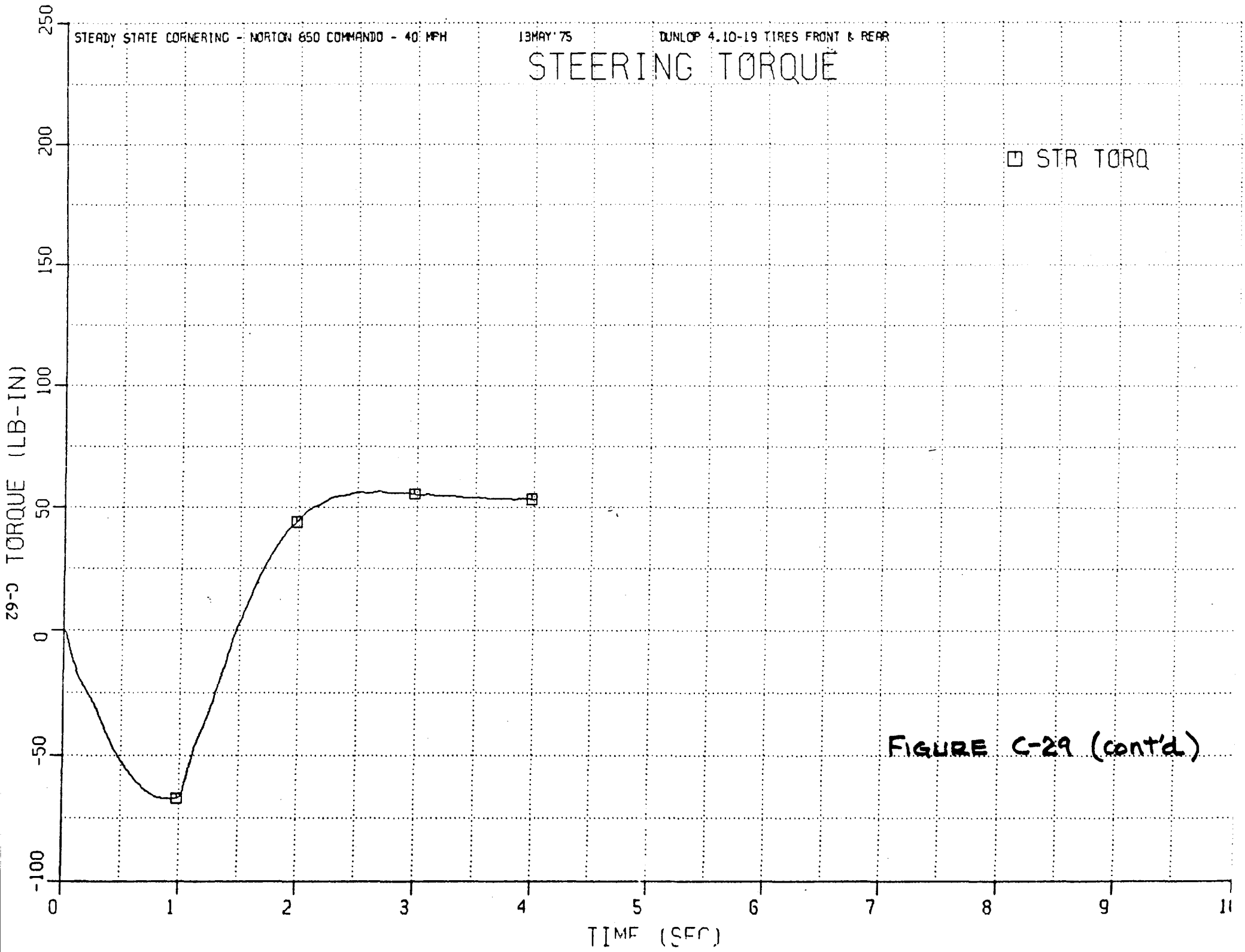
FIGURE C-28

STEADY STATE CORNERING - NORTON 650 COMMANDO - 40 MPH

13MAY 75

DUNLOP 4.10-19 TIRES FRONT & REAR

# STEERING TORQUE



□ STR TORQ

FIGURE C-29 (cont'd)



STEADY STATE CORNERING - NORTON 850 COMMANDO - 40 MPH

13MAY'75

DUNLOP 4.10-19 TIRES FRONT & REAR

# STEER AND ROLL ANGLES

□ ROLL  
○ STR ANG  
△ COM ROLL

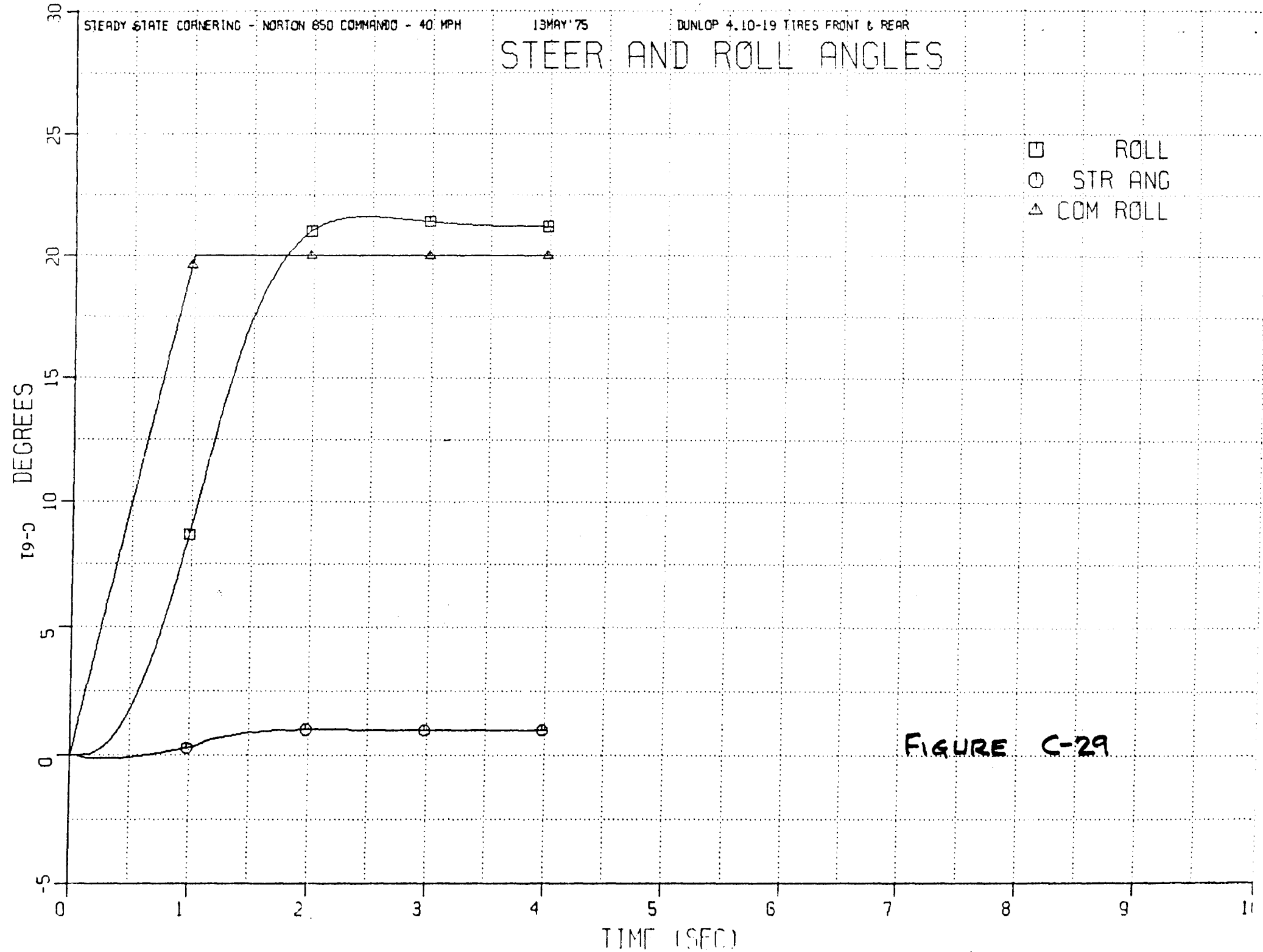


FIGURE C-29

STEADY STATE CORNERING - NORTON 850 COMMANDO - 40 MPH

13 MAY '75

DUNLOP 4.10-19 TIRES FRONT & REAR

# STEERING TORQUE

□ STR TORQ

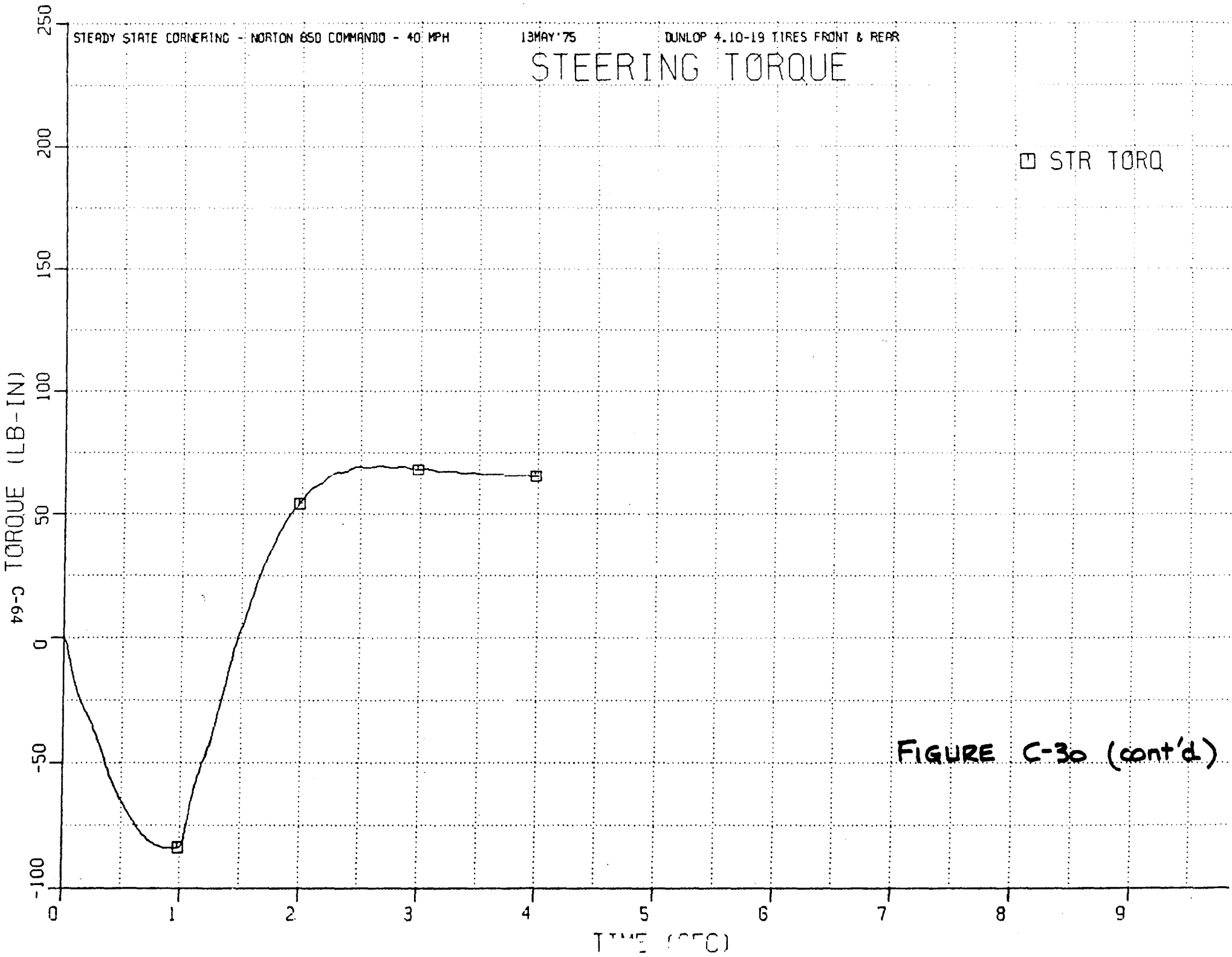


FIGURE C-30 (cont'd)

STEADY STATE CORNERING - NORTON 850 COMMANDO - 40 MPH

13MAY '75

DUNLOP 4.10-19 TIRES FRONT & REAR

# STEER AND ROLL ANGLES

- ROLL
- STR ANG
- △ COM ROLL

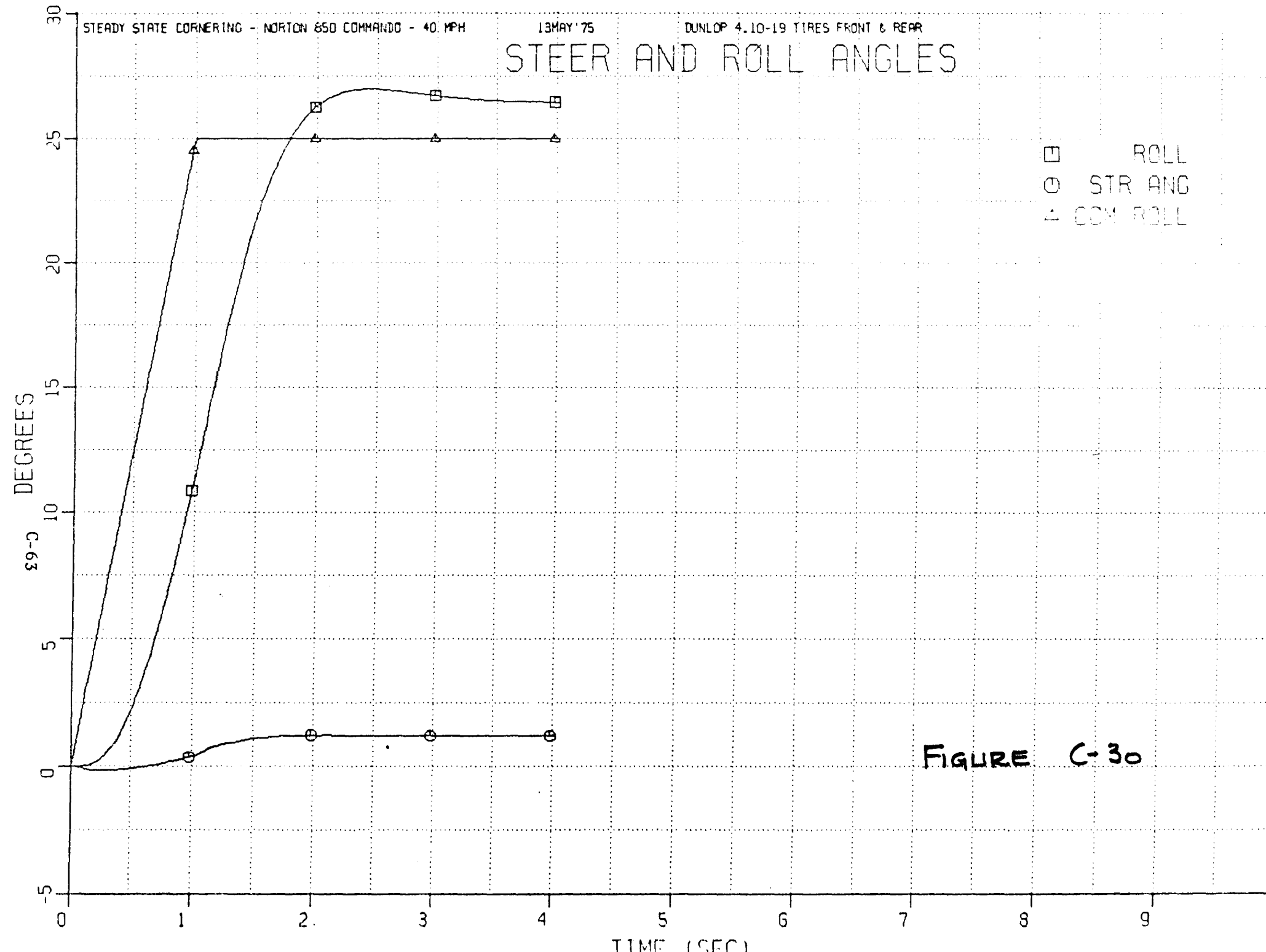


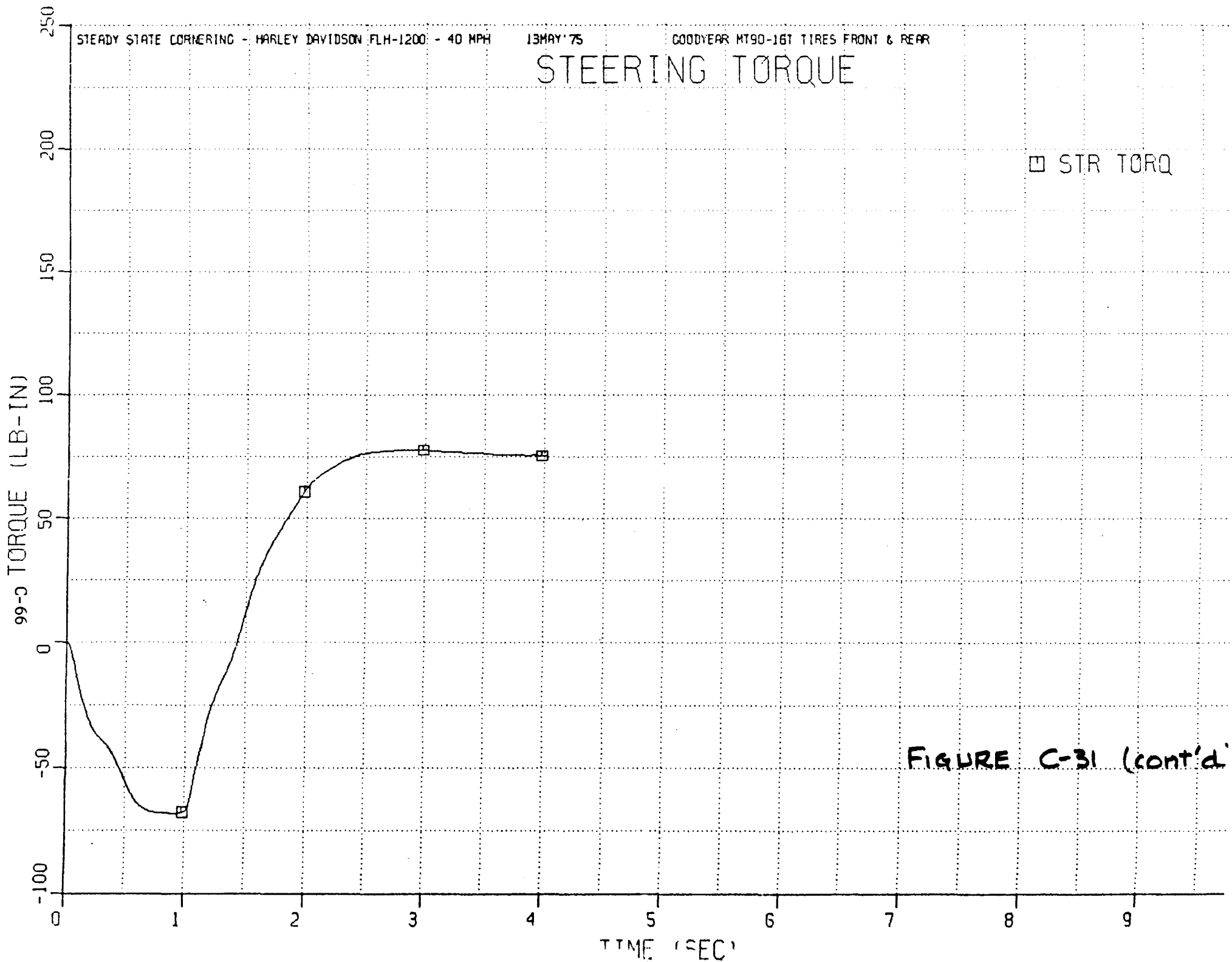
FIGURE C-30

STEADY STATE CORNERING - HARLEY DAVIDSON FLH-1200 - 40 MPH

13 MAY '75

GOODYEAR MT90-16T TIRES FRONT & REAR

# STEERING TORQUE



□ STR TORQ

FIGURE C-31 (cont'd)

STEADY STATE CORNERING - HARLEY DAVIDSON FLH-1200 - 40 MPH

13MAY '75

GOODYEAR MT90-16T TIRES FRONT & REAR

# STEER AND ROLL ANGLES

- ROLL
- STR ANG
- △ COM ROLL

DEGREES

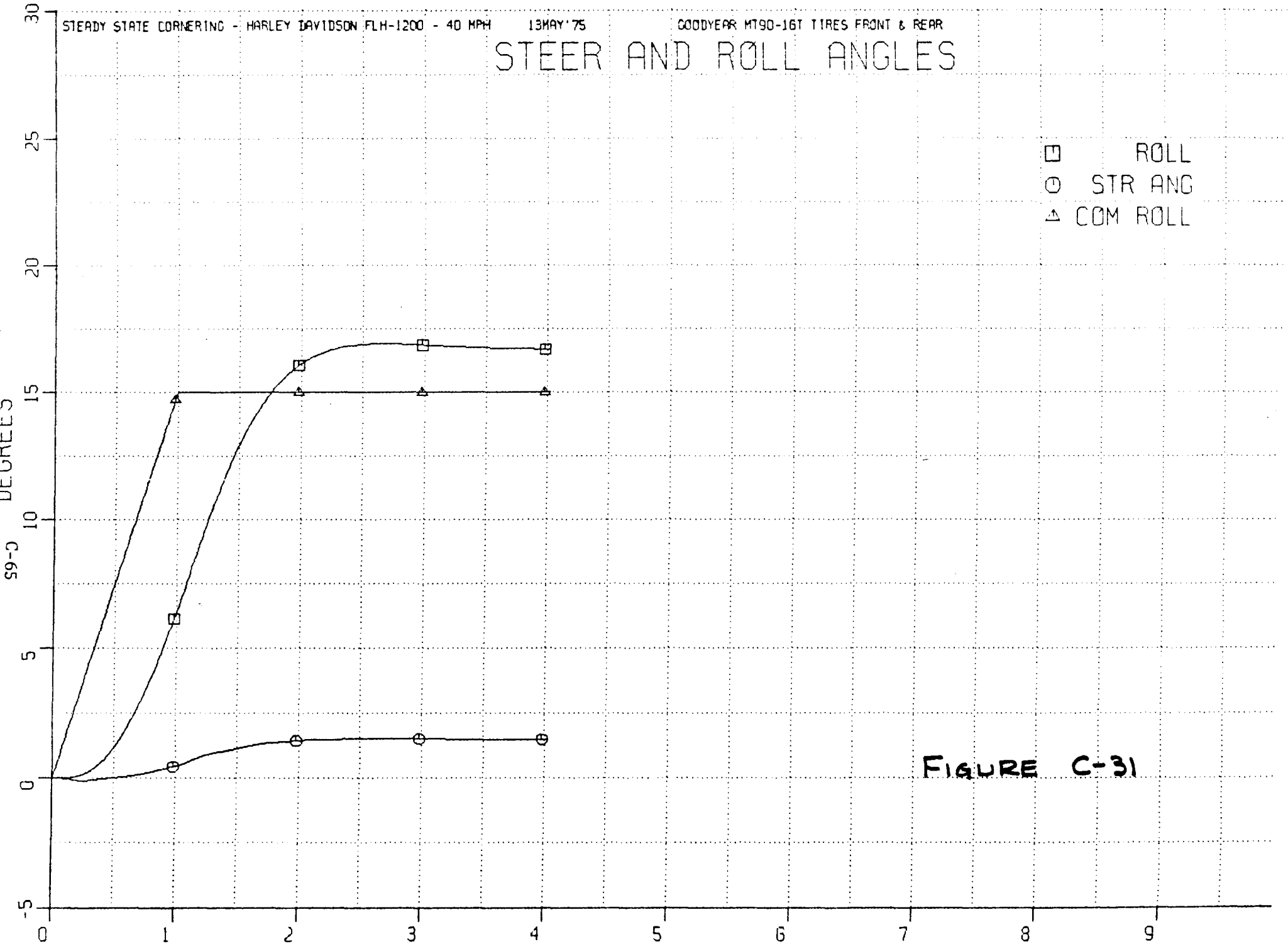


FIGURE C-31

STEADY STATE CORNERING - HARLEY DAVIDSON FLH-1200 - 40 MPH

13 MAY '75

GOODYEAR MT90-16T TIRES FRONT & REAR

# STEERING TORQUE

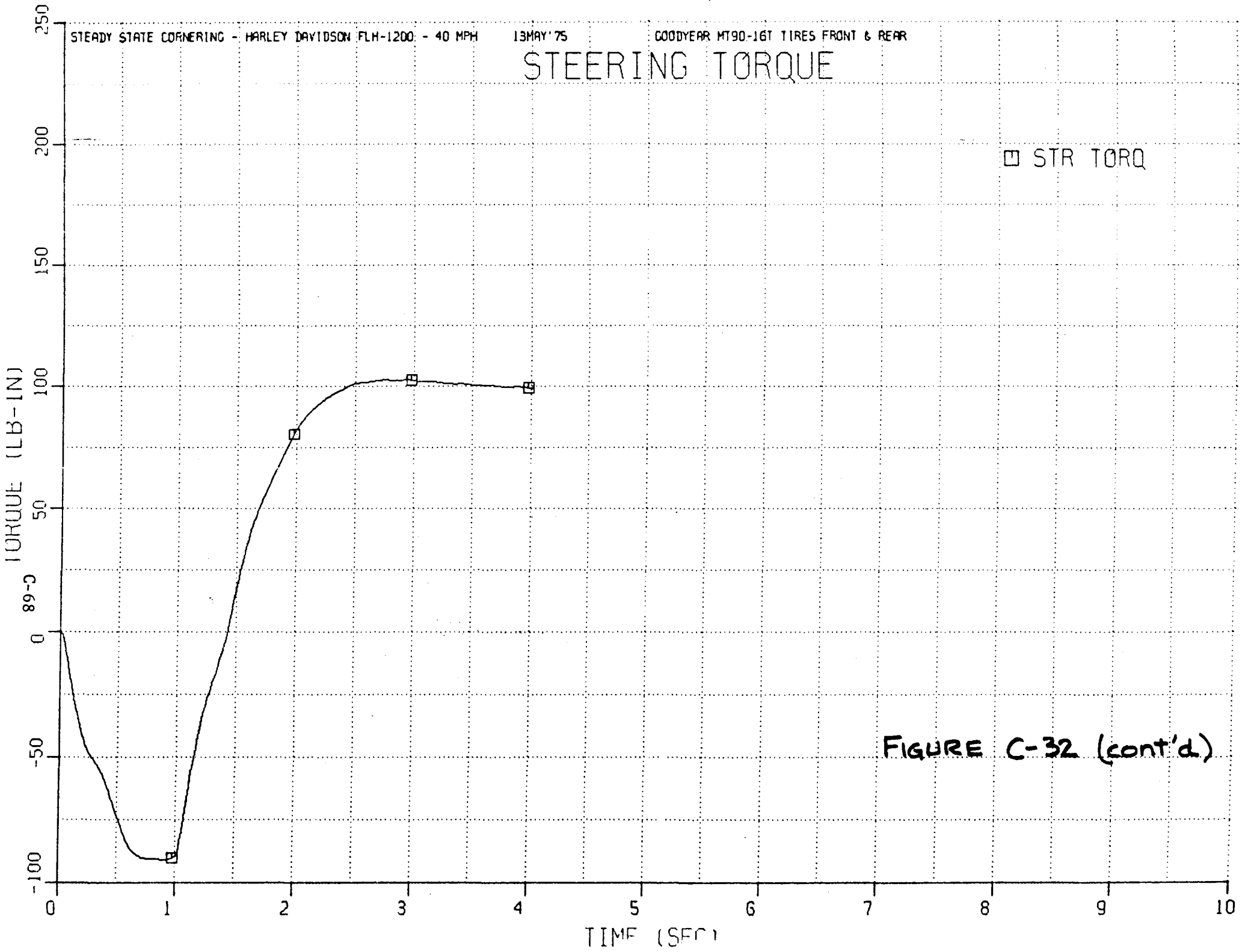


FIGURE C-32 (cont'd)

STEADY STATE CORNERING - HARLEY DAVIDSON FLH-1200 - 40 MPH

13 MAY '75

GOODYEAR MT90-16T TIRES FRONT & REAR

# STEER AND ROLL ANGLES

- ROLL
- STR ANG
- △ COM ROLL

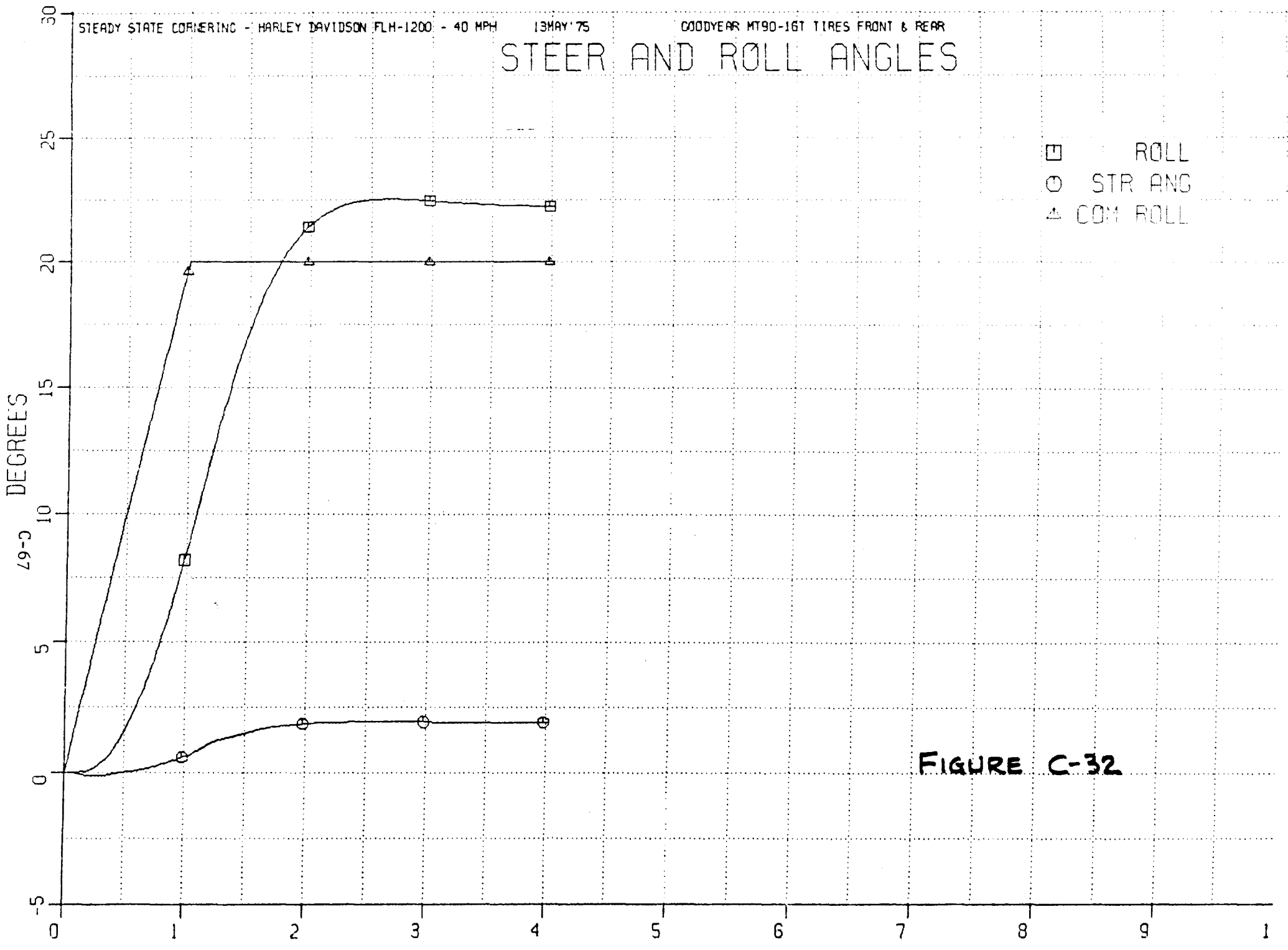


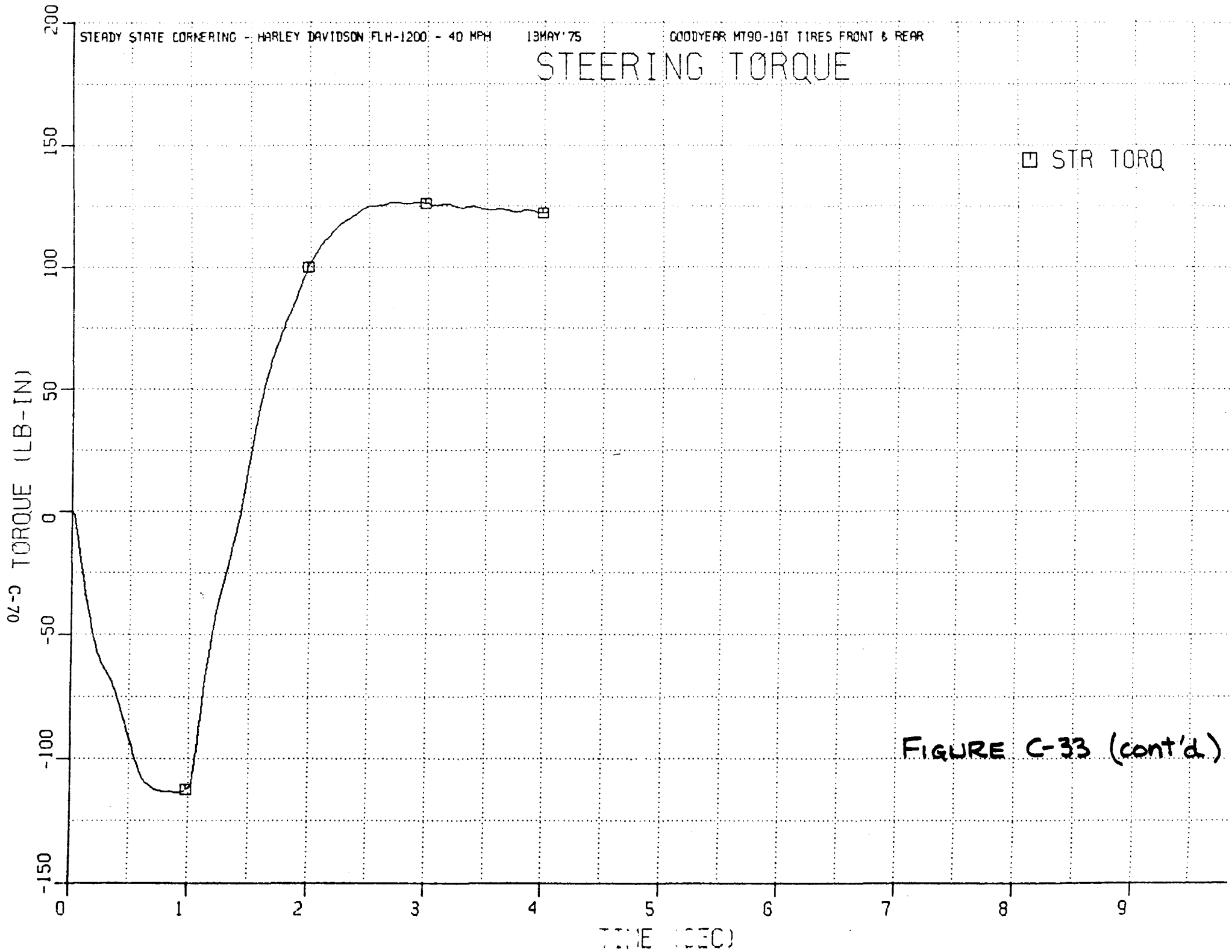
FIGURE C-32

STEADY STATE CORNERING - HARLEY DAVIDSON FLH-1200 - 40 MPH

13 MAY '75

GOODYEAR MT90-16T TIRES FRONT & REAR

# STEERING TORQUE



□ STR TORQ

FIGURE C-33 (cont'd)

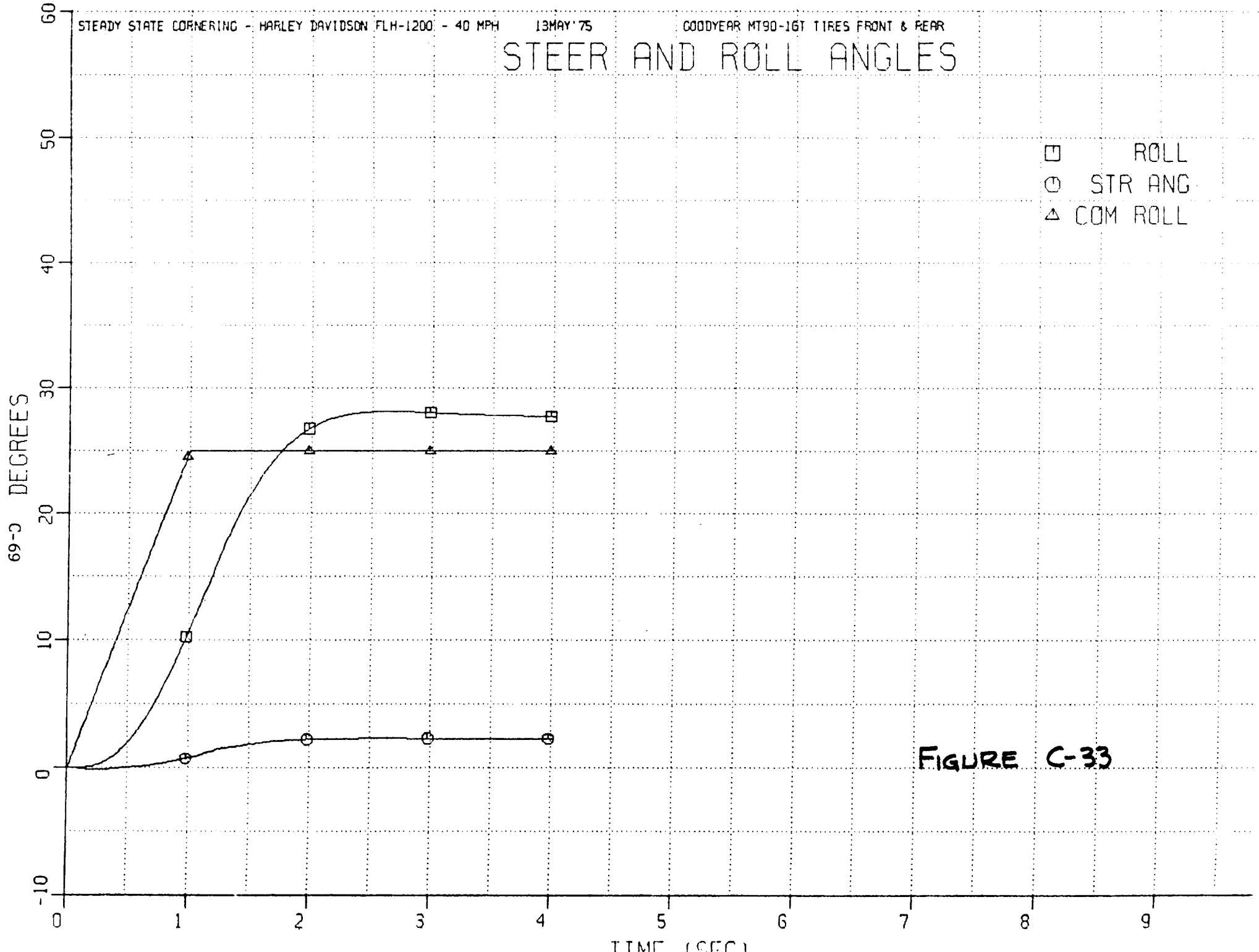


STEADY STATE CORNERING - HARLEY DAVIDSON FLH-1200 - 40 MPH

13 MAY '75

GOODYEAR MT90-16T TIRES FRONT & REAR

# STEER AND ROLL ANGLES



- ROLL
- STR ANG
- △ COM ROLL

FIGURE C-33

MOTORCYCLE STEADY STATE CORNERING (140 MPH)

29 JAN '75

HARLEY DAVIDSON FLH-1200 ELECTRA GLIDE

# STEER AND ROLL ANGLES

C-72  
DEGREES

- ROLL
- STR ANG
- △ COM ROLL

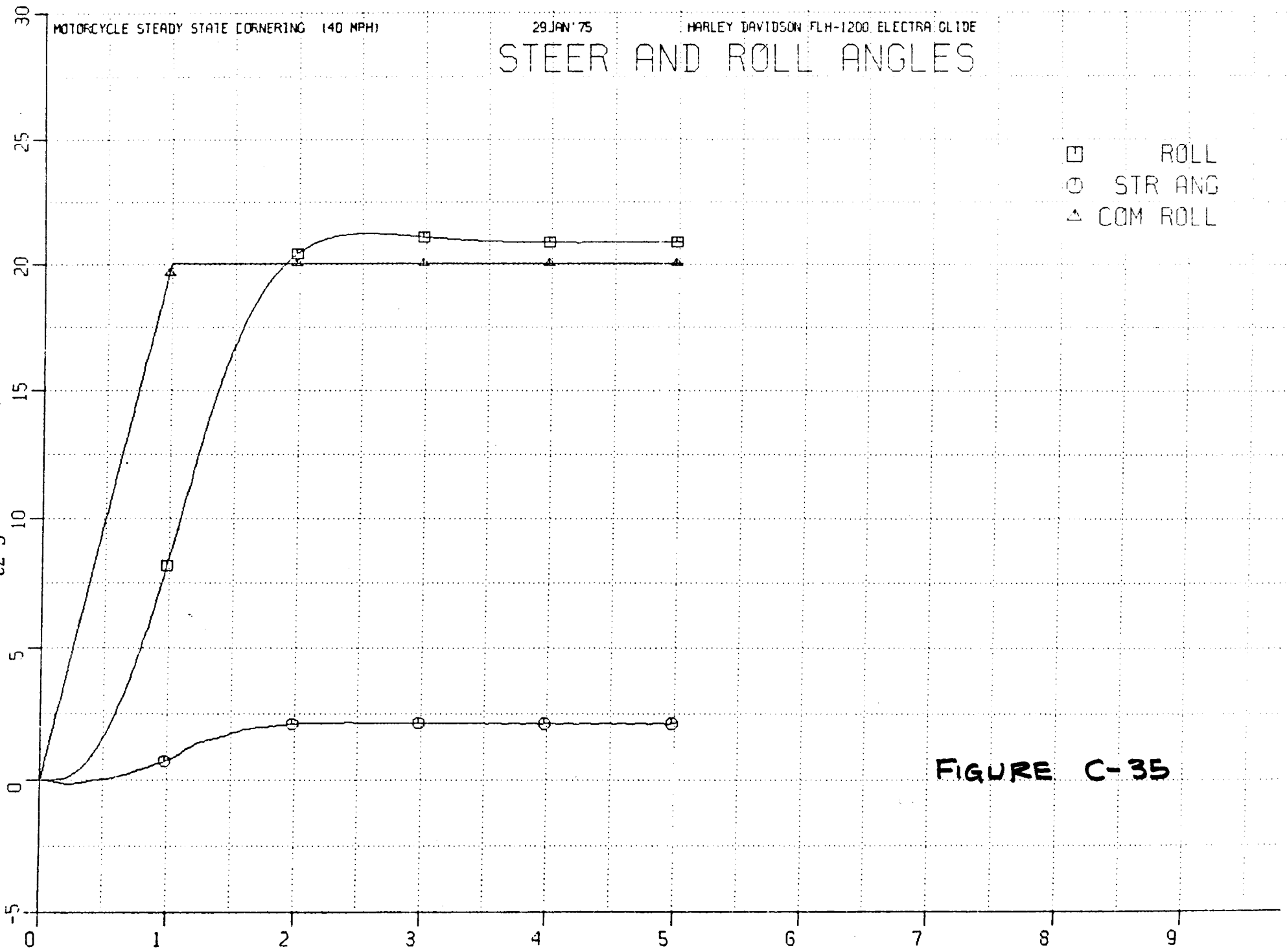


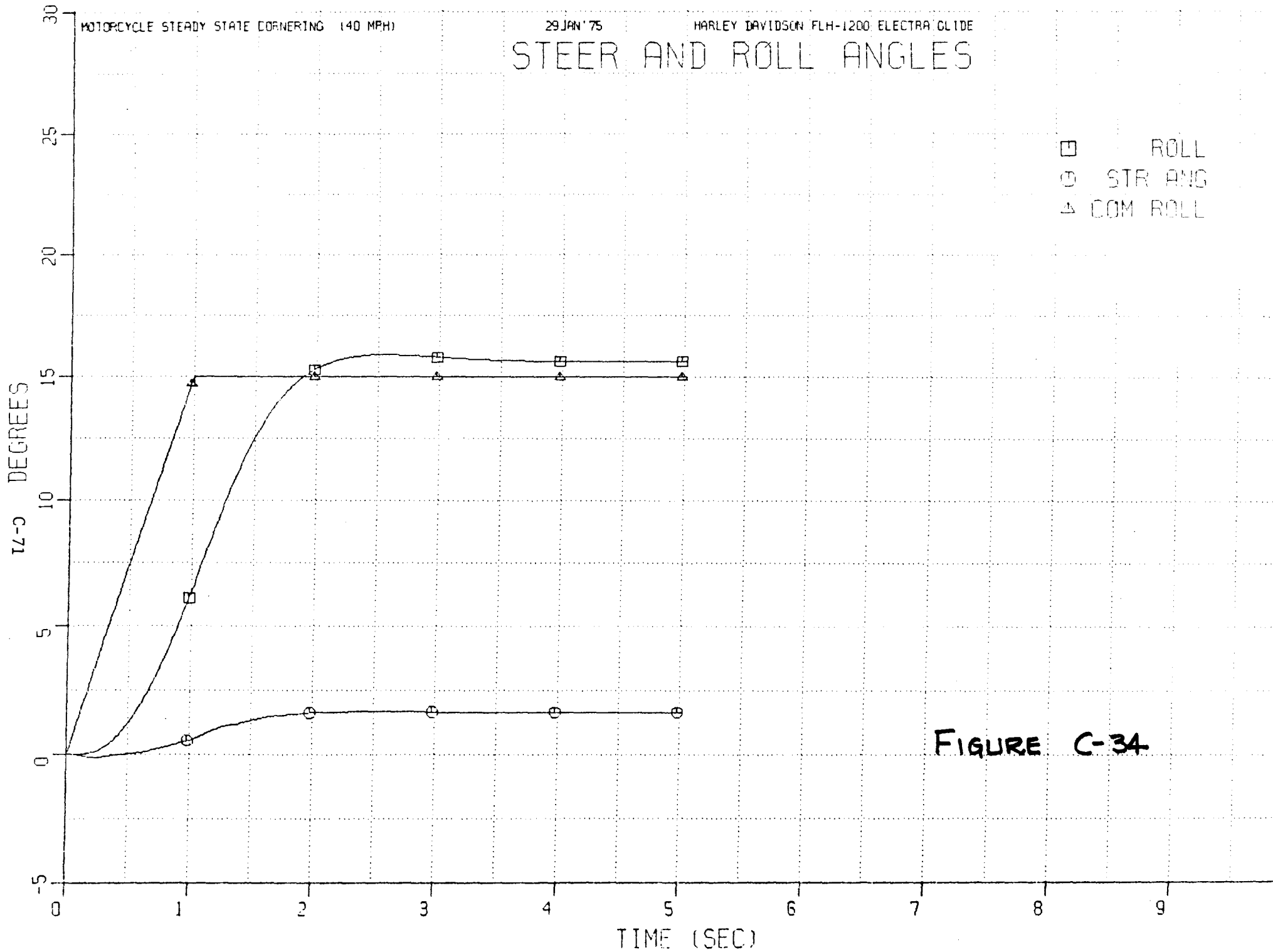
FIGURE C-35

MOTORCYCLE STEADY STATE CORNERING (140 MPH)

29 JAN '75

HARLEY DAVIDSON FLH-1200 ELECTRA GLIDE

# STEER AND ROLL ANGLES



□ ROLL  
○ STR ANG  
△ COM ROLL

FIGURE C-34

- 1. 1000 Hz
- 2. 100 Hz
- 3. 10 Hz

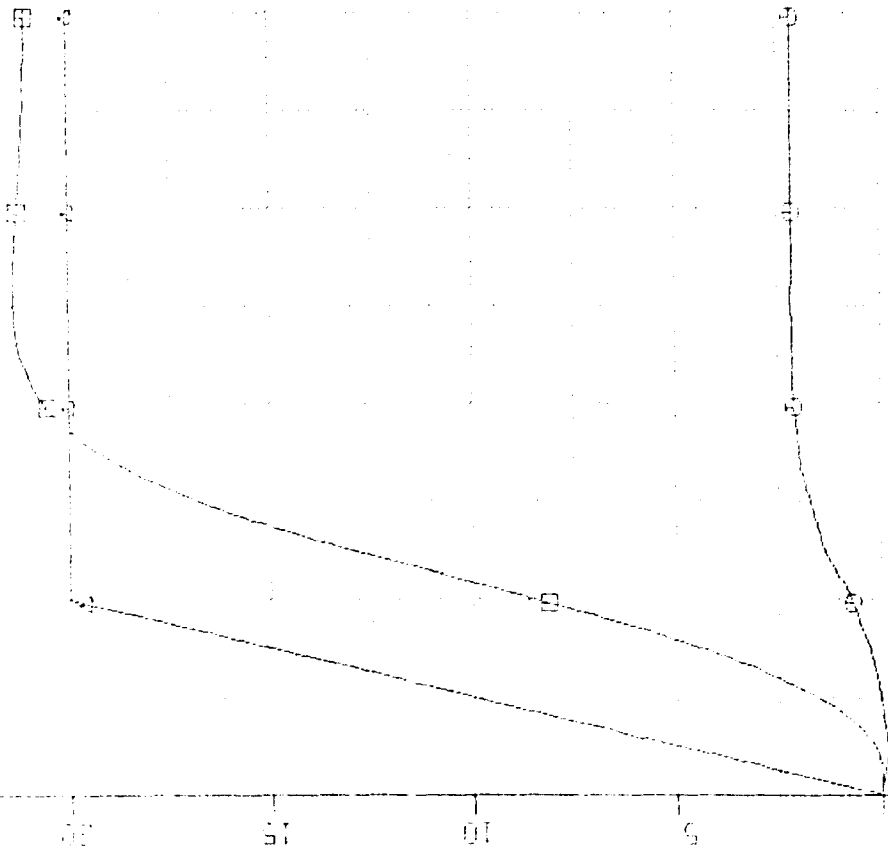


FIGURE C-37

MOTORCYCLE STEADY STATE CORNERING (140 MPH)

29 JAN '75

HARLEY DAVIDSON FLH-1200 ELECTRA GLIDE

# STEER AND ROLL ANGLES

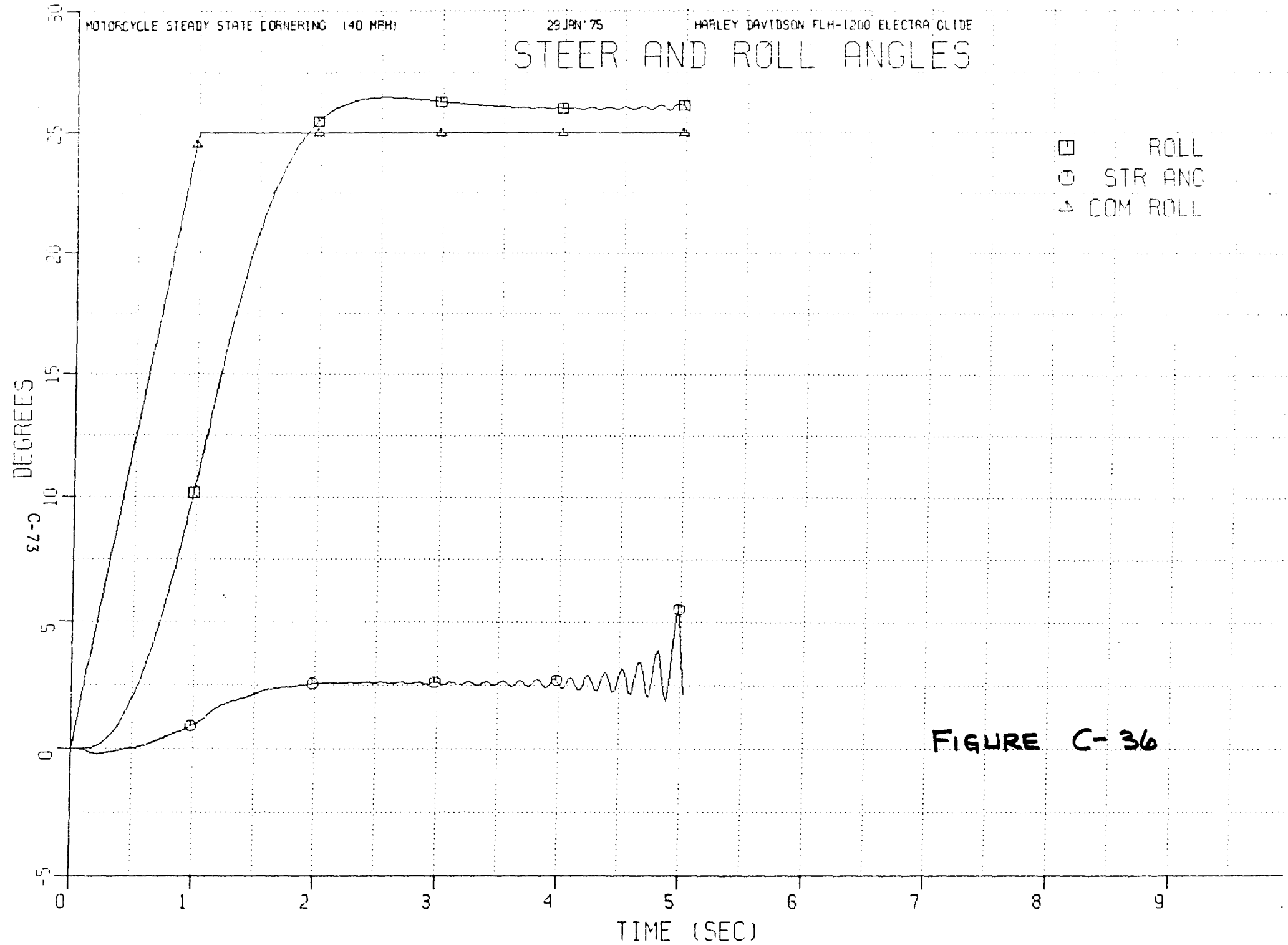


FIGURE C-36



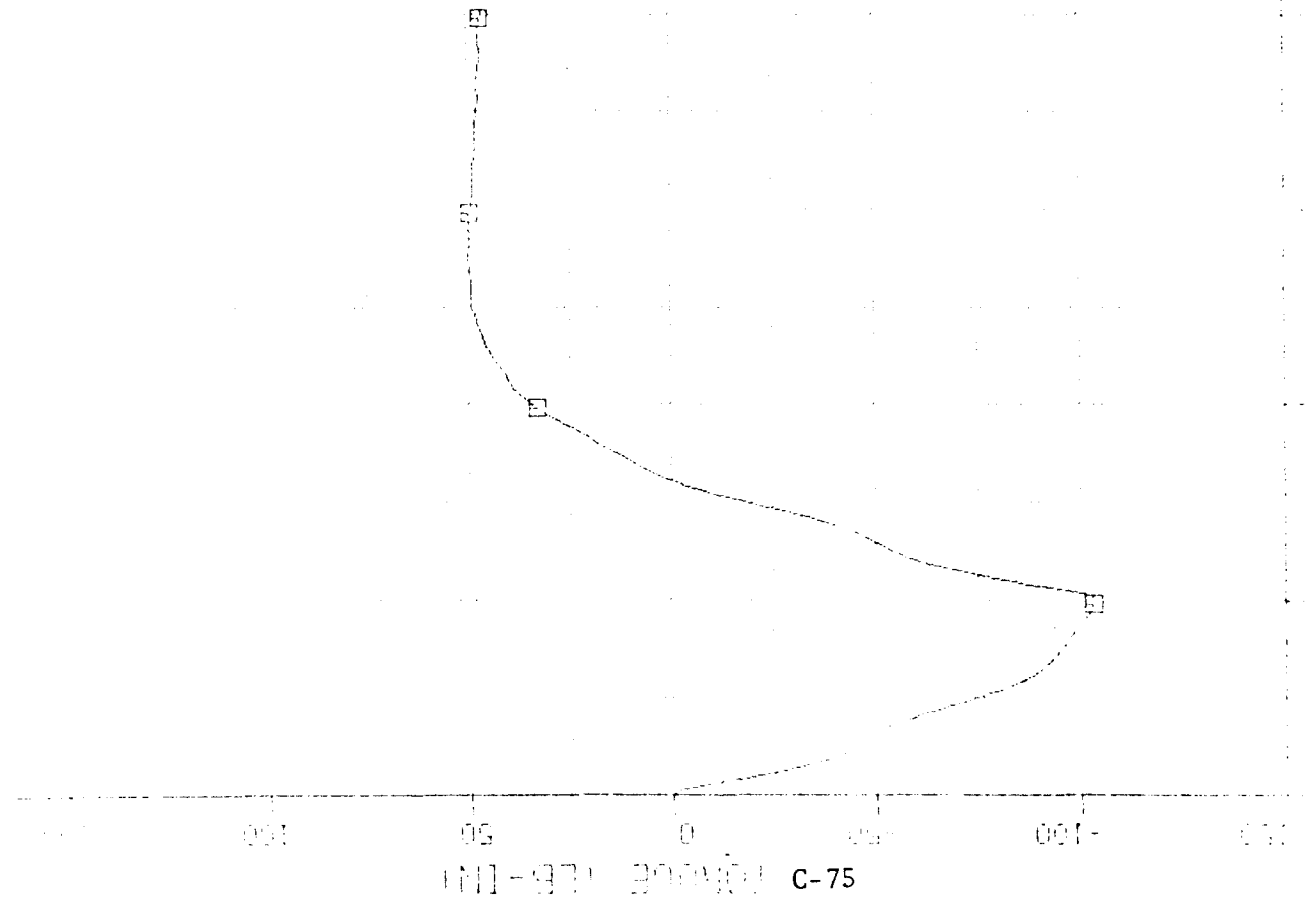


FIGURE C-37 (cont'd)

Table D-1

FULL SCALE TESTING - RUN SUMMARY

Run No.		Run Description
Start	End	
1	12	Directional Control, 300-700 ft. radius, CCW, 40 mph, normal lean control, velocity noise
13	17	DC, 300-700'
18	22	DC, 300', 40-50 mph
23	25	Lane Change, 60', 30-40 mph
26		Steady State, 150' radius, CW, Max Speed
27	32	Yaw rate gyro checkout - straight, serpentine, 20 and 30 mph SS @ 150'
33	35	DC, 300', lean = normal, out, in
36		DC, 300', rider plus passenger
37	42	LC, 20, 30, 40 mph
43	45	Yaw checkout, straight with mild turns
46	47	Straight - Roll angle established with rider lean and steer
48	51	LC, 40 mph, course layout off slightly
52		SS, 150', 30 mph
		New yaw gyro installed to eliminate 1-2 Hz oscillation. Course layout adjusted.
53	54	DC, 300', CCW, 40 mph
55	61	DC, 300/200/150/100, CCW, 20 mph
62	63	DC, 300', CW, 40 mph
64	68	DC, 200/150/100', CCW, 30 mph
69	71	DC, 200/150/100', CCW, 20 mph
72	117	Lane Change Maneuvers - all done from entrance lane to left exit lane
72	81	LC, $\Delta x=60'$ , 40 mph
82	83	LC, $\Delta x=60'$ , 30 mph
84		LC, $\Delta x=60'$ , 20 mph
85	87	LC, $\Delta x=60'$ , 40 mph
88	91	LC, $\Delta x=60'$ , max speed attempt at about 45 mph
92	94	LC, $\Delta x=80'$ , 50 mph, transmission of signal improved
95	98	LC, $\Delta x=80'$ , max speed attempt at about 52-54 mph
99	100	LC, $\Delta x=45'$ , 30 mph
101	104	LC, $\Delta x=45'$ , max speed attempt at about 32-33 mph
105	108	LC, $\Delta x=30'$ , 20 mph
109	114	Repeat LC, $\Delta x=60'$ , 40 mph with improved signal
115	117	LC, $\Delta x=60'$ , 40 mph with cone pair at midpoint of LC for simulation analysis



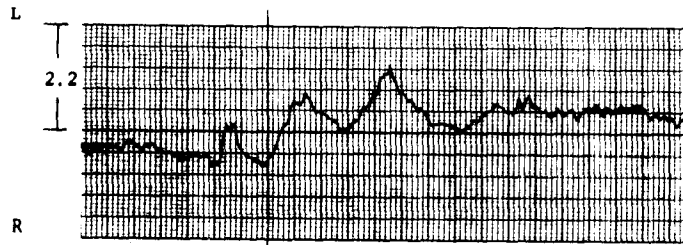
Appendix D  
Full Scale Testing

This appendix contains representative raw data plots (time histories) for runs selected from the full-scale test program. All runs were performed with the Honda CB 360 G in its OE configuration under dry road conditions on Calspan's VERF testing grounds. One rider performed all tests--some 117 runs--over a range of speed and test course geometry (which are discussed at length in the technical volume of this report) for the two procedures described earlier in Appendix A. A summary of the run schedule is included here as Table D-1.

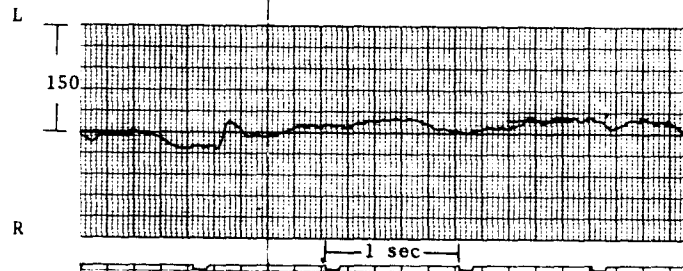
All data are presented with the same time base of 25 mm = 1 sec. Scale factors for each of the variables were adjusted over test period and are indicated in each figure. For the sake of convenience, the sense of each variable is described here as "right" and "left" in the rider's perspective. A more detailed explanation of the applicable coordinate systems is given in Section 3.8 of this report.

As explained previously, tape switches placed at the starting points of the two course layouts were used to activate the event marker of the chart recorder and thus indicate the motorcycle's position as its wheels passed over the switch. This signal appears below the yaw rate trace in each of the data records.

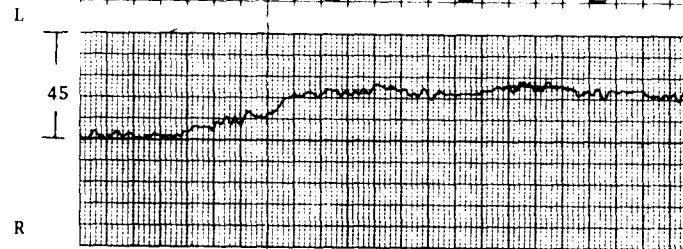
Steer Angle  
(degrees)



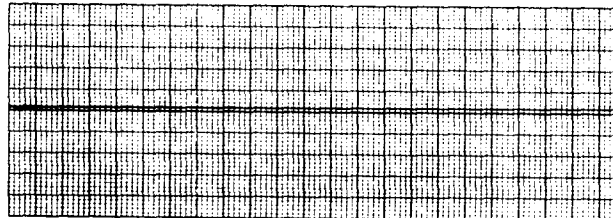
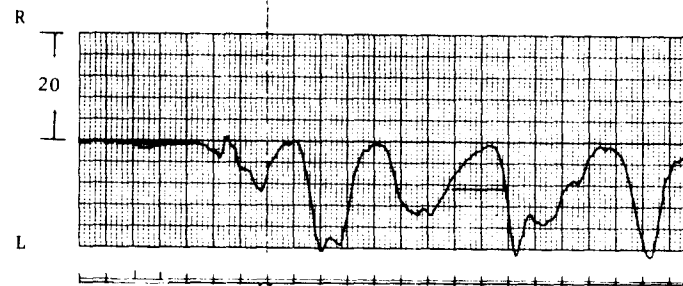
Steer Torque  
(in-lb)



Roll Angle  
(degrees)



Yaw Rate  
(degrees/sec)



Rider Lean Angle  
(degrees)

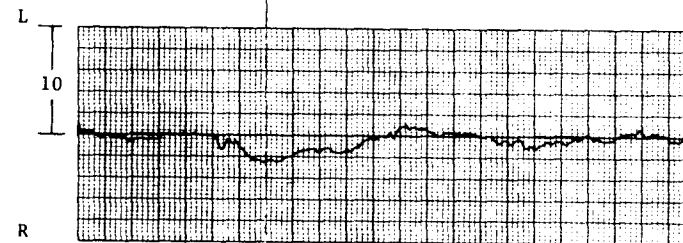


Fig. D-2. Run No. 14. Directional Control, 40 mph, 400 ft. radius.

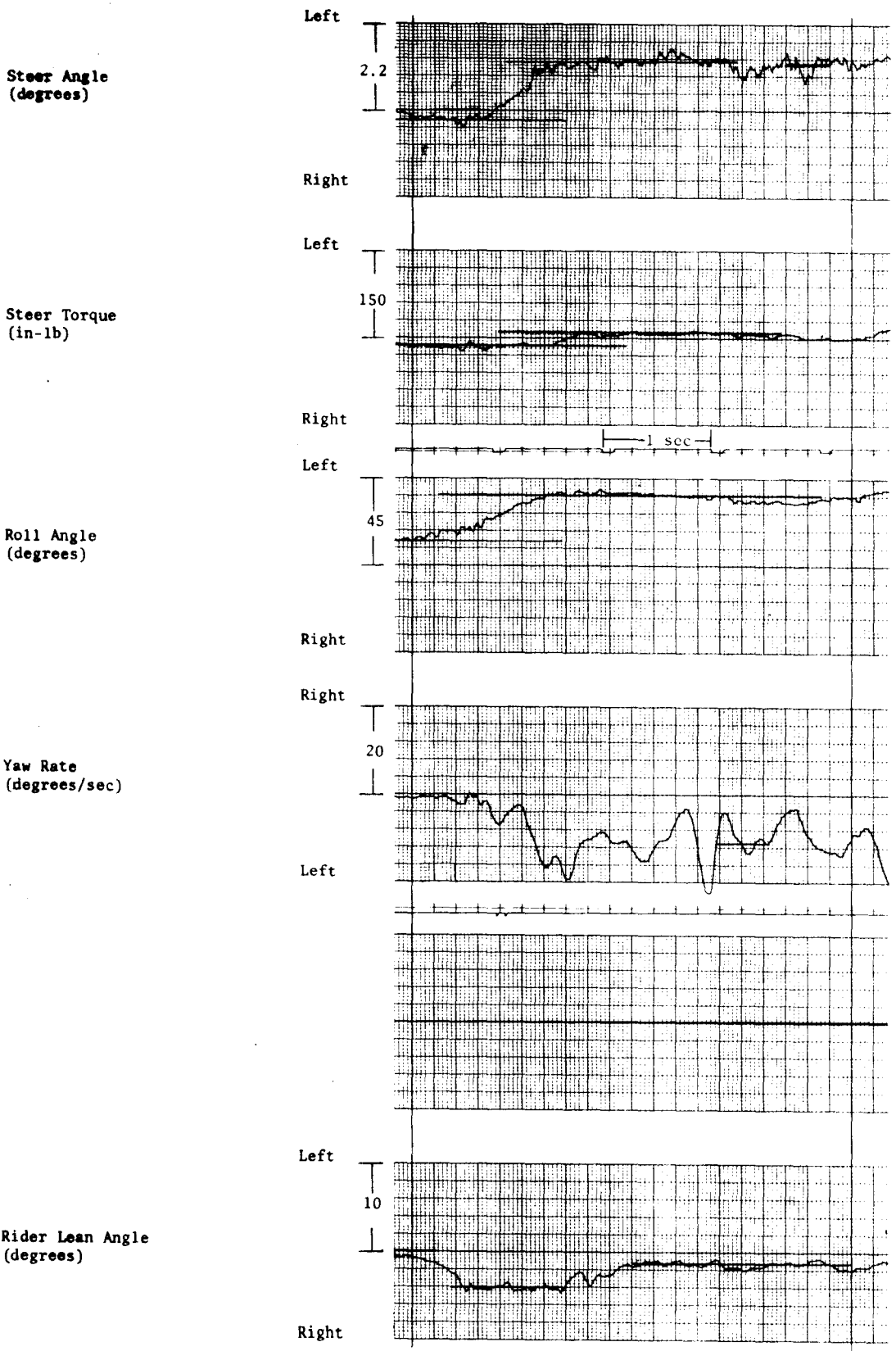
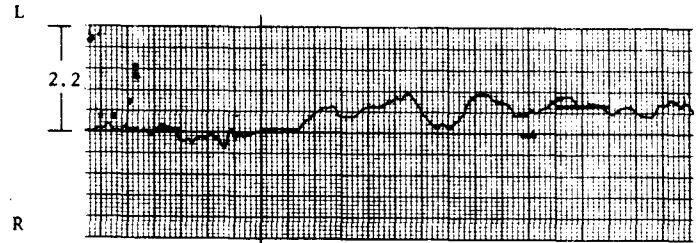
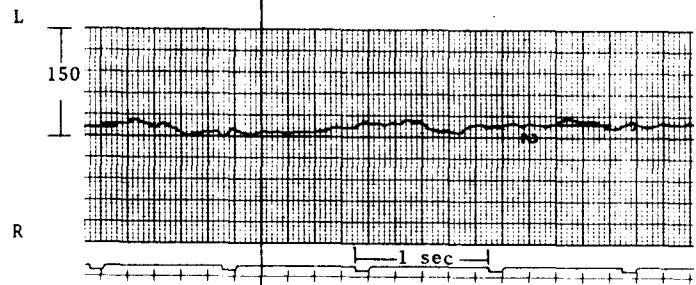


Fig. D-1. Run No. 13. Directional Control, 40 mph, 300 ft. radius.

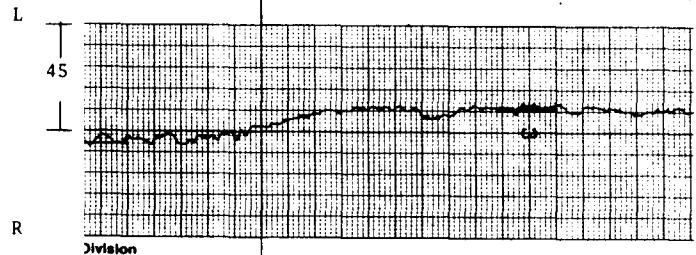
Steer Angle  
(degrees)



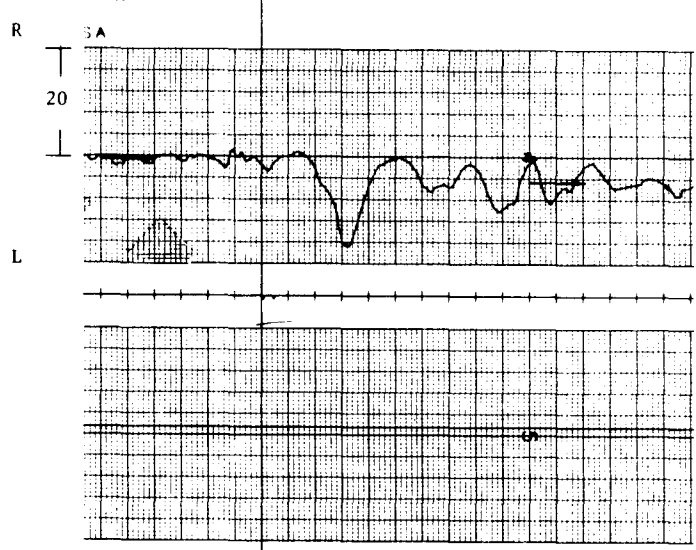
Steer Torque  
(in-lb)



Roll Angle  
(degrees)



Yaw Rate  
(degrees/sec)



Rider Lean Angle  
(degrees)

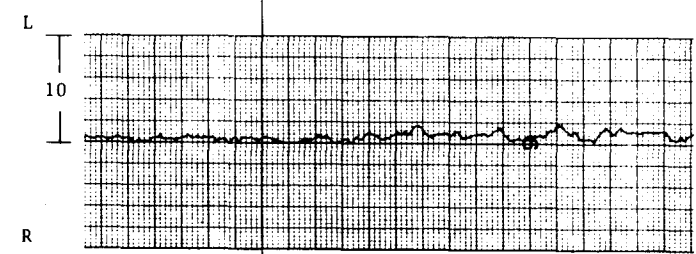
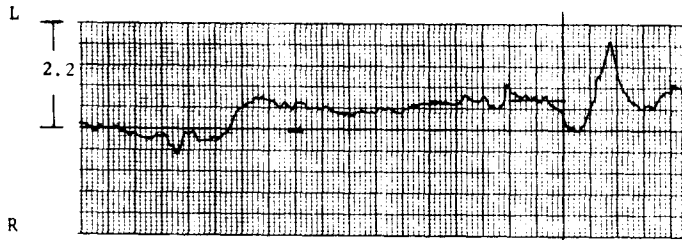
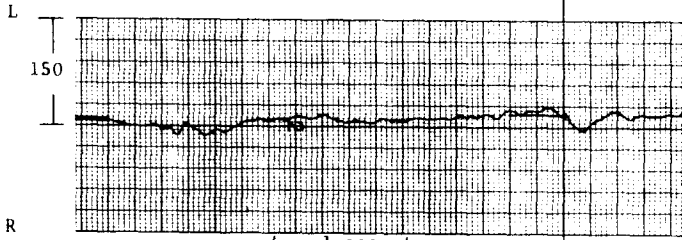


Fig. D-4. Run No. 16. Directional Control, 40 mph, 600 ft. radius.

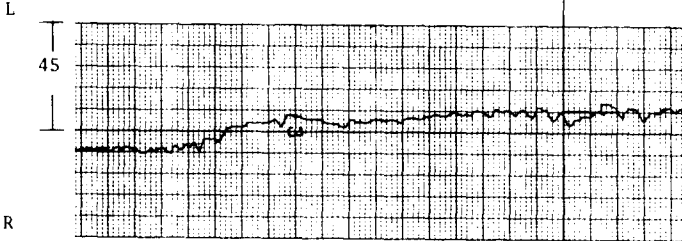
Steer Angle  
(degrees)



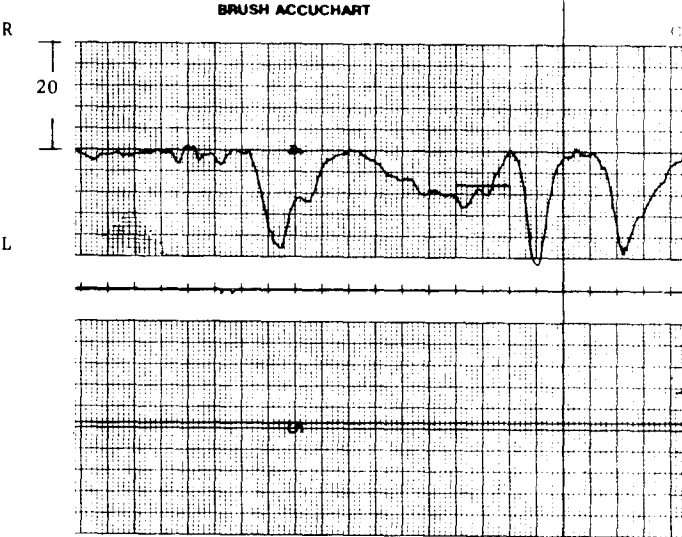
Steer Torque  
(in-lb)



Roll Angle  
(degrees)



Yaw Rate  
(degrees/sec)



Rider Lean Angle  
(degrees)

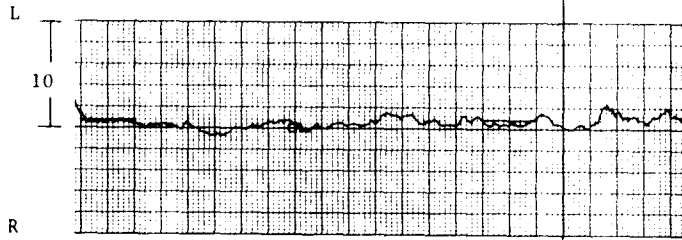


Fig. D-3. Run No. 15. Directional Control, 40 mph, 500 ft. radius.

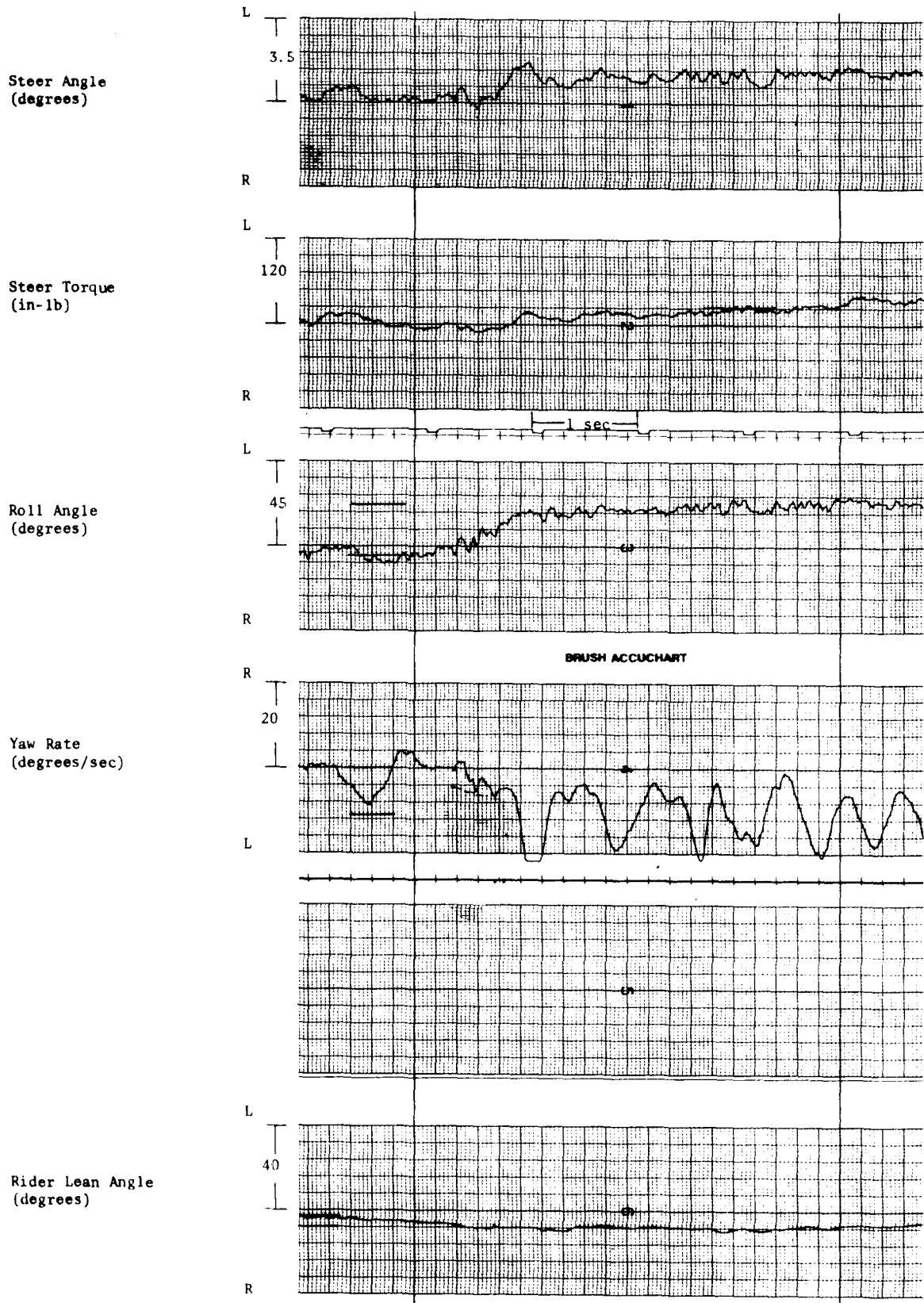


Fig. D-6. Run No. 33. Directional Control, 40 mph, 300 ft. radius. Rider Lean Normal.

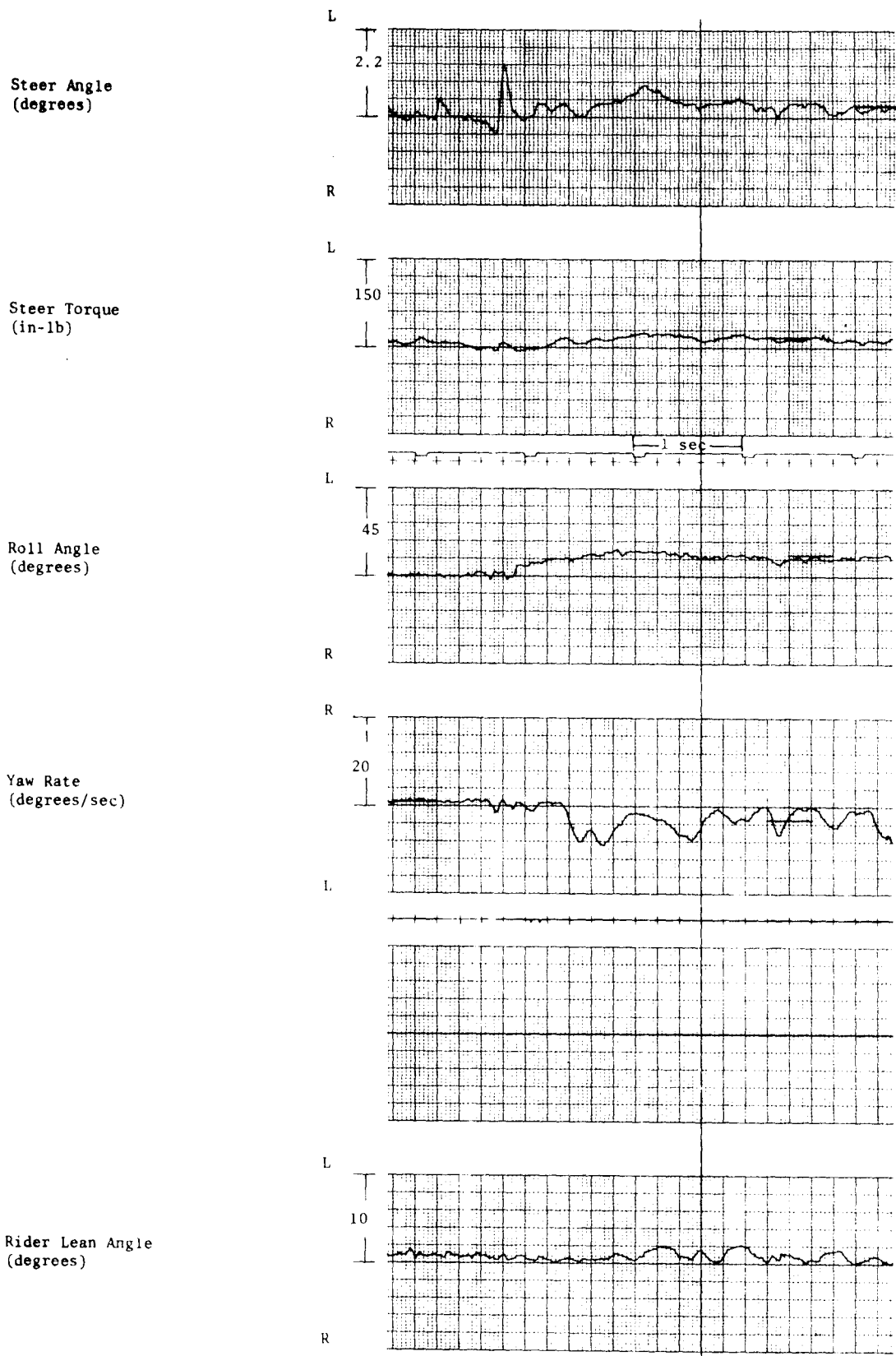


Fig. D-5. Run No. 17. Directional Control, 40 mph, 700' radius.

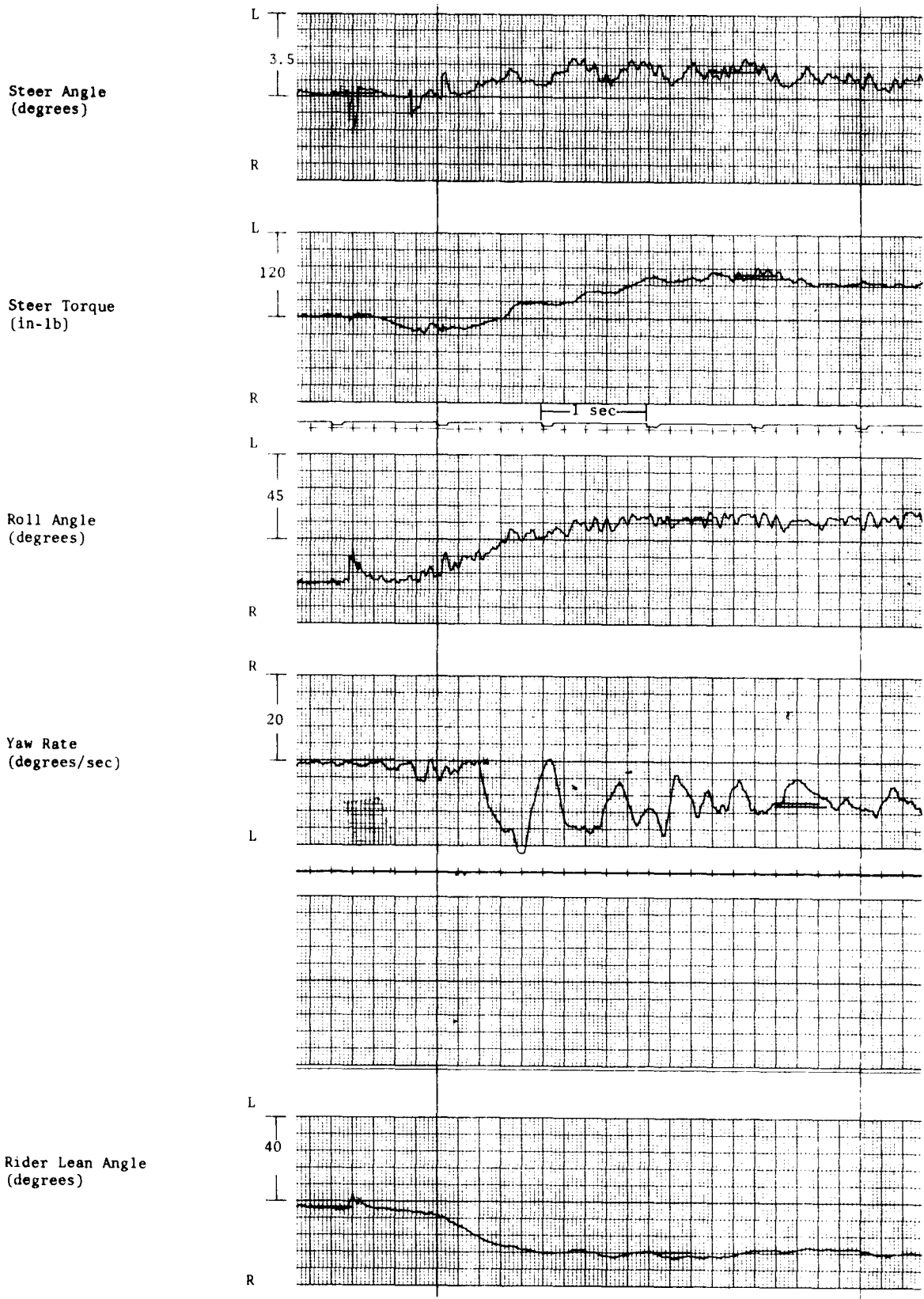
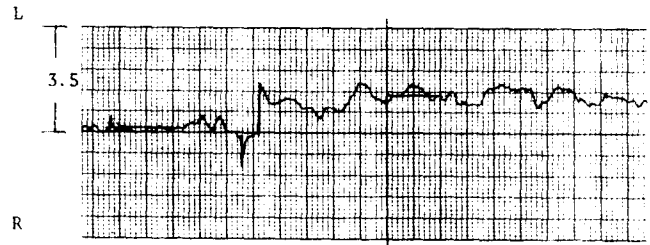


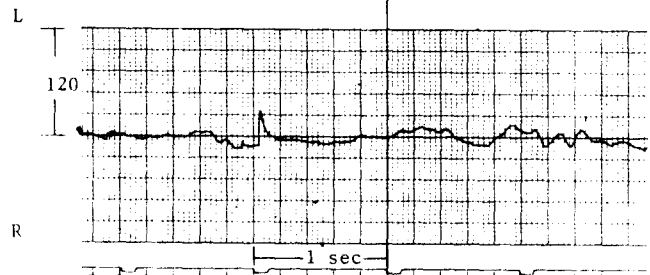
Fig. D-8. Run No. 35. Directional Control, 40 mph, 300 ft. radius. Rider Lean Forced Outward.



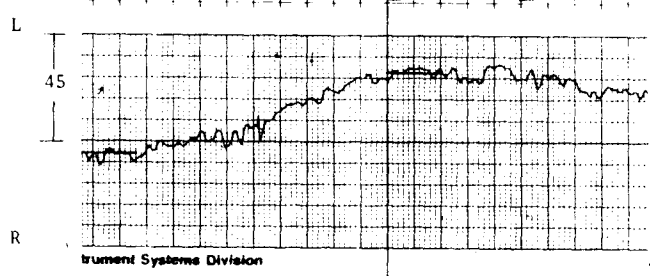
Steer Angle  
(degrees)



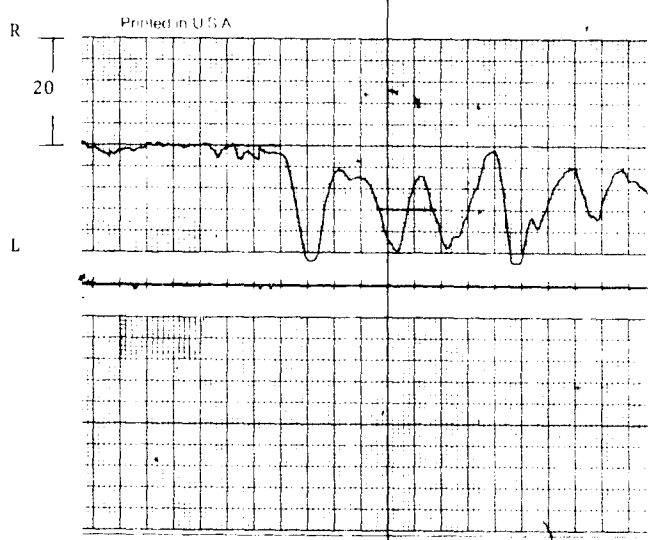
Steer Torque  
(in-lb)



Roll Angle  
(degrees)



Yaw Rate  
(degrees/sec)



Rider Lean Angle  
(degrees)

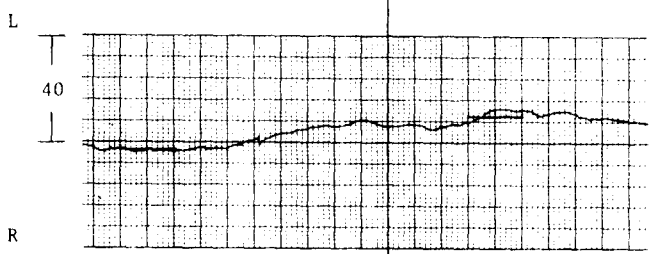


Fig. D-7. Run No. 34. Directional Control, 40 mph, 300 ft. radius. Rider Lean Forced Inward.

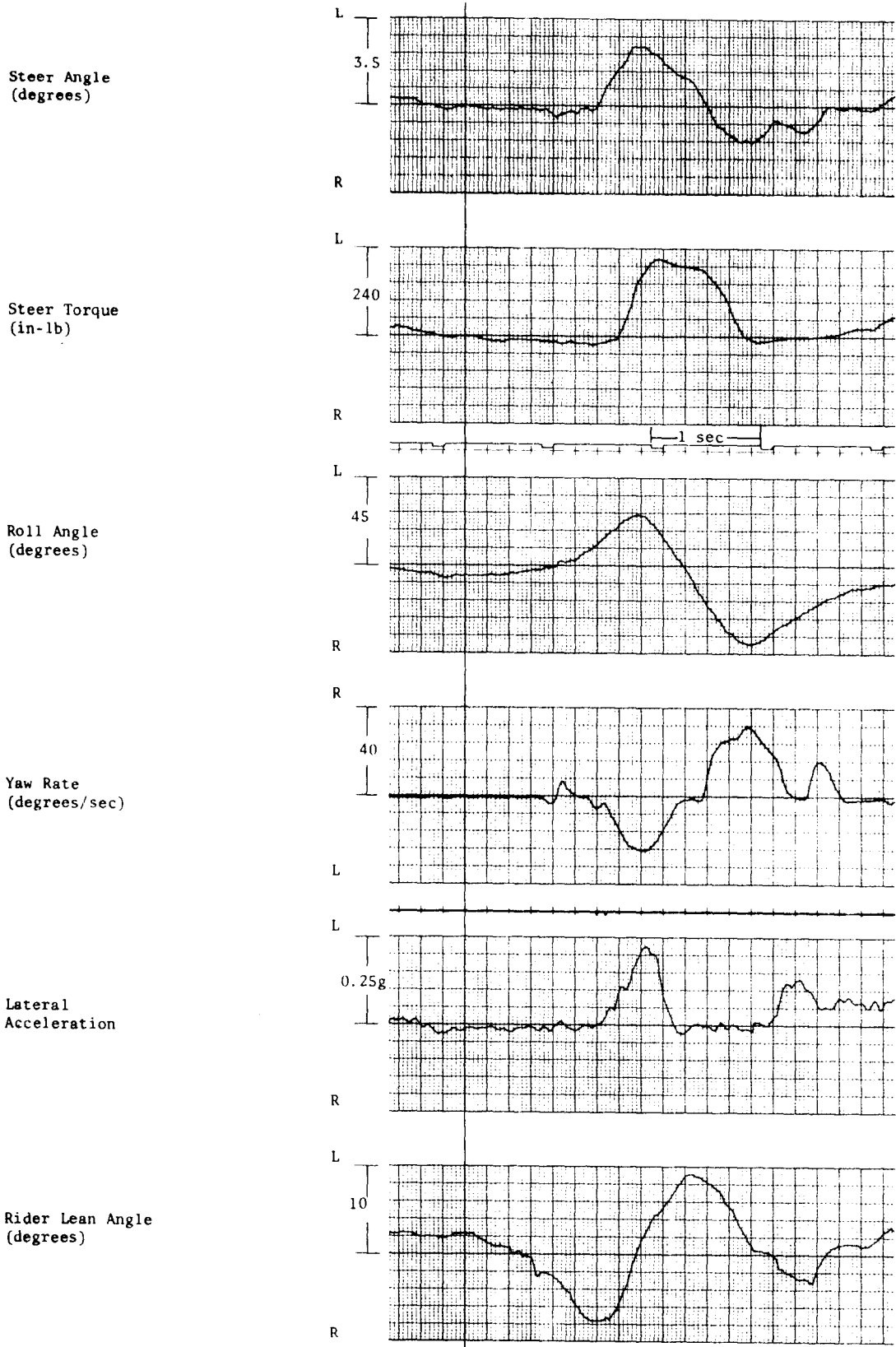


Fig. D-10. Run No. 114. Lane Change,  $\Delta x=60$  ft. 40 mph.

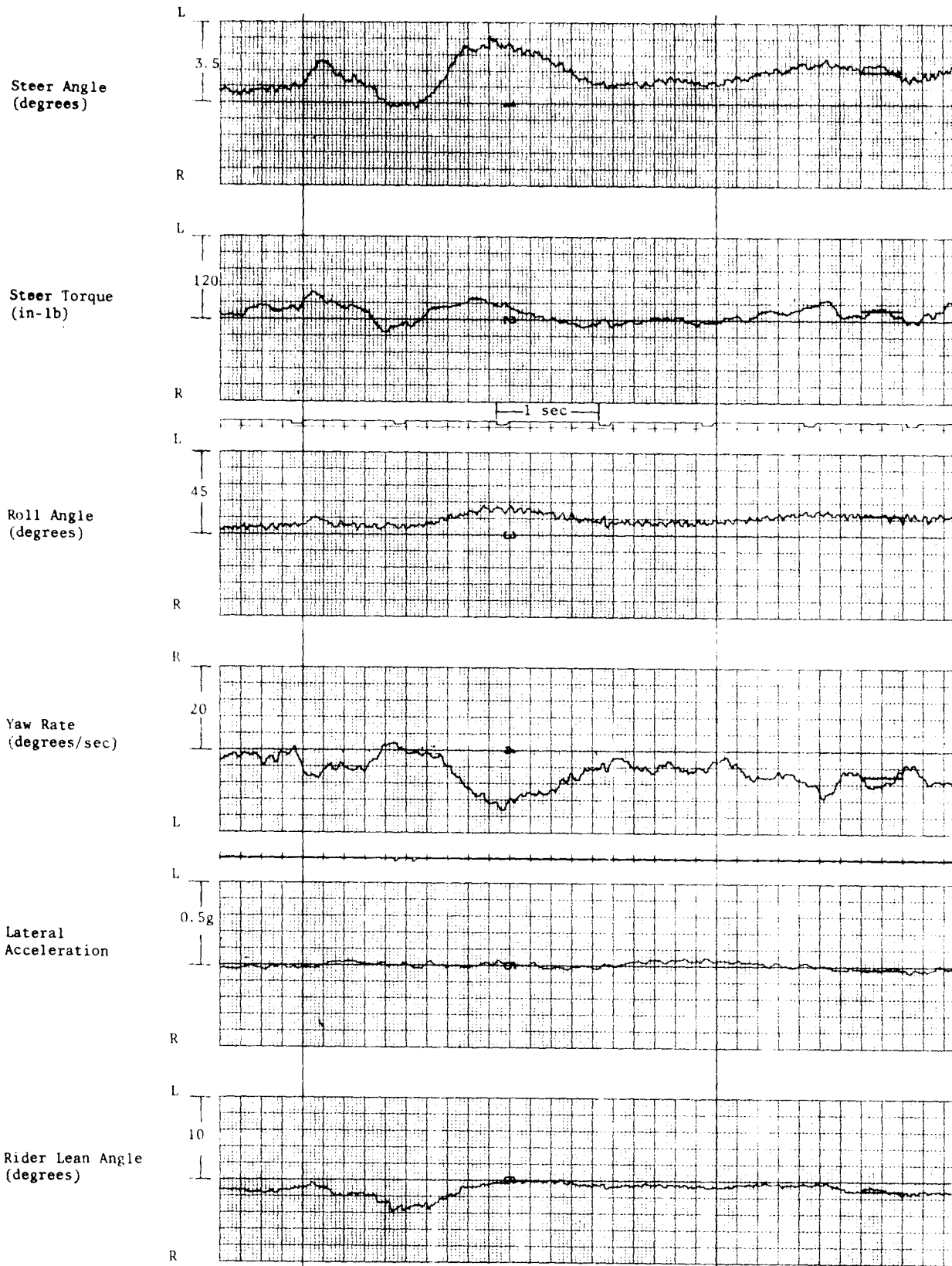
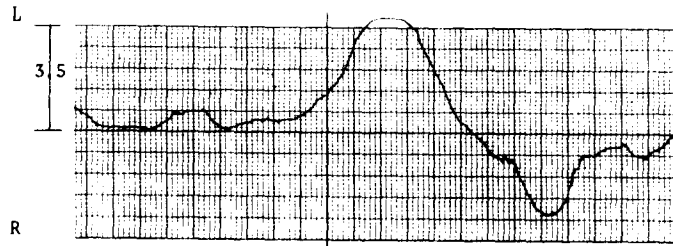
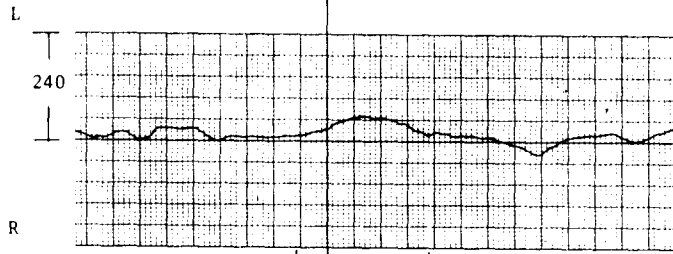


Fig. D-9. Run No. 55. Directional Control, 20 mph, 300 ft. radius.

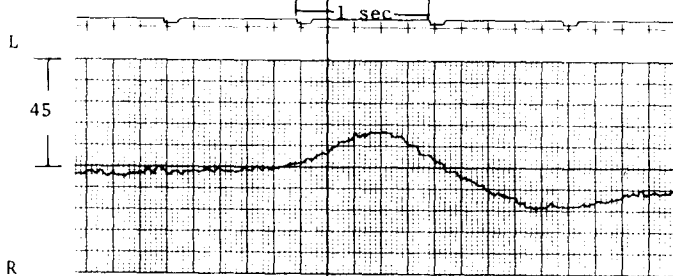
Steer Angle  
(degrees)



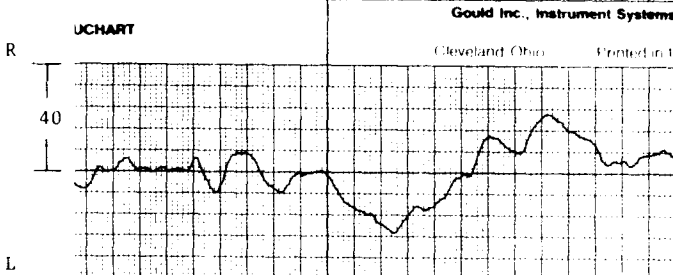
Steer Torque  
(in-lb)



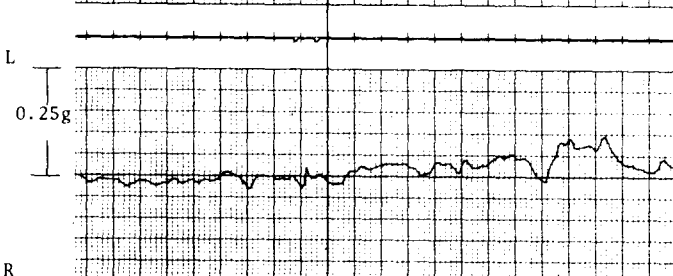
Roll Angle  
(degrees)



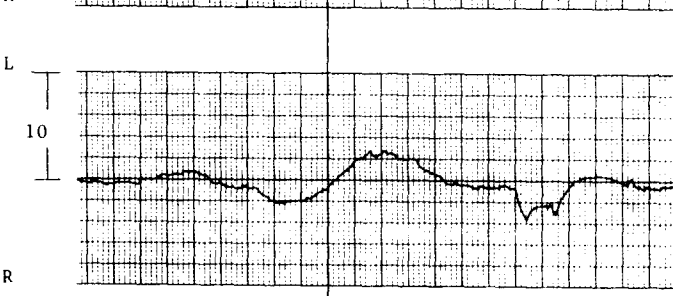
Yaw Rate  
(degrees/sec)



Lateral  
Acceleration



Rider Lean Angle  
(degrees)



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Fig. D-12. Run No. 84. Lane Change,  $\Delta x=60$  ft., 20 mph.

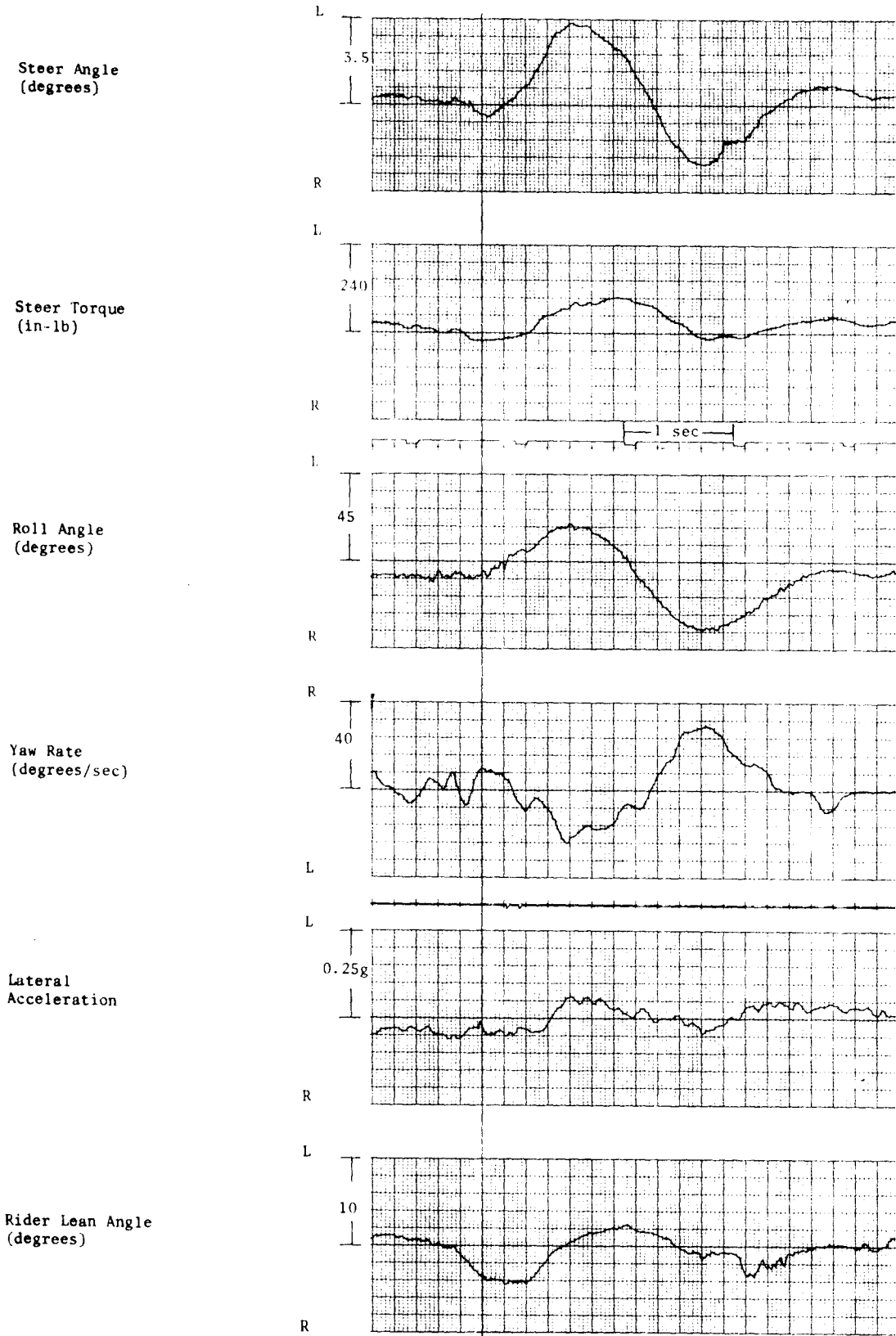


Fig. D-11. Run No. 83. Lane Change,  $\Delta x=60$  ft., 30 mph.

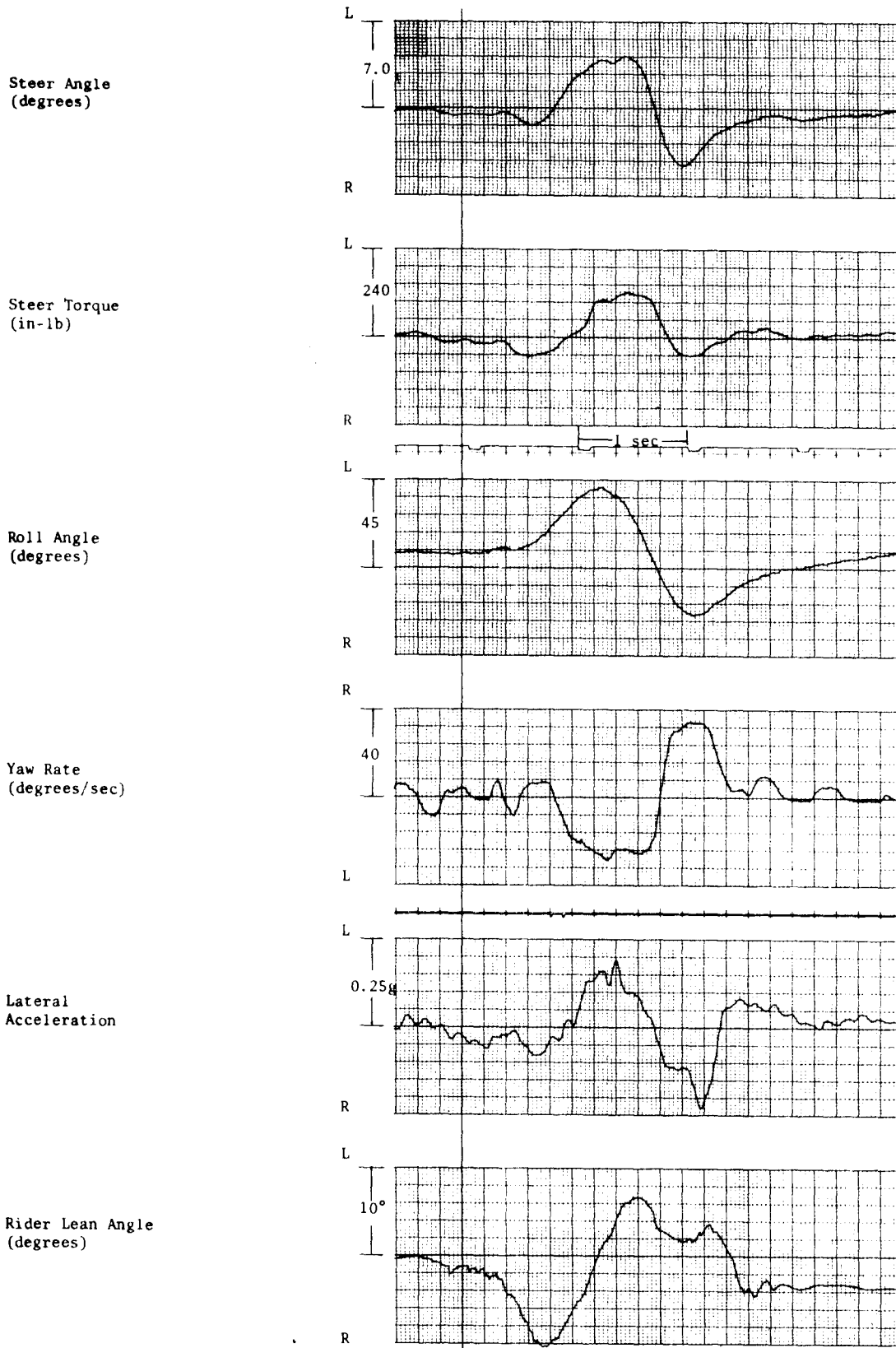
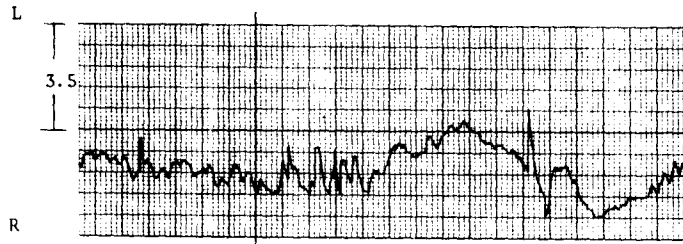
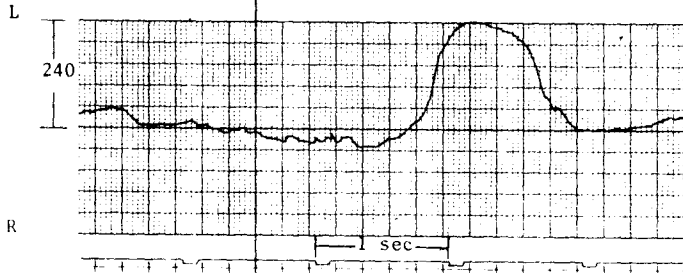


Fig. D-14. Run No. 100. Lane Change,  $\Delta x=45'$ , 30 mph.

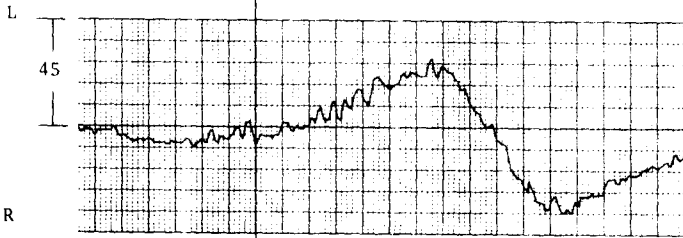
Steer Angle  
(degrees)



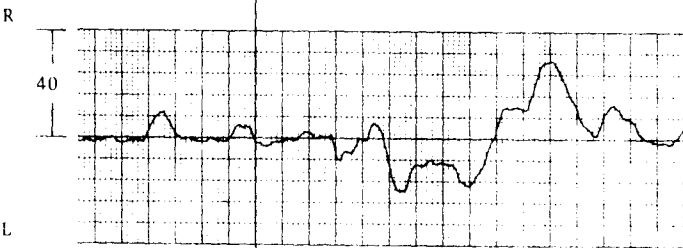
Steer Torque  
(in-lb)



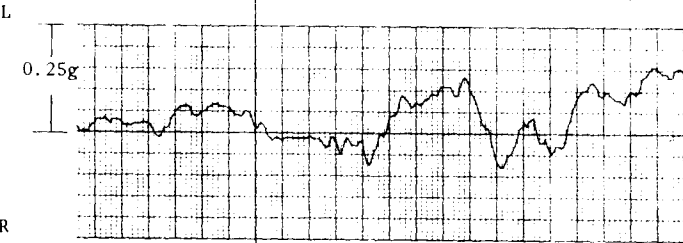
Roll Angle  
(degrees)



Yaw Rate  
(degrees/sec)



Lateral  
Acceleration



Rider Lean Angle  
(degrees)

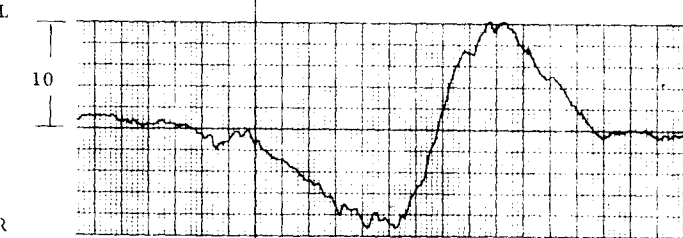
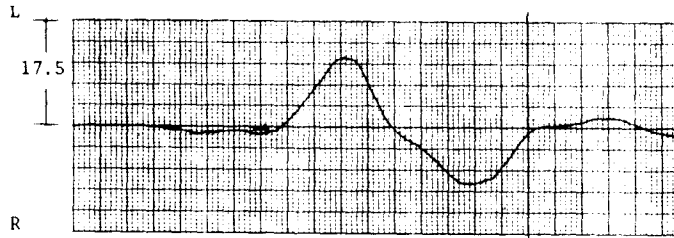


Fig. D-13. Run No. 84. Lane Change,  $\Delta x=80$  ft., 50 mph.

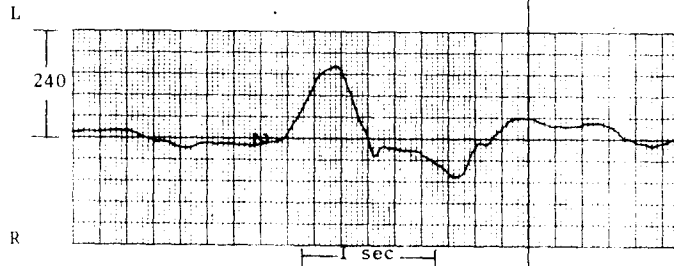




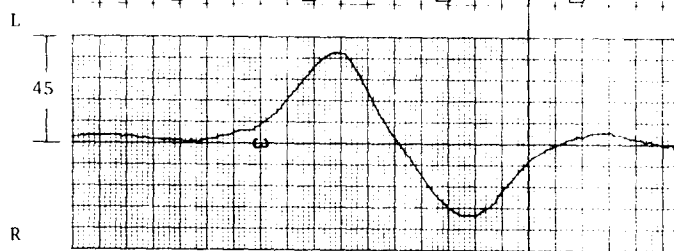
Steer Angle  
(degrees)



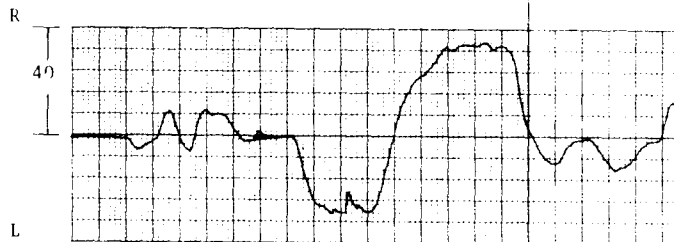
Steer Torque  
(in-lb)



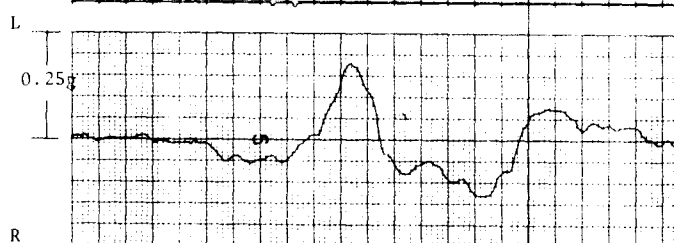
Roll Angle  
(degrees)



Yaw Rate  
(degrees/sec)



Lateral  
Acceleration



Rider Lean Angle  
(degrees)

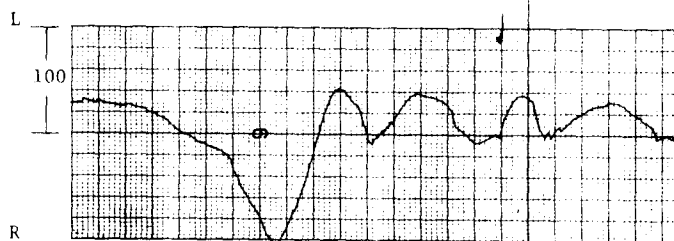


Fig. D-15. Run No. 108. Lane Change,  $\Delta x=30'$ , 20 mph.